

# Summary of *Extending the Rank Likelihood for Semiparametric Copula Estimation*, by Peter Hoff

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## Recall: General Social Survey data

|        |                                                  |
|--------|--------------------------------------------------|
| INC    | Respondent's Income                              |
| DEG    | Highest degree obtained                          |
| CHILD  | Number of children                               |
| PINC   | Parent's income when respondent was 16           |
| PDEG   | Max(mother's degree, father's degree, na.rm = T) |
| PCHILD | Number of siblings + 1                           |
| AGE    | Age of respondent                                |

## Recall: Which do we choose?

$$\begin{aligned} INC_i = & \beta_0 + \beta_1 CHILD_i + \beta_2 DEG_i + \beta_3 AGE_i \\ & + \beta_4 PCHILD_i + \beta_5 PINC_i + \beta_6 PDEG_i + \epsilon_i \end{aligned}$$

or

$$\begin{aligned} CHILD_i \sim & \text{Pois}(\exp\{\beta_0 + \beta_1 INC_i + \beta_2 DEG_i + \beta_3 AGE_i \\ & + \beta_4 PCHILD_i + \beta_5 PINC_i + \beta_6 PDEG_i\}) \end{aligned}$$

# Will Sandwich Help?

| Response | INC                   | CHILD               | DEG           |
|----------|-----------------------|---------------------|---------------|
| INC      | NA                    | <b>1.103(0.112)</b> | 7.025(<0.001) |
| CHILD    | <b>0.005(0.00922)</b> | NA                  | -0.068(0.056) |

| Response | AGE           | PCHILD       | PINC          | PDEG          |
|----------|---------------|--------------|---------------|---------------|
| INC      | 0.335(<0.001) | 0.284(0.407) | 4.070(0.001)  | 1.399(0.115)  |
| CHILD    | 0.037(<0.001) | 0.021(0.080) | -0.063(0.195) | -0.051(0.204) |

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Using a sandwich estimator we have:

| Response | INC                   | CHILD               | ... |
|----------|-----------------------|---------------------|-----|
| INC      | NA                    | <b>1.103(0.108)</b> | ... |
| CHILD    | <b>0.005(0.00939)</b> | NA                  | ... |

## Recall: Setup

Let  $y_{i,j}$  be the value of the  $j^{th}$  variable taken on by the  $i^{th}$  observational unit.

### Gaussian Copula Sampling Model

$$\mathbf{z}_1, \dots, \mathbf{z}_n | \mathbf{C} \sim \text{i.i.d. multivariate normal}(\mathbf{0}, \mathbf{C})$$

$$y_{i,j} = F_j^{-1}[\Phi(z_{i,j})]$$

- Estimate association parameters without having to estimate marginals.
- Do this by only using the partial ordering induced by the data:  
 $y_{k,j} < y_{i,j} \Rightarrow z_{k,j} < z_{i,j}$ .
- A partial ordering is a total ordering without the *totality* condition (i.e., some elements may be incomparable).

# The Extended Rank Likelihood

Let  $D$  be the set of  $\mathbf{Z} := (z_{i,j})$ 's that satisfy the partial ordering. Use the following “marginal likelihood” for inference:

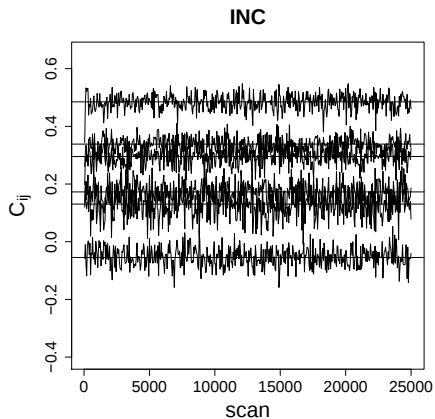
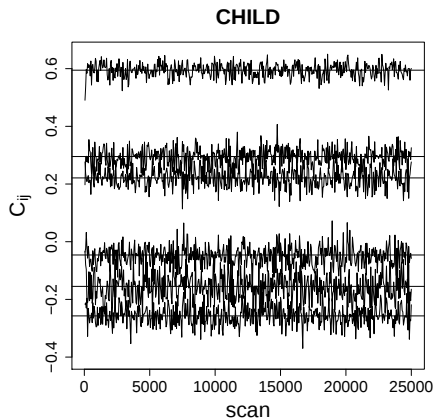
$$Pr(\mathbf{Z} \in D | \mathbf{C}, F_1, \dots, F_p) = \int_D p(\mathbf{Z} | \mathbf{C}) d\mathbf{Z} = Pr(\mathbf{Z} \in D)$$

# Gibbs Sampler

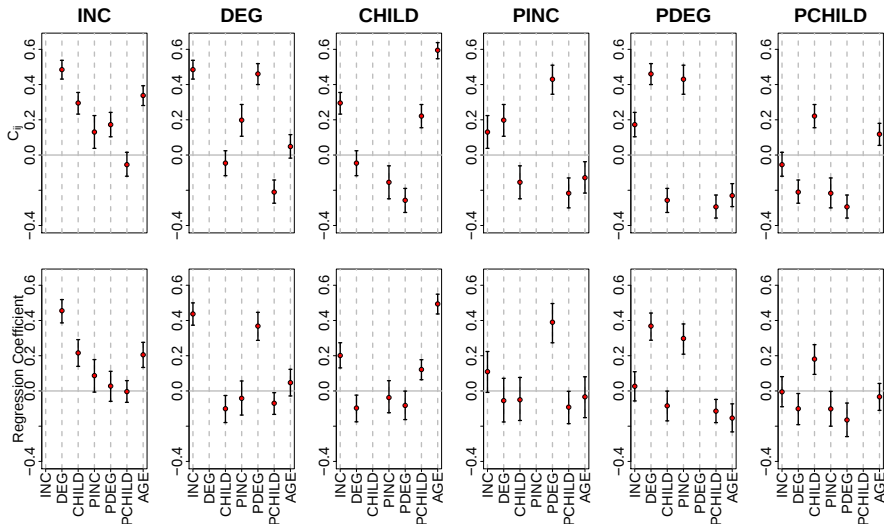
Full conditionals of the  $z_{i,j}$ 's are easy to derive, so we can implement a Gibb's sampler (using covariance matrix rather than correlation matrix, but doesn't matter for estimation).

- 1 Sample  $z_{i,j} | \mathbf{Z}_{[-i,-j]}, \mathbf{V}$  from a truncated normal with the bounds set by the partial ordering and the conditional mean and variance found in the usual way:  $\sigma_j^2 = \mathbf{V}_{[j,j]} - \mathbf{V}_{[j,-j]} \mathbf{V}_{[-j,-j]}^{-1} \mathbf{V}_{[-j,j]}$  and  $\mu = \mathbf{V}_{[j,-j]} \mathbf{V}_{[-j,-j]}^{-1} \mathbf{Z}_{[-j,-j]}^T$ .
- 2 Sample  $\mathbf{V}$  from an inverse-Wishart distribution (if you use the conjugate prior).
- 3 Let  $\mathbf{C}_{[i,j]} = \mathbf{V}_{[i,j]} / \sqrt{\mathbf{V}_{[i,i]} \mathbf{V}_{[j,j]}}$

# Some Trace Plots



# 95% Posterior Credible Intervals



# Visualizing Conditional Dependencies of GSS data.

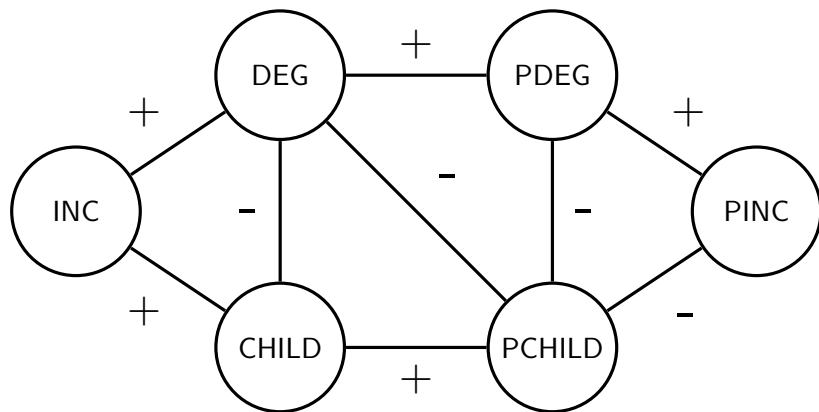
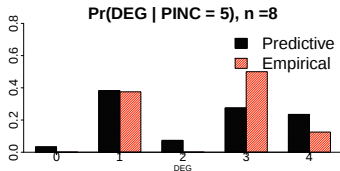
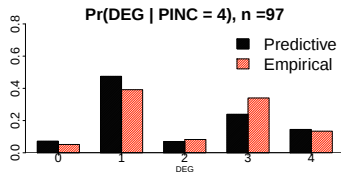
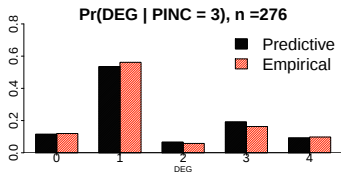
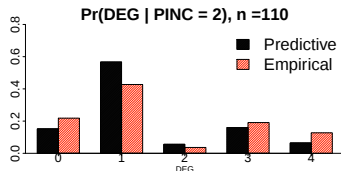
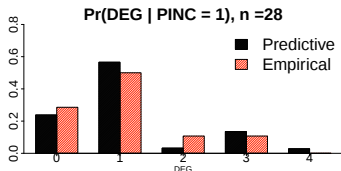


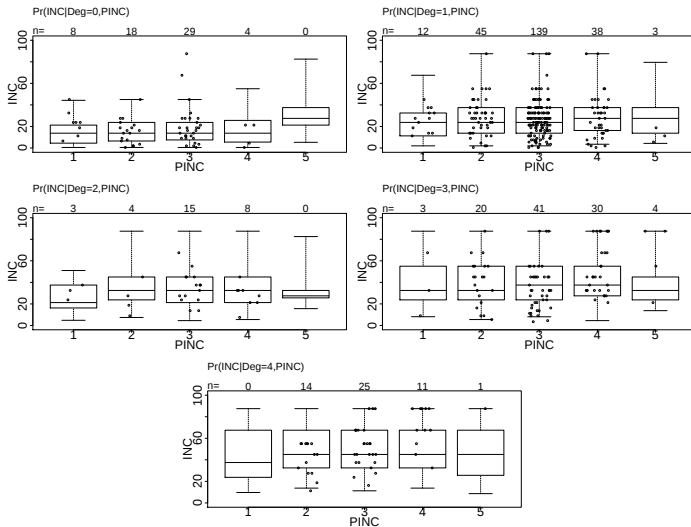
Figure: Reduced conditional dependence graph for the General Social Survey data.

- We can also sample from a posterior predictive distribution to do inference on  $y$ 's.
  - Compare to empirical distributions for model checking.
- 1 sample  $\mathbf{C} \sim p(\mathbf{C}|\mathbf{Z} \in D)$ ;
  - 2 sample  $\mathbf{z} \sim \text{multivariate normal}(\mathbf{0}, \mathbf{C})$ ;
  - 3 set  $y_j = \hat{F}_j^{-1}(\Phi(z_j))$ .

# Posterior Predictive and Empirical distributions of DEG given PINC



# Posterior Predictive and Empirical distributions of INC given DEG and PINC



- The paper proves that ranks are “G-sufficient” and “L-Sufficient” when we have continuous marginals.
- However, when the data are discrete the partial ordering does not have either of these properties.

# Groups

## Definition

A collection  $\mathcal{G}$  of 1-1 transformations of  $\mathcal{X}$  (the sample space) is a **group** if

- ① For all  $g_1, g_2 \in \mathcal{G}$ ,  $g_1 g_2 \in \mathcal{G}$
- ② For all  $g \in \mathcal{G}$ ,  $g^{-1} \in \mathcal{G}$ .

## Definition

Two points  $x_1, x_2 \in \mathcal{X}$  are **equivalent** if there exists a  $g \in \mathcal{G}$  such that  $x_1 = gx_2$ . The sets of equivalent points are the **orbits** of  $\mathcal{G}$ .

## Definition

A function  $M$  is said to be **maximally invariant** if it is in 1-1 correspondence with the orbits of  $\mathcal{G}$ . i.e.  $M(gx) = M(x)$  for all  $g \in \mathcal{G}$  and  $M(x_1) = M(x_2) \Rightarrow x_2 = gx_1$  for some  $g \in \mathcal{G}$ .

- $\mathcal{G}$  induces a group  $\bar{\mathcal{G}}$  over the parameter space.
- Let  $\bar{\mathcal{G}} = \{\bar{g} : \Omega \rightarrow \Omega \text{ s.t. } \bar{g}\theta = \theta' \text{ if } X \sim P_\theta \text{ and } gX \sim P_{\theta'}\}$ .
- There are also maximally invariant parameters for  $\bar{\mathcal{G}}$ .

- Under a group of transformations,  $\mathcal{G}$ , the maximally invariant statistic is called “G-sufficient” for the maximally invariant parameter.
- The ranks are the maximally invariant statistics under the group of continuous strictly increasing functions [Lehmann and Romano, 2005, pp 215 - 216]. You can also put the correlation matrix in a 1-1 correspondence with the induced group  $\bar{\mathcal{G}}$ 's orbits (but only if the marginals are continuous).
- Hence, the ranks are “G-sufficient” for the correlation matrix.
- Intuition: if we assume the marginals are unknown, then applying strictly increasing continuous functions to the data should not change the estimation problem

# Simple Example

- Let  $X_1, \dots, X_n \sim i.i.d. N(\mu, \sigma^2)$ ,  $\Omega = \{(\mu, \sigma) : \mu \in \mathbb{R}, \sigma^2 > 0\}$  and  $\mathcal{X} = \mathbb{R}$ .
- Let  $\mathcal{G} = \{g : g(\mathbf{x}) = \mathbf{x} + a\mathbf{1}, a \in \mathbb{R}\}$
- Then  $g(\mathbf{X}) = (X_1 + a, \dots, X_n + a)$  s.t.  $X_i \sim i.i.d. N(\mu + a, \sigma^2)$  and  $\bar{\mathcal{G}} = \left\{ \bar{g} : \bar{g} \left( \begin{pmatrix} \mu \\ \sigma \end{pmatrix} \right) = \begin{pmatrix} \mu + a \\ \sigma \end{pmatrix} \right\}$ .
- Orbits of  $\Omega$  under  $\bar{\mathcal{G}}$  are defined by  $\sigma$ . So  $\sigma$  is the maximally invariant parameter.
- Orbits of  $\mathcal{X}$  under  $\mathcal{G}$  are defined by the differences from the mean  $(X_1 - \bar{X}, \dots, X_n - \bar{X})$ , so the differences are G-sufficient for  $\sigma$  and inference should only be based on the differences.
- Can extend these ideas to *minimal* G-sufficient (“maximal invariant reduction of minimal sufficient statistics”) [Barnard, 1963]. Here,  $s^2$ .

- For  $\{F_1, \dots, F_p\} \in \mathcal{F}$  the marginal distributions, a statistic  $t(\mathbf{Y})$  is L-sufficient for  $\mathbf{C}$  if
  - ①  $t(\mathbf{Y}_0) = t(\mathbf{Y}_1) \Rightarrow \sup_{\{F_1, \dots, F_p\} \in \mathcal{F}} p(\mathbf{Y}_0 | \mathbf{C}, F_1, \dots, F_p) = \sup_{\{F_1, \dots, F_p\} \in \mathcal{F}} p(\mathbf{Y}_1 | \mathbf{C}, F_1, \dots, F_p)$ ; and
  - ②  $p(t(\mathbf{Y}) | \mathbf{C}, F_1, \dots, F_p) = p(t(\mathbf{Y}) | \mathbf{C})$
- If there are no nuisance parameters, L-sufficiency becomes “full sufficiency”.
- Intuition: partition generated by L-sufficient statistic is “at least as fine” as the partition generated by the M.L.E. of  $\mathbf{C}$  [Rémon, 1984] (i.e. MLE is function of ranks alone).

- Develop maximum likelihood approach using the extended rank likelihood.
  - Lots of trouble with this. [Pettitt, 1982] used an approximation for the rank likelihood in the standard multivariate normal setting.
- Run simulation study against the competitors [Genest et al., 1995] (just plugged in ECDF); [Olsson, 1979] (estimate thresholding values when number of categories is known)
- Develop technique for other copulas, then simulate and see what info is lost by using the wrong copula.

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