Assessing Uncertainty in High-dimensional Regression Models A summary of van de Geer et al. (2013)

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- Motivation: marginal/conditional associations.
- Testing procedure: a bias-corrected estimator.
- Properties: Theoretical and numerical.
- Discussion.

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Associations: Marginal v.s. Conditional

Genes: $\{A^*\}$ $\{B_1^*, B_2, B_3\}$ $\{C_1, C_2, C_3\}$

(An example from Grazier G'Sell et al. 2013.)



Figure: A Manhattan plot from Nishimura et al. (2012). $-\log(0.05) \approx 1.3$

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Consider a linear model:

$$\underline{Y} = \mathbf{X} \underline{\beta}^* + \underline{\epsilon} = \beta_1^* \underline{X}_{(1)} + \mathbf{X}_{(-1)} \underline{\beta}^*_{-1} + \underline{\epsilon}, \quad \underline{\epsilon} \sim N_n(\underline{0}, \sigma_{\epsilon}^2 \mathbf{I}_n).$$
(1)

We want to find:

- A p-value for H_0 : $\beta_1^* = 0$ v.s. H_a : $\beta_1^* \neq 0$.
- ► A p-value for $H_0: \beta_j^* = 0 \forall j \in G \text{ v.s. } H_a: \exists j \in G, \beta_j^* \neq 0.$

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$$(1 - \alpha)$$
 confidence interval for β_1^* .

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- Variable selections: Correct recover of support requires the "beta-min" assumption (Meinshausen and Bühlmann 2006, Wainwright 2009, Negahban et al. 2010).
- A significance test for the lasso (Lockhart, Taylor, Tibshirani, and Tibshirani, 2013).
- Bootstrap and subsampling method. In low-dimensional setting, bootstraps for lasso are proposed by Chatterjee and Lahiri (2011), Sartori (2011). For Ridge regression, see Crivelli et al. (1995) and Cule et al. (2011).

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- Zhang and Zhang (2011), and Bühlmann (2012) provided hypothesis testing procedures on high-dimensional linear models.
- Javanmard and Montanari (2013) provided a minimax test for linear models.
- ► van de Geer et al. (2013) claimed to reach the semiparametric efficiency bound, and the method be generalized to ℓ₁-penalized GLMs and ridge regressions.

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$$\underline{Y} = \mathbf{X} \underline{\beta}^* + \underline{\epsilon}, \quad \underline{\epsilon} \sim N_n(\underline{0}, \sigma_{\epsilon}^2 \mathbf{I}_n).$$
⁽²⁾

When p < n, the MLE is

$$\hat{\beta} = \underset{\substack{\beta \in \mathbb{R}^{p}}{\underset{\beta \in \mathbb{R}^{p}}{\arg\min(\|\underline{Y} - \mathbf{X}_{\beta}\|_{2}^{2}/2n)}}{\arg\min(\|\underline{Y} - \mathbf{X}_{\beta}\|_{2}^{2}/2n)}.$$
(3)

The Karush-Kuhn-Tucker condition is then

$$-\mathbf{X}^{T}(\underline{Y}-\mathbf{X}_{\hat{\beta}})=\underline{0}.$$
(4)

Let $\hat{\boldsymbol{\Sigma}} \triangleq n^{-1} \boldsymbol{X}^T \boldsymbol{X}$. Further assume that $\hat{\boldsymbol{\Sigma}}$ is invertible, with $\hat{\boldsymbol{\Theta}} = \hat{\boldsymbol{\Sigma}}^{-1}$. Hence,

$$\hat{\beta} = \frac{1}{n} \hat{\Theta} \mathbf{X}^T \underline{Y} = \underline{\beta}^* + \frac{1}{n} \hat{\Theta} \mathbf{X}^T \underline{\epsilon}.$$
(5)

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$$\hat{\beta} = \underset{\substack{\beta \in \mathbb{R}^{p}}{\text{sigma}}}{\operatorname{argmin}} (\|\underline{Y} - \mathbf{X}_{\beta}\|_{2}^{2}/(2n) + \lambda \|_{\beta}\|_{1}).$$
(6)

The KKT condition is

$$-\mathbf{X}^{T}(\underline{Y} - \mathbf{X}_{\hat{\beta}}) + \lambda_{\hat{\tau}} = \underline{0}, \ \hat{\tau}_{j} = \text{ SGN } (\hat{\beta}_{j})$$
(7)

Now assume we have a $\hat{\boldsymbol{\Theta}}$ that is a "relaxed form" of an inverse of $\hat{\boldsymbol{\Sigma}} \triangleq n^{-1} \boldsymbol{X}^T \boldsymbol{X}$.

$$\hat{\beta} - \beta^* + \hat{\Theta} \lambda_{\hat{\tau}} = \hat{\Theta} \mathbf{X}^T \underline{\epsilon} / n - \Delta,$$
(8)

where $\underline{\Delta} = (\hat{\Theta}\hat{\Sigma} - I_p)(\hat{\beta} - \beta^*).$ Finally let

$$\hat{\underline{b}} = \hat{\beta} + \hat{\Theta} \mathbf{X}^{\mathsf{T}} (\underline{Y} - \mathbf{X} \hat{\beta}) / n.$$
(9)

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Finding $\hat{\Theta}$: sparse inverse covariance estimation

Let
$$\hat{\gamma}_j = \underset{\substack{\beta \in \mathbb{R}^p}{\beta \in \mathbb{R}^p}}{\operatorname{argmin}} (\|\chi_j - \mathbf{X}_{-j}\gamma\|_2^2/(2n) + \lambda_j \|\gamma\|_1).$$

Then define

$$\hat{\mathbf{C}} = \begin{pmatrix} 1 & -\hat{\gamma}_{1,2} & \cdots & -\hat{\gamma}_{1,p} \\ -\hat{\gamma}_{2,1} & 1 & \cdots & -\hat{\gamma}_{2,p} \\ \vdots & \vdots & \ddots & \vdots \\ -\hat{\gamma}_{p,1} & -\hat{\gamma}_{p,2} & \cdots & 1 \end{pmatrix},$$
(10)

and also

$$\hat{\mathbf{T}}^2 = \operatorname{diag}(\hat{\tau}_1^2, \cdots, \hat{\tau}_p^2), \quad \hat{\tau}_j^2 = (\underline{X}_j - \mathbf{X}_{-j}\hat{\underline{\gamma}}_j)^T \underline{X}_j / n \qquad (11)$$

Finally,

$$\hat{\boldsymbol{\Theta}} = \hat{\boldsymbol{\mathsf{T}}}^{-2} \hat{\boldsymbol{\mathsf{C}}}.$$
 (12)

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• We defined a new estimator for β^* :

$$\hat{\underline{b}} = \hat{\underline{\beta}} + \hat{\Theta} \mathbf{X}^{\mathsf{T}} (\underline{Y} - \mathbf{X} \hat{\underline{\beta}}) / n.$$

► Under certain conditions, $\sqrt{n}\Delta$ is asymptotically negligible, hence

$$\sqrt{n}(\hat{\underline{b}} - \underline{\beta}^*) = \hat{\Theta} \mathbf{X}^{\mathsf{T}} \underline{\epsilon} + o_{\mathsf{P}}(1), \quad \hat{\Theta} \mathbf{X}^{\mathsf{T}} \underline{\epsilon} | \mathbf{X} \sim N_{\mathsf{P}}(\underline{0}, \sigma_{\epsilon}^2 \hat{\Theta} \hat{\mathbf{\Sigma}} \hat{\Theta}^{\mathsf{T}}).$$

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One preliminary result:



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Theorem (Theorem 2.2 in van de Geer et al. (2013)) For the linear model in (1) with Gaussian error $\underline{\epsilon} \sim N_n(\underline{0}, \sigma_{\epsilon}^2 \mathbf{I}_n)$, assume Restricted Eigenvalues and the sparsity assumption hold. When using $\lambda_j = \lambda_{\max} \asymp \sqrt{\log(p)/n}$, $\forall j$, and $\lambda \asymp \sqrt{\log(p)/n}$, we have:

$$\begin{aligned} \sqrt{n} (\hat{b}_{Lasso} - \beta^{0}) &= \mathcal{W}_{n} + \Delta_{n}, \\ \mathcal{W}_{n} | \mathbf{X} \sim \mathcal{N}_{p}(\underline{0}, \sigma_{\epsilon}^{2} \mathbf{\Omega}), \ \mathbf{\Omega}_{n} &= \hat{\mathbf{\Theta}} \hat{\mathbf{\Sigma}} \hat{\mathbf{\Theta}}^{T}, \\ \| \underline{\Delta}_{n} \|_{\infty} &= o_{P}(1). \end{aligned} \tag{13}$$

Furthermore, $\|\mathbf{\Omega}_n - \mathbf{\Sigma}^{-1}\|_{\infty} = o_P(1)$ as $n \to \infty$.

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Assumption (Sparsity) $s_0 = o(n^{1/2}/\log(p))$ and $s_j \le s_{\max} = o(n/\log(p))$.

Assumption (Restricted eigenvalue)

The rows of X are i.i.d. realizations from a Gaussian distribution P_X whose p-dimensional covariance matrix Σ has the smallest eigenvalue $\Lambda_{\min}^2 \ge L > 0$, and $\|\mathbf{\Sigma}\|_{\infty} \triangleq \max_{j,k} |\mathbf{\Sigma}_{jk}| = O(1)$.

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- Why sparsity?
- Why restrict the minimum eigenvalue?
- Why Gaussian design?

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Some setups:

- $\beta^* = (b_0, b_0, b_0, b_0, b_0, 0, ...0).$
- ► $X_i \sim_{\text{iid}} N_n(0, \Sigma)$, where Σ is a block-diagonal matrix. $(m_1 = 40)$

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$$\Upsilon \sim N_n(\mathbf{X}_{\beta^*}, \mathbf{I}_n)$$
. $(m_2 = 100)$.

Parameters in this study are:

- ▶ $p \in \{1000, 2000\}.$
- ▶ $n \in \{100, 400, 800\}.$
- ▶ ρ ∈ {0, 0.4}
- ▶ $b_0 \in \{0.25, 0.75\}.$
- λ ranges from 0.5 to 3, and one chosen by BIC.

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The baseline graph



p = 2000



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 $\overline{\rho} = 0.4$



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- The estimation/testing procedure.
- Theoretical justifications.
- Some simulation results.

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For general linear models, we need to consider

- $\hat{\beta}$ (Van de Geer, 2008),
- $\hat{\Sigma} \triangleq -\ddot{\ell}$: new assumptions.
- $\hat{\boldsymbol{\Theta}}:$ "the relaxed inverse",
 - Sparse matrix: estimate Θ using other methods, e.g. Glasso (Friedman et al., 2008).
 - Matrix of different types.

In application,

- Sample size.
- Tuning parameter.

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