STAT 518 Update Student Presentation

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April 30, 2013

What's the paper about again?

- Gaussian Processes (GP)
 - Focus on covariance functions between outcomes
 - $\rightarrow\,$ how two outcomes are correlated, based on values of their predictors
 - ightarrow letting the data speak for itself
- Prediction
 - Objective is to obtain a predictive distribution for the outcome of a future observation
- Radford M. Neal [1999]

Yes, there was some math

- Simple Linear Regression Example
- Observed data : $\left(x^{(1)},t^{(1)}
 ight),\ldots,\left(x^{(n)},t^{(n)}
 ight)$
- $t^{(i)} =$ outcome (target) for case i
- $x^{(i)} = \text{fixed input (predictor) for case } i$
- ightarrow univariate for this example, but may be *p*-dimensional
 - Fit a familiar model:

$$t^{(i)} = \alpha + x^{(i)}\beta + \epsilon^{(i)}, \quad \epsilon^{(i)} \underset{iid}{\sim} N\left(0, \sigma_{\epsilon}^{2}\right)$$

• Put independent priors on unknown parameters α and β :

$$\alpha \sim N\left(0, \sigma_{\alpha}^{2}\right), \quad \beta \underset{iid}{\sim} N\left(0, \sigma_{\beta}^{2}\right)$$

Yes, there was some math

\Rightarrow Prior joint multivariate Gaussian distribution for *t*:

$$t = \left[t^{(1)}, \ldots, t^{(n)}
ight]^T \sim N_n(\mathbf{0}, \mathbf{C})$$

Covariance matrix
$$C = \left\{ \text{Cov} \left[t^{(i)}, t^{(j)} \right] \ i, j \in [1, n] \right\}$$

 $\text{Cov} \left[t^{(i)}, t^{(j)} \right] = \mathsf{E} \left[\left(\alpha + x^{(i)}\beta + \epsilon^{(i)} \right) \left(\alpha + x^{(j)}\beta + \epsilon^{(j)} \right) \right]$

$$= \sigma_{\alpha}^{2} + x^{(i)} x^{(j)} \sigma_{\beta}^{2} + \delta_{ij} \sigma_{\epsilon}^{2},$$

 $\delta_{ij} = 1$ if i = j and 0 otherwise i.e. Kronecker delta

So why the fuss over the covariance function?

$$C_{ij} = \text{Cov}\left[t^{(i)}, t^{(j)}\right] = \underbrace{\sigma_{\alpha}^{2}}_{Constant} + \underbrace{x^{(i)}x^{(j)}\sigma_{\beta}^{2}}_{Linear} + \underbrace{\delta_{ij}\sigma_{\epsilon}^{2}}_{Noise}$$

- Covariance between the outcomes is fully described by the relationship between the predictors
- e.g. Linear function of predictors: restrictive? Suppose the covariance depends on differences between predictor values, rather than just the values themselves?
 - \Rightarrow Are there other ways to describe the covariance function?

So why the fuss over the covariance function?

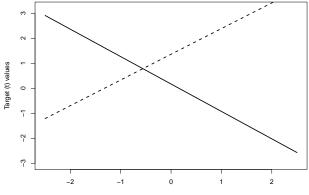
• How about an exponential term instead?

$$C_{ij} = \operatorname{Cov}\left[t^{(i)}, t^{(j)}\right] = \underbrace{\eta^{2} \exp\left(-\rho^{2} \left(x^{(i)} - x^{(j)}\right)^{2}\right)}_{Exponential} + \underbrace{\delta_{ij} \sigma_{\epsilon}^{2}}_{Noise}$$

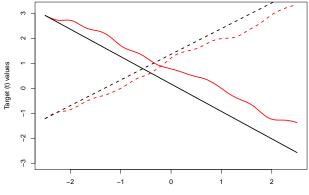
- Observations with predictor values that are "far apart" have much smaller covariances
- $\eta = magnitude$
- $\rho = \text{scale}$

$$\Rightarrow$$
 Gaussian kernel: exp $\left(-\frac{\left(x^{(i)}-x^{(j)}\right)^2}{1/\rho^2}\right)$

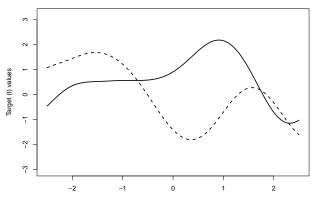
$$Cov[t^{(i)}, t^{(j)}] = 1 + x^{(i)}x^{(j)}$$



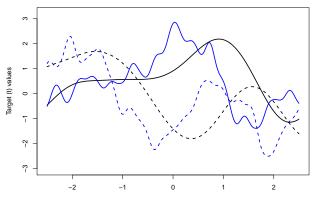
$$Cov [t^{(i)}, t^{(j)}] = 1 + x^{(i)}x^{(j)} + 0.1^{2} \exp\left(-3^{2} (x^{(i)} - x^{(j)})^{2}\right)$$
$$Cov [t^{(i)}, t^{(j)}] = 1 + x^{(i)}x^{(j)}$$



$$\mathsf{Cov}\left[t^{(i)}, t^{(j)}\right] = \exp\left(-\left(x^{(i)} - x^{(j)}\right)^2\right)$$



$$Cov [t^{(i)}, t^{(j)}] = exp \left(- (x^{(i)} - x^{(j)})^2 \right) + 0.5^2 exp \left(-5^2 (x^{(i)} - x^{(j)})^2 \right)$$
$$Cov [t^{(i)}, t^{(j)}] = exp \left(- (x^{(i)} - x^{(j)})^2 \right)$$



Enough with the covariance functions

- May be constructed with various components e.g. constant, linear, exponential.
- Components of the covariance function may reflect different plausible features of the underlying structure
- Valid covariance function must always result in a positive definite covariance matrix for the targets.
- Different forms of the covariance function Cov [t⁽ⁱ⁾, t^(j)] define infinitely many flexible regression models

Step back to prediction

• Targets still have a multivariate Gaussian distribution

$$t = \left[t^{(1)}, \ldots, t^{(n)}\right]^{T} \sim N_{n}\left(\mathbf{0}, \mathbf{C}\right)$$

- $C_{ij} = \operatorname{Cov}\left[t^{(i)}, t^{(j)}\right]$
- Given the inputs for a new case x⁽ⁿ⁺¹⁾, the predictive distribution for the new outcome t⁽ⁿ⁺¹⁾ is Gaussian:

$$\mathsf{E}\left[t^{(n+1)} \mid t^{(1)}, \dots, t^{(n)}\right] = k^{\mathsf{T}} \mathsf{C}^{-1} t \\ \mathsf{var}\left[t^{(n+1)} \mid t^{(1)}, \dots, t^{(n)}\right] = \mathsf{V} - k^{\mathsf{T}} \mathsf{C}^{-1} k$$

•
$$k = \left(\text{Cov} \left[t^{(n+1)}, t^{(1)} \right], \dots, \text{Cov} \left[t^{(n+1)}, t^{(n)} \right] \right)^T$$

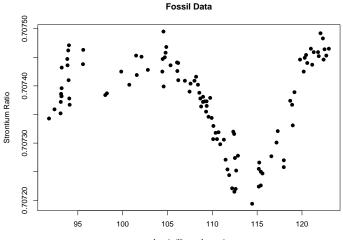
• $V = \text{Cov} \left[t^{(n+1)}, t^{(n+1)} \right] = \text{prior var} \left[t^{(n+1)} \right]$

Finally ... some data

- 106 observations of fossil shells
- Age (in millions of years) and Ratios of strontium isotopes
- Previous example from STAT 527
- Data from SemiPar package in R [Ruppert et al., 2003], who got it from Bralower et al. [1997]



An "old" dataset



Age (millions of years)

How to fit a Gaussian Process Regression Model

• Assume the prior covariance function:

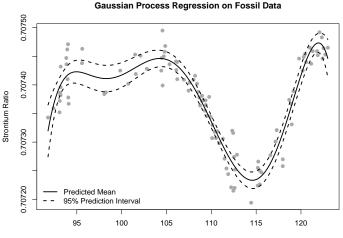
$$\boldsymbol{C}_{ij} = \operatorname{Cov}\left[t^{(i)}, t^{(j)}\right] = \eta^{2} \exp\left(-\rho^{2} \left(x^{(i)} - x^{(j)}\right)^{2}\right) + \delta_{ij} \sigma_{\epsilon}^{2}$$

• Based on the multivariate Gaussian distribution of the outcomes, the log-likelihood is:

$$\log p(t \mid x, \eta, \rho) = -\frac{n}{2}\log(2\pi) - \frac{1}{2}\log|\boldsymbol{C}| - \frac{1}{2}t^{\mathsf{T}}\boldsymbol{C}^{-1}t$$

- Find maximum likelihood esimates $\hat{\eta}, \hat{
 ho}$
- σ_{ϵ}^2 assumed to be fixed at 10^{-9}

Gaussian Process Regression on Fossil data



Age (millions of years)

What's Next?

$$\boldsymbol{\mathcal{C}}_{ij} = \operatorname{Cov}\left[t^{(i)}, t^{(j)}\right] = \eta^{2} \exp\left(-\rho^{2} \left(x^{(i)} - x^{(j)}\right)^{2}\right) + \delta_{ij} \sigma_{\epsilon}^{2}$$

- How to implement a Bayesian approach?
 - Integrate out parameters to get "parameter-free" marginal distribution $p(t^{(n+1)} | t^{(1)}, ..., t^{(n)})$ for prediction?
- More to come . . .
 - Compare against other semi-parametric procedures
 - *p*-dimension covariate regression example (p > 1)
 - How to implement a three-way classification / discrimination procedure?

References

- T J Bralower, P D Fullagar, C K Paull, G S Dwyer, and R M Leckie. Mid-Cretaceous strontium-isotope stratigraphy of deep-sea sections. *Geological Society of America Bulletin*, 109:1421–1442, 1997. doi: 10.1130/0016-7606(1997)109(1421.
- R M Neal. Regression and classification using Gaussian process priors (with discussion). *Bayesian Statistics*, 6: 475–501, 1999.
- David Ruppert, Matthew P Wand, and Raymond J Carroll. Semiparametric regression, volume 12. Cambridge University Press, 2003. ISBN 0521785162.