

Application of Time-to-Event Methods in the Assessment of Safety in Clinical Trials

Progress, Updates, Problems

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Overview

- Marginal vs Conditional
- What is TMLE?
- Key Estimation procedure
- Some test simulations
- Hidden assumptions
- Hidden Statistical Properties

Brief Review: Time-to-event outcomes

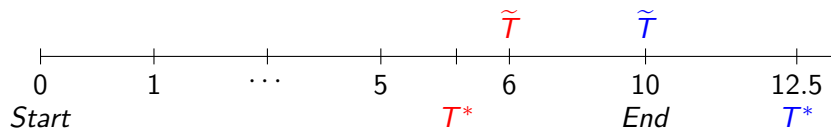
$$S(t) = \Pr(T > t) = 1 - F(t)$$

$$\lambda(t) = \lim_{\Delta t \rightarrow 0} \frac{\Pr[t \leq T < t + \Delta t | T \geq t]}{\Delta t}$$

Event of Interest: Infection/AE at clinic visit

Right censored data: Non-ignorable missing data.

Discrete Failure Time (Zhang and Gilbert, 2010)



$$\lambda(t_j) = \Pr(T = t_j | T > t_{j-1})$$

T^* : "True" failure time (Unobserved due to discrete follow-up)

$T = t_j$ if $T^* \in [t_{j-1}, t_j)$ with t_j for $j = 1, \dots, 10$.

$\tilde{T} = \min(T, C)$: where C is our censoring time.

$\Delta = I(T \leq C)$: Indicator of subject **not** being censored

Objectives (Moore and van der Laan, 2009b)

- Estimate **marginal** treatment specific survival at a fixed end point
- Use covariates to gain efficiency
- Provide a consistent estimator in the presence of **informative censoring**

Question we want to address

Approximate Scientific question: $\Pr(T_1 > t_k) - \Pr(T_0 > t_k)$

Event of Interest: First record of adverse event reported

Simplest analysis: Kaplan Meier Survival curves

Assumptions: Random censoring

Adjusted analysis: Cox-PH or Logistic regression (More assumptions)

RCT: Marginal or Conditional

Scientific question: $\Pr(T > t_k | A = 1) - \Pr(T > t_k | A = 0)$

Marginal

$$P(T > t | A = a) = S_0(t | A = a)$$

Estimated probability of survival past time t for treatment a for the entire population.

Conditional

$$P(T > t | A = a, W) = S_0(t | A = a, W)$$

Estimated probability of survival past time t for treatment a while holding W fixed.

What does TMLE estimate

Let $\Psi : \mathcal{M} \rightarrow \mathbb{R}$ is pathwise differentiable at any density $p_0 \in \mathcal{M}$

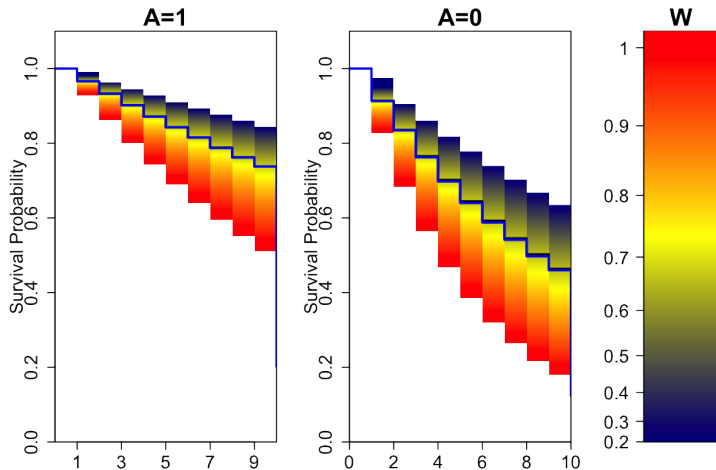
$$\begin{aligned}\psi_1(p_0)(t_k) &= \overbrace{\Pr(T_1 > t_k)}^{\text{Marginal}} = E_W[\overbrace{S_0(t_k|A=1, \mathbf{W})}^{\text{Conditional}}] \\ \psi_0(p_0)(t_k) &= \Pr(T_0 > t_k) = E_W[S_0(t_k|A=0, \mathbf{W})] \\ \psi_{AD}(p_0)(t_k) &= \psi_1(p_0)(t_k) - \psi_0(p_0)(t_k)\end{aligned}$$

Consider the treatment group $A = 1$,

$\Pr(T_1 > t_k|\mathbf{W}) = S_0(t_k|A=1, \mathbf{W})$: Probability of surviving beyond t_k when treatment is 1 given the covariates W .

$\Pr(T_1 > t_k) = E[S_0(t_k|A=1, \mathbf{W})]$: Probability of surviving beyond t_k when treatment is 1 averaging over the covariates W .

Example: Random treatment assignment of 0.5



$$W \sim U(0.2, 1.2)$$

$$\lambda(t|A, W) = \text{expit}(-3 - A + W^2)I(t < 10) + I(t = 10)$$

Idea behind TMLE (Van Der Laan, 2011)

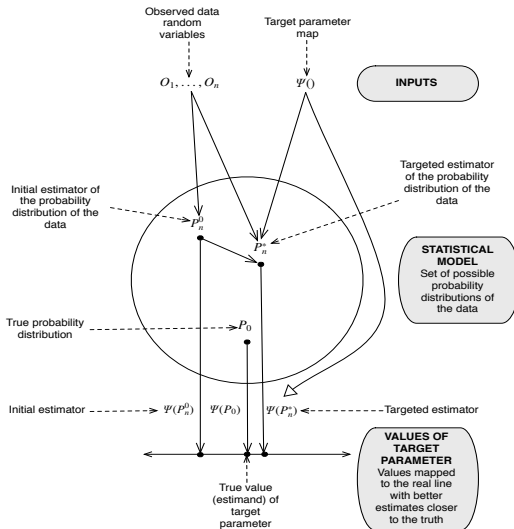


Fig. 5.1 TMLE flow chart.

Likelihood representation for 1 observation

\mathbf{W} : Covariates

A : Treatment

(\tilde{T}, Δ) : Time and event indicator

$\bar{G}(t_-|A, \mathbf{W}) = \Pr(C \geq t|A, \mathbf{W})$ (Moore and van der Laan, 2009a)

$$S(t_k|A, W) = \prod_{t \leq t_k} [1 - \lambda(t|A, W)]$$

$$P_0(\mathcal{O}) = \Pr(\mathbf{W}, A, \tilde{T}, \Delta) = \Pr(\tilde{T}, \Delta | \mathbf{W}, A) \Pr(\mathbf{W}) \Pr(A | \mathbf{W})$$

$$\begin{aligned} & \overbrace{\left[\lambda(t_k|A, \mathbf{W}) \prod_{t=1}^{t_k-1} (1 - \lambda(t_k|A, \mathbf{W})) \right]^\delta \left[\prod_{t=1}^{t_k} (1 - \lambda(t_k|A, \mathbf{W})) \right]^{1-\delta}}^{Q_{20}} \\ & \underbrace{\bar{G}(t_-|A, \mathbf{W})^\delta}_{g_{20}} \underbrace{\Pr(C = t_k|A, \mathbf{W})^{1-\delta}}_{Q_{10}} \underbrace{\Pr(\mathbf{W}) \Pr(A|\mathbf{W})}_{g_{10}} \end{aligned}$$

Key Results for TMLE: Doubly robust

Q_0

Q_{10} : Distribution of the baseline covariates

Q_{20} : Conditional distribution of the hazard given treatment and baseline covariates

g_0

g_{10} : Treatment mechanism

g_{20} : Conditional distribution of the censoring distribution given treatment and baseline covariates

Either Q_0 or g_0 is correct, then TMLE is consistent

TMLE as Plug-in estimators

1. Estimate the $\hat{g}^0(A = 1|W) = \frac{1}{n} \sum_{i=1}^n A_i$
2. Estimate the conditional probability of censoring $\bar{G}^0(t_-|A, W)$
3. Estimate the $\hat{\lambda}^0(t|A, W)$ via logistic regression

$$\text{logit}[\hat{\lambda}^0(t|A, W)] = \sum_{i=1}^K \alpha_i I(t = i) + \beta_A A + \beta_W W$$

4. Update the above model using $\hat{\lambda}^0(t|A, W)$ by including the penalty $\epsilon = \{\epsilon_0, \epsilon_1\}$ and the “clever” covariate $\hat{h}^0(t, A, W) = \{\hat{h}_0, \hat{h}_1\}$

$$\text{logit}[\hat{\lambda}^1(t|A, W)] = \text{logit}[\hat{\lambda}^0(t|A, W)] + \epsilon^T \hat{h}^0(t, A, W)$$

$$\hat{h}_i(t, A, W) = - \frac{I(A = i)I(t \leq t_k)}{\hat{g}^0(A = i|W)\bar{G}^0(t_-|A, W)} \frac{\hat{S}(t_k|A, W)}{\hat{S}(t|A, W)}$$

TMLE as Plug-in estimators continued

5. Use current estimate of $\hat{\lambda}^1(t|A, W)$ to update $\hat{h}^1(t, A, W)$

$$\hat{S}(t_k|A, W) = \prod_{t \leq t_k} [1 - \hat{\lambda}^1(t|A, W)]$$

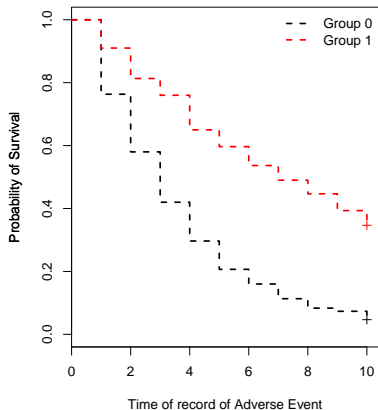
6. Iterate 4 & 5 until $\hat{\epsilon} \rightarrow 0$
7. Plug-in final estimate of $\hat{S}_i^*(t_k|A = i, W)$ for $i = 0, 1$

$$\hat{\Psi}_1(p_0)(t_k) = \frac{1}{n} \sum_{i=1}^n \hat{S}^*(t_k|A = 1, W_i)$$

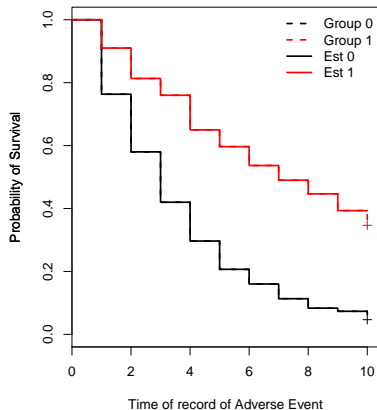
$$\hat{\Psi}_0(p_0)(t_k) = \frac{1}{n} \sum_{i=1}^n \hat{S}^*(t_k|A = 0, W_i)$$

Test simulations with no covariates

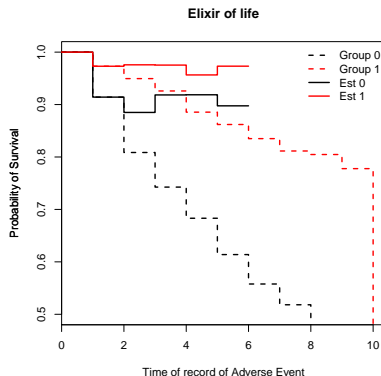
Ta-Da!!!



Ta-Da!!!



Test Simulations for weak covariates



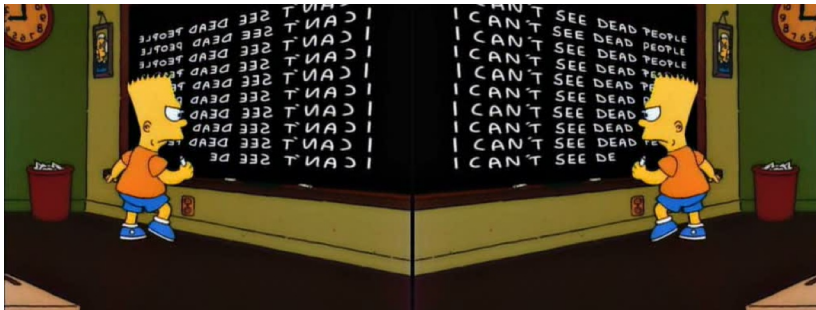
Simulations

$$W \sim U(0.2, 1.2); A \sim \text{Bin}(0, \frac{1}{2})$$

$$\lambda(t|A, W) = \text{expit}(-3 - A + W^2)I(t < 10) + I(t = 10)$$

Problem

Survival function never increases over time.



Acknowledgements: Taken from bartsblackboard.com

Next steps

Compute the variance/Bootstrap

Rerun simulations

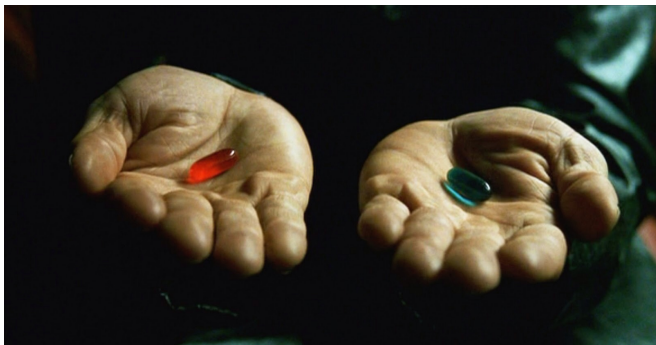
Fill in the gaps in the paper

Extensions

References

- Moore, K. and van der Laan, M. (2009a). Increasing power in randomized trials with right censored outcomes through covariate adjustment. *Journal of biopharmaceutical statistics*, 19(6):1099–1131.
- Moore, K. L. and van der Laan, M. J. (2009b). Application of time-to-event methods in the assessment of safety in clinical trials (chapter 20). In Peace, K. E., editor, *Design and Analysis of Clinical Trials with Time-to-Event Endpoints*, pages 455–482. Chapman and Hall/CRC; Biostatistics Series.
- Stitelman, O. and van der Laan, M. (2010). Collaborative targeted maximum likelihood for time to event data. *The international journal of biostatistics*, 6(1):Article–21.
- Van Der Laan, M. (2011). *Targeted Learning: Causal Inference for Observational and Experimental Data*. Springer.
- Zhang, M. and Gilbert, P. B. (2010). Increasing the efficiency of prevention trials by incorporating baseline covariates. *Statistical communications in infectious diseases*, 2(1).

Thinking in counterfactuals



You take the red pill - you stay in Wonderland and I show you how deep the rabbit hole goes.

You take the blue pill - the story ends, you wake up in your bed and believe whatever you want to believe.

Morpheus, The Matrix

Hidden Assumptions: Thinking in counterfactuals

For an individual in the placebo arm...

$$IC_{0t_k}^*(p_O) = \sum_{t \leq t_k} [I(\tilde{T} = t, \Delta = 1) - I(\tilde{T} \geq t)\lambda(t|A=0, W)]h_0(t, A, W) \\ + S_0(t_k|A=0, W) - \Psi_0(p_O)(t_k)$$

$$h_i(t, A, W) = -\frac{I(A=i)}{g(1)\bar{G}(t_-|A, W)} \frac{S(t_k|A, W)}{S(t|A, W)} I(t \leq t_k)$$

Key assumptions 1: Coarsening at random

Definition of CAR (Stitelman and van der Laan, 2010)

Coarsened data structures are data structures where the full data is not observed.

“Coarsening mechanism” is only a function of the full data, i.e. the data in which you would have seen all counterfactuals, through the observed data

Implications

$$dP_0(O) = Q_0(O)g_0(O|X)$$

Q_0 is the density associated with full data

g_0 contains the censoring and treatment mechanism.

Statistical definitions

\mathcal{M} is the set of possible probability distribution of \mathcal{O} with probability distribution $P_0 \in \mathcal{M}$ where \mathcal{M} is dominated by common measure μ . Hence, density $p = \frac{dP_0}{d\mu}$

O_1, \dots, O_n are n i.i.d realizations of \mathcal{O} .

O_1, \dots, O_n can be represented by the empirical probability distribution P_n placing mass $1/n$ on each of the n observations.

Statistical properties

TMLE uses solves the efficient Influence curve.

IDEA: If we can linearize our estimator

Linearity of estimator

An estimator ψ_n is an asymptotically linear estimator of a parameter ψ if

$$\psi_n - \psi = \frac{1}{n} \sum_{i=1}^n IC_P(O_i) + o_P\left(\frac{1}{\sqrt{n}}\right)$$

where the influence curve $IC_P(O)$ has expectation 0 and finite variance i.e. $IC_P(O) \in L_0^2(P)$ and moreover this should hold for all $P \in \mathcal{M}$.

Efficient Influence curve

Asymptotic Distribution

The asymptotic distribution (via linearity of the influence curve)

$$\sqrt{n} \left(\hat{\psi}^*(t_k) - \Psi(p_0)(t_k) \right) \rightarrow N(0, \sigma^2)$$

Estimate σ^2 by empirical variance

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n IC_P(O_i)^2$$

Implications

Compute Wald-like confidence intervals $\hat{\psi}^*(t_k) \pm 1.96 \frac{\hat{\sigma}^2}{\sqrt{n}}$