

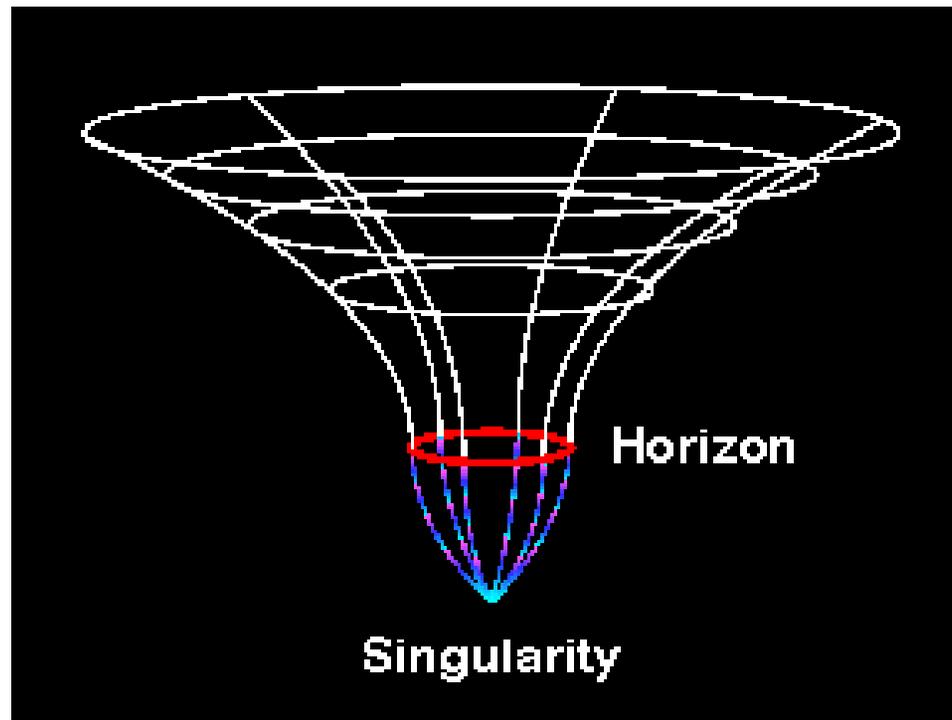
Physics 311
GENERAL RELATIVITY

Lecture 15:
Metrics and curved space

NO HOMEWORK this week

Today's lecture plan

- Flat spacetime of Special Relativity.
- Solving Einstein Field Equation for empty space – the “vacuum solution”
- Schwarzschild metric



A look back

- In Special Relativity the spacetime is said to be “flat”, it has no “curvature”. What do we mean when we say “the spacetime is flat”, “the spacetime has no curvature”?
- We mean that the path of a free particle is a straight line, and that the square of the interval is a *linear* combination of the space and time components squared:

$$ds^2 = dt^2 - (dx^2 + dy^2 + dz^2)$$

(in the system of units where $c = 1$)

- This is a lot like the Euclidean geometry, which is also flat. We’ve alluded to a non-Euclidean geometry in the last lecture; we’ll soon see how it comes to be.

The Minkowski metric

- We can write the expression for the interval in the matrix form:

$$ds = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & i & 0 & 0 \\ 0 & 0 & i & 0 \\ 0 & 0 & 0 & i \end{pmatrix} \times \begin{pmatrix} dt \\ dx \\ dy \\ dz \end{pmatrix}$$

(so that $ds^2 = dt^2 - dx^2 - dy^2 - dz^2$)

- This matrix – a very simple matrix indeed – defines the metric of Special Relativity, the **Minkowski metric**. It is simple yet powerful; it completely describes the spacetime of Special Relativity.

Einstein Field Equation: another dissection

- Generally speaking, Einstein field equation

$$\mathbf{G}_{\mu\nu} = 8\pi\mathbf{T}_{\mu\nu}$$

is a set of 10 (16 components in each tensor, minus 6 due to symmetry, and if you're smart enough, minus 4 more) *coupled elliptic-hyperbolic nonlinear partial differential equations for the metric components*.

- Just so that we are clear on definitions:

“**coupled**” – each differential equation contains multiple terms; equations cannot be solved individually.

“**elliptic-hyperbolic**” – determinants of sub-matrices of the system of equations matrix are either positive or negative; never zero.

“**nonlinear**” – dependent on nonlinear function of metric components

“**partial differential equation**” – an equation containing partial derivatives of functions, for example $\partial^2 f(x,y,z)/\partial x \partial y$

“**metric components**” – components of the metric tensor $g_{\mu\nu}$

Einstein Field Equation expanded

- From “simple” form: $\mathbf{G}_{\mu\nu} = 8\pi\mathbf{T}_{\mu\nu}$

...to rather more complex, expanded form...

$$\begin{aligned}
 & \left[\partial_{\eta}(\Gamma_{\mu\nu}^{\eta}) - \partial_{\nu}(\Gamma_{\eta\mu}^{\eta}) + \Gamma_{\eta\lambda}^{\eta} \Gamma_{\mu\nu}^{\lambda} - \Gamma_{\mu\eta}^{\lambda} \Gamma_{\nu\lambda}^{\eta} \right] \\
 & - \frac{1}{2} g^{\alpha\beta} \left[\partial_{\eta}(\Gamma_{\alpha\beta}^{\eta}) - \partial_{\beta}(\Gamma_{\eta\alpha}^{\eta}) + \Gamma_{\eta\lambda}^{\eta} \Gamma_{\alpha\beta}^{\lambda} - \Gamma_{\alpha\eta}^{\lambda} \Gamma_{\beta\lambda}^{\eta} \right] g_{\mu\nu} = 8\pi T_{\mu\nu}
 \end{aligned}$$

Note: The diagram shows a red bracket grouping the first two lines, with an arrow pointing to $R_{\mu\nu}$. A green bracket groups the second line, with an arrow pointing to R .

Here, $\Gamma_{\alpha\beta}^{\gamma} = \frac{1}{2} g^{\delta\gamma} [\partial_{\beta}(g_{\alpha\delta}) + \partial_{\alpha}(g_{\beta\delta}) - \partial_{\delta}(g_{\alpha\beta})]$ are *Christoffel symbols of 2nd kind* – tensor-like objects derived from Riemann metric g ;

$\partial_{\alpha} = (\partial/\partial x^{\alpha})$ denotes partial derivative with respect to variable x^{α} ;

and $g_{\alpha\beta}$ is the metric tensor – roughly speaking, the function that tells us how to compute distances between points in a given space:

$$ds^2 = \sum g_{\alpha\beta} dx_{\alpha} dx_{\beta}$$

Back to Minkowski metric

- The matrix in the expression for the interval is nothing more, nor less, than the Minkowski metric tensor $g_{\alpha\beta}$

$$ds = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & i & 0 & 0 \\ 0 & 0 & i & 0 \\ 0 & 0 & 0 & i \end{pmatrix} \times \begin{pmatrix} dt \\ dx \\ dy \\ dz \end{pmatrix}$$

- So we actually know one metric tensor already – it's not too scary at all!

... but that's a very special case...

... a slightly more general case...

... looks a lot different...

If you sit down and write down the Ricci tensor for a general case of a 2-dimensional space with axial symmetry, you would get something like this:

$$\begin{aligned}
R_{\eta\eta} = & -\frac{2a^2 \frac{\partial \psi}{\partial \theta} \cot \theta}{\delta \psi} + \frac{2ac \frac{\partial \psi}{\partial \eta} \cot \theta}{\delta \psi} + \frac{a \frac{\partial c}{\partial \eta} \cot \theta}{\delta} - \frac{\frac{\partial a}{\partial \eta} c \cot \theta}{2\delta} - \frac{a \frac{\partial a}{\partial \theta} \cot \theta}{2\delta} - \frac{2a^2 \frac{\partial^2 \psi}{\partial \theta^2}}{\delta \psi} \\
& - \frac{2a^2 \left(\frac{\partial \psi}{\partial \theta}\right)^2}{\delta \psi^2} + \frac{4ac \frac{\partial \psi}{\partial \eta} \frac{\partial \psi}{\partial \theta}}{\delta \psi^2} - \frac{a^2 \frac{\partial d}{\partial \theta} \frac{\partial \psi}{\partial \theta}}{\delta d \psi} + \frac{ac \frac{\partial d}{\partial \eta} \frac{\partial \psi}{\partial \theta}}{\delta d \psi} + \frac{2a \frac{\partial c}{\partial \eta} \frac{\partial \psi}{\partial \theta}}{\delta \psi} - \frac{\frac{\partial a}{\partial \eta} c \frac{\partial \psi}{\partial \theta}}{\delta \psi} \\
& - \frac{3a \frac{\partial a}{\partial \theta} \frac{\partial \psi}{\partial \theta}}{\delta \psi} - \frac{2a^2 c \frac{\partial c}{\partial \theta} \frac{\partial \psi}{\partial \theta}}{\delta^2 \psi} + \frac{2a^2 b \frac{\partial c}{\partial \eta} \frac{\partial \psi}{\partial \theta}}{\delta^2 \psi} - \frac{a^2 \frac{\partial b}{\partial \eta} c \frac{\partial \psi}{\partial \theta}}{\delta^2 \psi} - \frac{a \frac{\partial a}{\partial \eta} b c \frac{\partial \psi}{\partial \theta}}{\delta^2 \psi} + \frac{a^3 \frac{\partial b}{\partial \theta} \frac{\partial \psi}{\partial \theta}}{\delta^2 \psi} \\
& + \frac{a^2 \frac{\partial a}{\partial \theta} b \frac{\partial \psi}{\partial \theta}}{\delta^2 \psi} - \frac{2ab \frac{\partial^2 \psi}{\partial \eta^2}}{\delta \psi} - \frac{2 \frac{\partial^2 \psi}{\partial \eta^2}}{\psi} + \frac{4ac \frac{\partial^2 \psi}{\partial \eta \partial \theta}}{\delta \psi} - \frac{2ab \left(\frac{\partial c}{\partial \eta}\right)^2}{\delta \psi^2} + \frac{6 \left(\frac{\partial \psi}{\partial \eta}\right)^2}{\psi^2} \\
& + \frac{ac \frac{\partial d}{\partial \theta} \frac{\partial \psi}{\partial \eta}}{\delta d \psi} - \frac{ab \frac{\partial d}{\partial \eta} \frac{\partial \psi}{\partial \eta}}{\delta d \psi} - \frac{2c \frac{\partial c}{\partial \eta} \frac{\partial \psi}{\partial \eta}}{\delta \psi} + \frac{\frac{\partial a}{\partial \theta} c \frac{\partial \psi}{\partial \eta}}{\delta \psi} - \frac{2a \frac{\partial b}{\partial \eta} \frac{\partial \psi}{\partial \eta}}{\delta \psi} + \frac{\frac{\partial a}{\partial \eta} b \frac{\partial \psi}{\partial \eta}}{\delta \psi} \\
& + \frac{2a^2 b \frac{\partial c}{\partial \theta} \frac{\partial \psi}{\partial \eta}}{\delta^2 \psi} - \frac{2abc \frac{\partial c}{\partial \eta} \frac{\partial \psi}{\partial \eta}}{\delta^2 \psi} - \frac{a^2 \frac{\partial b}{\partial \theta} c \frac{\partial \psi}{\partial \eta}}{\delta^2 \psi} - \frac{a \frac{\partial a}{\partial \theta} b c \frac{\partial \psi}{\partial \eta}}{\delta^2 \psi} + \frac{a^2 b \frac{\partial b}{\partial \eta} \frac{\partial \psi}{\partial \eta}}{\delta^2 \psi} + \frac{a \frac{\partial a}{\partial \eta} b^2 \frac{\partial \psi}{\partial \eta}}{\delta^2 \psi} \\
& + \frac{a \frac{\partial c}{\partial \eta} \frac{\partial d}{\partial \theta}}{2\delta d} - \frac{\frac{\partial a}{\partial \eta} c \frac{\partial d}{\partial \theta}}{4\delta d} - \frac{a \frac{\partial a}{\partial \theta} \frac{\partial d}{\partial \theta}}{4\delta d} - \frac{\frac{\partial^2 d}{\partial \eta^2}}{2d} + \frac{\left(\frac{\partial d}{\partial \eta}\right)^2}{4d^2} - \frac{c \frac{\partial c}{\partial \eta} \frac{\partial d}{\partial \eta}}{2\delta d} \\
& + \frac{\frac{\partial a}{\partial \theta} c \frac{\partial d}{\partial \eta}}{4\delta d} + \frac{\frac{\partial a}{\partial \eta} b \frac{\partial d}{\partial \eta}}{4\delta d} + \frac{a \frac{\partial^2 c}{\partial \eta \partial \theta}}{\delta} - \frac{a \frac{\partial^2 b}{\partial \eta^2}}{2\delta} - \frac{a \frac{\partial^2 a}{\partial \theta^2}}{2\delta} + \frac{ac \frac{\partial c}{\partial \eta} \frac{\partial c}{\partial \theta}}{\delta^2}
\end{aligned}$$

$$\begin{aligned}
& -\frac{a \frac{\partial a}{\partial \theta} c \frac{\partial c}{\partial \theta}}{2 \delta^2} - \frac{a \frac{\partial a}{\partial \eta} b \frac{\partial c}{\partial \theta}}{2 \delta^2} - \frac{a \frac{\partial b}{\partial \eta} c \frac{\partial c}{\partial \eta}}{2 \delta^2} - \frac{a^2 \frac{\partial b}{\partial \theta} \frac{\partial c}{\partial \eta}}{2 \delta^2} + \frac{a \frac{\partial a}{\partial \eta} \frac{\partial b}{\partial \theta} c}{4 \delta^2} - \frac{a \frac{\partial a}{\partial \theta} \frac{\partial b}{\partial \eta} c}{4 \delta^2} \\
& + \frac{a^2 \frac{\partial a}{\partial \theta} \frac{\partial b}{\partial \theta}}{4 \delta^2} + \frac{a^2 \left(\frac{\partial b}{\partial \eta}\right)^2}{4 \delta^2} + \frac{a \frac{\partial a}{\partial \eta} b \frac{\partial b}{\partial \eta}}{4 \delta^2} + \frac{a \left(\frac{\partial a}{\partial \theta}\right)^2 b}{4 \delta^2}
\end{aligned}$$

$$R_{\eta\theta} = -\frac{2ac \frac{\partial \psi}{\partial \theta} \cot \theta}{\delta \psi} + \frac{2ab \frac{\partial \psi}{\partial \eta} \cot \theta}{\delta \psi} - \frac{2 \frac{\partial \psi}{\partial \eta} \cot \theta}{\psi} - \frac{\frac{\partial d}{\partial \eta} \cot \theta}{2d} - \frac{\frac{\partial a}{\partial \theta} c \cot \theta}{2\delta} + \frac{a \frac{\partial b}{\partial \eta} \cot \theta}{2\delta}$$

$$-\frac{2ac \frac{\partial^2 \psi}{\partial \theta^2}}{\delta \psi} - \frac{2ac \left(\frac{\partial \psi}{\partial \theta}\right)^2}{\delta \psi^2} + \frac{4ab \frac{\partial \psi}{\partial \eta} \frac{\partial \psi}{\partial \theta}}{\delta \psi^2} + \frac{2 \frac{\partial \psi}{\partial \eta} \frac{\partial \psi}{\partial \theta}}{\psi^2} - \frac{ac \frac{\partial d}{\partial \theta} \frac{\partial \psi}{\partial \theta}}{\delta d \psi} + \frac{ab \frac{\partial d}{\partial \eta} \frac{\partial \psi}{\partial \theta}}{\delta d \psi}$$

$$-\frac{\frac{\partial d}{\partial \eta} \frac{\partial \psi}{\partial \theta}}{d \psi} + \frac{2a \frac{\partial c}{\partial \theta} \frac{\partial \psi}{\partial \theta}}{\delta \psi} - \frac{3 \frac{\partial a}{\partial \theta} c \frac{\partial \psi}{\partial \theta}}{\delta \psi} + \frac{2a \frac{\partial b}{\partial \eta} \frac{\partial \psi}{\partial \theta}}{\delta \psi} + \frac{\frac{\partial a}{\partial \eta} b \frac{\partial \psi}{\partial \theta}}{\delta \psi} - \frac{2a^2 b \frac{\partial c}{\partial \theta} \frac{\partial \psi}{\partial \theta}}{\delta^2 \psi}$$

$$+\frac{2abc \frac{\partial c}{\partial \eta} \frac{\partial \psi}{\partial \theta}}{\delta^2 \psi} + \frac{a^2 \frac{\partial b}{\partial \theta} c \frac{\partial \psi}{\partial \theta}}{\delta^2 \psi} + \frac{a \frac{\partial a}{\partial \theta} b c \frac{\partial \psi}{\partial \theta}}{\delta^2 \psi} - \frac{a^2 b \frac{\partial b}{\partial \eta} \frac{\partial \psi}{\partial \theta}}{\delta^2 \psi} - \frac{a \frac{\partial a}{\partial \eta} b^2 \frac{\partial \psi}{\partial \theta}}{\delta^2 \psi} - \frac{2bc \frac{\partial^2 \psi}{\partial \eta^2}}{\delta \psi}$$

$$+\frac{4ab \frac{\partial^2 \psi}{\partial \eta \partial \theta}}{\delta \psi} - \frac{6 \frac{\partial^2 \psi}{\partial \eta \partial \theta}}{\psi} - \frac{2bc \left(\frac{\partial \psi}{\partial \eta}\right)^2}{\delta \psi^2} + \frac{ab \frac{\partial d}{\partial \theta} \frac{\partial \psi}{\partial \eta}}{\delta d \psi} - \frac{\frac{\partial d}{\partial \theta} \frac{\partial \psi}{\partial \eta}}{d \psi} - \frac{bc \frac{\partial d}{\partial \eta} \frac{\partial \psi}{\partial \theta}}{\delta d \psi}$$

$$+\frac{2b \frac{\partial c}{\partial \eta} \frac{\partial \psi}{\partial \eta}}{\delta \psi} - \frac{3 \frac{\partial b}{\partial \eta} c \frac{\partial \psi}{\partial \eta}}{\delta \psi} + \frac{a \frac{\partial b}{\partial \theta} \frac{\partial \psi}{\partial \eta}}{\delta \psi} + \frac{2 \frac{\partial a}{\partial \theta} b \frac{\partial \psi}{\partial \eta}}{\delta \psi} + \frac{2abc \frac{\partial c}{\partial \theta} \frac{\partial \psi}{\partial \eta}}{\delta^2 \psi} - \frac{2ab^2 \frac{\partial c}{\partial \eta} \frac{\partial \psi}{\partial \eta}}{\delta^2 \psi}$$

... and just a little bit more.

$$\begin{aligned}
 & + \frac{a b \frac{\partial b}{\partial \eta} c \frac{\partial \psi}{\partial \eta}}{\delta^2 \psi} + \frac{\frac{\partial a}{\partial \eta} b^2 c \frac{\partial c}{\partial \eta}}{\delta^2 \psi} - \frac{a^2 b \frac{\partial b}{\partial \theta} \frac{\partial \psi}{\partial \eta}}{\delta^2 \psi} - \frac{a \frac{\partial a}{\partial \theta} b^2 \frac{\partial \psi}{\partial \eta}}{\delta^2 \psi} + \frac{\frac{\partial d}{\partial \eta} \frac{\partial d}}{4 d^2} - \frac{\frac{\partial a}{\partial \theta} c \frac{\partial d}{\partial \theta}}{4 \delta d} \\
 & + \frac{a \frac{\partial b}{\partial \eta} \frac{\partial d}{\partial \theta}}{4 \delta d} - \frac{\frac{\partial^2 d}{\partial \eta \partial \theta}}{2 d} - \frac{\frac{\partial b}{\partial \eta} c \frac{\partial d}{\partial \eta}}{4 \delta d} + \frac{\frac{\partial a}{\partial \theta} b \frac{\partial d}{\partial \eta}}{4 \delta d} - \frac{\frac{\partial c}{\partial \eta} \frac{\partial c}}{\delta} + \frac{\frac{\partial a}{\partial \theta} \frac{\partial c}}{2 \delta} \\
 & + \frac{c \frac{\partial^2 c}{\partial \eta \partial \theta}}{\delta} + \frac{\frac{\partial b}{\partial \eta} \frac{\partial c}{\partial \eta}}{2 \delta} - \frac{\frac{\partial^2 b}{\partial \eta^2} c}{2 \delta} - \frac{\frac{\partial^2 a}{\partial \theta^2} c}{2 \delta} - \frac{\frac{\partial a}{\partial \eta} \frac{\partial b}{\partial \theta}}{4 \delta} + \frac{\frac{\partial a}{\partial \theta} \frac{\partial b}{\partial \eta}}{4 \delta} \\
 & + \frac{a b \frac{\partial c}{\partial \eta} \frac{\partial c}}{\delta^2} - \frac{\frac{\partial a}{\partial \eta} b c \frac{\partial c}{\partial \theta}}{2 \delta^2} - \frac{a \frac{\partial a}{\partial \theta} b \frac{\partial c}{\partial \theta}}{2 \delta^2} - \frac{a \frac{\partial b}{\partial \theta} c \frac{\partial c}{\partial \eta}}{2 \delta^2} - \frac{a b \frac{\partial b}{\partial \eta} \frac{\partial c}{\partial \eta}}{2 \delta^2} + \frac{a \frac{\partial a}{\partial \theta} \frac{\partial b}{\partial \theta} c}{4 \delta^2} \\
 & + \frac{a \left(\frac{\partial b}{\partial \eta}\right)^2 c}{4 \delta^2} + \frac{\frac{\partial a}{\partial \eta} b \frac{\partial b}{\partial \eta} c}{4 \delta^2} + \frac{\left(\frac{\partial a}{\partial \theta}\right)^2 b c}{4 \delta^2} + \frac{a \frac{\partial a}{\partial \eta} b \frac{\partial b}{\partial \theta}}{4 \delta^2} - \frac{a \frac{\partial a}{\partial \theta} b \frac{\partial b}{\partial \eta}}{4 \delta^2} \\
 R_{\theta\theta} = & - \frac{2 a b \frac{\partial \psi}{\partial \theta} \cot \theta}{\delta \psi} + \frac{2 b c \frac{\partial \psi}{\partial \eta} \cot \theta}{\delta \psi} - \frac{\frac{\partial d}{\partial \theta} \cot \theta}{d} - \frac{c \frac{\partial c}{\partial \theta} \cot \theta}{\delta} + \frac{\frac{\partial b}{\partial \eta} c \cot \theta}{2 \delta} + \frac{a \frac{\partial b}{\partial \theta} \cot \theta}{2 \delta} \\
 & - \frac{2 a b \frac{\partial^2 \psi}{\partial \theta^2}}{\delta \psi} - \frac{2 \frac{\partial^2 \psi}{\partial \theta^2}}{\psi} - \frac{2 a b \left(\frac{\partial \psi}{\partial \theta}\right)^2}{\delta \psi^2} + \frac{6 \left(\frac{\partial c}{\partial \theta}\right)^2}{\psi^2} + \frac{4 b c \frac{\partial \psi}{\partial \eta} \frac{\partial \psi}{\partial \theta}}{\delta \psi^2} - \frac{a b \frac{\partial d}{\partial \theta} \frac{\partial \psi}{\partial \theta}}{\delta d \psi}
 \end{aligned}$$

This is a general expression for Ricci tensor R_{mn} in only two dimensions, with axial symmetry. (From Larry Smarr, Univ. of Illinois)

Just try to imagine all of three dimensions of space plus one of time!

Special case: vacuum

- I haven't said anything about the energy-stress tensor $T_{\mu\nu}$ yet. Well, here's an example of this tensor:

$$T_{\mu\nu} = 0$$

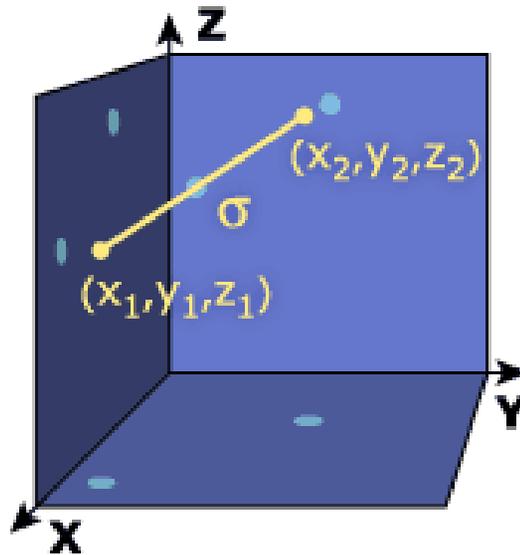
- This special case is called “vacuum”, and corresponding solutions for the metric $g_{\mu\nu}$ are called “vacuum solutions”. In this case, we have $R = 0$.
- Wait – what solutions? If we set $T_{\mu\nu}$ to zero, wouldn't our metric be just zero as well?
- Not really! The field equation now has form:

$$R_{\mu\nu} = 0$$

But the left-hand side is a **complicated mess** of derivatives of the metric. There can be many solutions for this “vacuum” equation, including several *exact analytic* solution. These different solutions arise from different symmetries we impose on the metric.

Minkowski metric (one last time)

- Minkowski metric is one of the *vacuum solutions* for a space that has perfect symmetry – a space that is:
 - uniform, so that $g(t,x,y,z) = g(t,x+\Delta x,y,z)$ (also true for y and z)
 - isotropic, so that $g(t,x,y,z) = g(t,-x,y,z)$ (also true for y and z)
- and a time that is:
- uniform, so that $g(t,x,y,z) = g(t+\Delta t,x,y,z)$



Schwarzschild Vacuum Solution

- Another important metric, first to be explicitly solved only weeks after Einstein published his General Relativity paper in 1915, is called ***Schwarzschild metric***, named after the man who solved it.
- This solution assumes *spherical symmetry* of space, as *around* an isolated star.
- How is this “vacuum” if there is a star?! There’s mass, thus there is energy, and there must be stress somehow, so tensor $T_{\mu\nu}$ must be nonzero!
- The keyword is “around” – the solution is for the metric of *empty space* (also known as “vacuum”) surrounding a spherically-symmetric massive object.



Karl Schwarzschild

Derivation of Schwarzschild solution.

1. Assumptions and notation

- We start by defining our assumptions and notation.
 1. The coordinates are (t, r, θ, ϕ) – time + spherical coordinate system. We call these coordinates x_μ , with $\mu = 1\dots 4$.
 2. Spherical symmetry: metric components are unchanged under $r \rightarrow -r$, $\theta \rightarrow -\theta$ and $\phi \rightarrow -\phi$.
 3. Spacetime is static, i.e. all metric components are independent of time: $(\partial g_{\mu\nu}/\partial t) = 0$; this also means that spacetime is invariant under time reversal.
 4. We are looking for vacuum solution $T_{\mu\nu} = 0$, with $R = 0$.
- What we need to solve then is:

$$R_{\mu\nu} = 0$$

Derivation of Schwarzschild solution.

2. Diagonalizing

- The requirements that metric be time-independent, and symmetric with respect to rotations, allow us to diagonalize the matrix:

1. Time-reversal symmetry: $(t, r, \theta, \phi) \rightarrow (-t, r, \theta, \phi)$ must conserve components of g . The components of the 1st column of the metric, $g_{\mu 1}$ ($\mu \neq 1$), transforms under time reversal as: $g_{\mu 1} \rightarrow -g_{\mu 1}$

Since we demand that $g_{\mu 1} = g_{1\mu}$, then $g_{\mu 1} = 0$ for ($\mu \neq 1$).

2. Same reasoning for r , θ and ϕ – symmetries leads to all other non-diagonal (i.e. $\mu \neq \nu$) metric components to vanish.

- Thus, the sought metric has the form:

$$ds^2 = g_{11}dt^2 + g_{22}dr^2 + g_{33}d\theta^2 + g_{44}d\phi^2$$

Derivation of Schwarzschild solution.

3. Simplifying

- On a sphere of constant radius, and at constant time, the only spherically-symmetric combination of $d\theta^2$ and $d\phi^2$ is $C(r)(d\theta^2 + \sin^2\theta d\phi^2)$, where $C(r)$ is (a yet unknown) function of radius coordinate only. This expression above is simply the element of a spherical surface.
- For constant t , θ and ϕ (i.e. on the radial line) metric should only depend on the radius coordinate r – again, to conserve the spherical symmetry. That means that the metric components for time and radius, g_{11} and g_{22} , must be functions of r only.
- This simplifies the metric even further, to:

$$ds^2 = A(r)dt^2 + B(r)dr^2 + C(r)(d\theta^2 + \sin^2\theta d\phi^2)$$

Derivation of Schwarzschild solution.

4. Solving for components

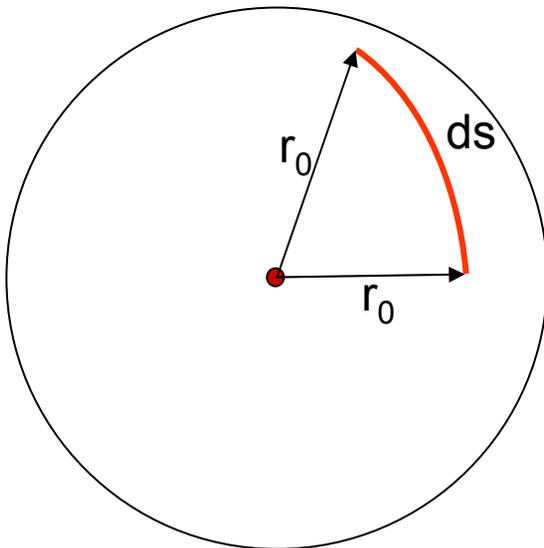
- First, we find the function $C(r)$ by noticing that at a surface of constant radius r_0 and at constant time, the separation can be written as:

$$ds^2 = r_0^2 (d\theta^2 + \sin^2\theta d\phi^2)$$

- Since this must hold true for all radial surfaces, i.e. for any r , the unknown function $C(r)$ is simply r^2 , and the θ and ϕ – components of the metric are:

$$g_{33} = r^2$$

$$g_{44} = r^2 \sin^2\theta$$



Derivation of Schwarzschild solution.

4.1. Solving for components

- Functions $A(r)$ and $B(r)$ can be found by solving the Einstein field equation (what a surprise!). Only 4 equations remain non-trivial:

$$4\partial_r AB - 2r\partial_r^2 BAB + r\partial_r A\partial_r BB + r\partial_r B^2 A = 0$$

$$r\partial_r AB + 2A^2 B - 2AB - r\partial_r BA = 0$$

$$-2r\partial_r^2 BAB + r\partial_r A\partial_r BB + r\partial_r B^2 A - 4\partial_r BA = 0$$

$$(-2r\partial_r^2 BAB + r\partial_r A\partial_r BB + r\partial_r B^2 A - 4\partial_r BAB)\sin^2\theta = 0$$

- Subtracting equations 1 and 3 leads to:

$$\partial_r AB + \partial_r BA = 0 \Rightarrow A(r)B(r) = K \text{ (a non-zero, real constant)}$$

- Substituting into equation 2 we get:

$$r\partial_r A - A(1 - A) = 0 \Rightarrow A(r) = K[1 + 1/(Sr)] = g_{11}$$

$$B(r) = [1 + 1/(Sr)]^{-1} = g_{22}$$

Derivation of Schwarzschild solution.

5. Arriving at solution

- Finally, we find the coefficients K and S in the *weak-field approximation* – i.e. far away from the gravitational source. At $r \rightarrow \infty$ the spacetime must approach Minkowski spacetime, thus:

$$g_{11} = K[1 + 1/(Sr)] \rightarrow K \Rightarrow K = c^2 = 1$$

- Gravity must converge to Newtonian in the weak field. This lets us find the numerical value of the constant S :

$$S = -c^2/(2Gm) = -1/(2m)$$

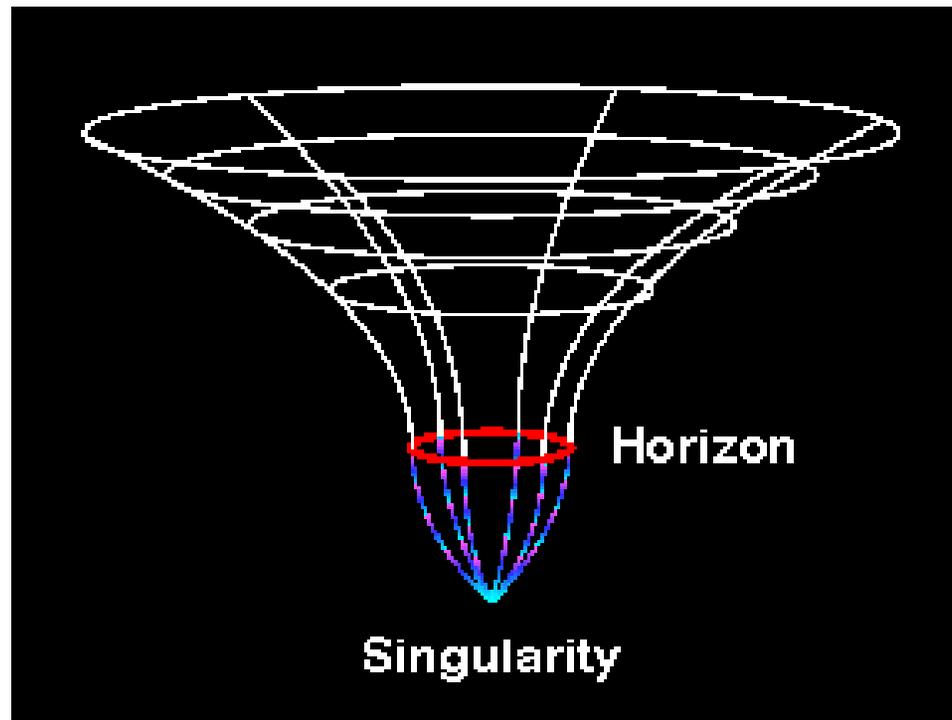
where m is the mass of the central body, and G is the gravitational constant.

- The full Schwarzschild metric is:

$$ds^2 = [1-(2m/r)]dt^2 - (1-(2m/r))^{-1}dr^2 - r^2d\theta^2 - r^2\sin^2\theta d\phi^2$$

Schwarzschild spacetime

- Schwarzschild spacetime has curvature that decreases with distance from the center. At infinity, Schwarzschild spacetime is identical to the flat Minkowski spacetime.
- In the center of Schwarzschild metric, *singularity* is possible, leading to formation of a Schwarzschild (non-rotating) *black hole*.



Recap:

- Einstein field equations can be explicitly solved for certain types of stress-energy tensor. These solutions are called *spacetime metrics*.
- Special case of stress-energy tensor – the vacuum – leads to Minkowski and Schwarzschild spacetime (among many others).
- Schwarzschild metric is fairly simple. We will mostly see its 3-dimensional (one time plus two space) case:

$$ds^2 = [1 - (2m/r)]dt^2 - [1 - (2m/r)]^{-1}dr^2 - r^2d\phi^2$$