Lecture 3. Terrestrial locomotion II: mechanical analysis of gaits and jumpiness.

- Recap: gaits and ballistic walking
- When the Froude Number (V<sup>2</sup>/g L) is greater than 1, simple ballistic walking is no longer possible.
- More aspects of jumping (energy and force)
- The jumper model accounts for an airborne phase of movement.
- Calculating optimal gaits for energy expenditure

#### Running: a combination of walking and jumping







# Kinematics and dynamics of jumping



Center of mass is a function of shape.

Animals move by exerting forces on their environment.

$$\Sigma \mathbf{F} = M \cdot \mathbf{a}$$

At which point on the moving body do we measure acceleration?

#### center of mass

$$x_{COM} = \frac{1}{M} \int_0^M x \ dm$$
$$y_{COM} = \frac{1}{M} \int_0^M y \ dm$$

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## The tradeoff between potential and kinetic energy



Kinetic Energy energy due to motion

kinetic energy of a moving body

Potential Energy energy of an object in a force field

gravitational potential energy mgh

elastic potential energy

 $\frac{1}{2}kx^2$ 

 $\frac{1}{2}mv^2$ 

#### Work

changes the energy of a system

Force in the same direction of motion yields positive work.

Force opposing the motion yields negative work.

#### The tradeoff between potential and kinetic energy



What are the forces at play?

What are the kinetic and potential energy of the system?

What is the work being done?



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#### Review of walking



#### How much energy input is needed for walking?



Matthis & Fajen, 2013

# Energy tradeoffs in walking and running









elastic potential energy

The jumper: for speeds greater than Fr = 1, gait must change with an airborne phase







Spring Loaded Inverted Pendulum







$$h = \frac{1}{2}g(\frac{T_{\text{air}}}{2})^2 = (1-\beta)^2 \frac{m \ g \ L^2}{8 \ V^2}$$

#### Energy

$$W = PE + KE$$
$$PE = m g h = (1 - \beta)^2 \frac{m g^2 L^2}{8 V^2}$$
$$KE = \frac{1}{2}m V^2$$

What is the average power per stride? What is the power during stance?