

# Digital Communication Systems Engineering with Software-Defined Radio

Di Pu, Alexander M. Wyglinski  
Worcester Polytechnic Institute

## Lecture 02

# Microelectronics Evolution is Key!

- ▶ Rapid evolution of microelectronics over the past several decades
  - ▶ **Moore's Law** defines the long-term trend of the number of transistors accommodated on an integrated circuit
  - ▶ Doubling number of transistors per integrated circuit approximately every two years
  - ▶ Affects processing speed and memory
- ▶ Microelectronics industry has significantly influenced digital communication systems sector
  - ▶ Digital communication transceivers are becoming more *versatile, powerful, and portable*
- ▶ Microelectronics advancements have given rise to **software-defined radio** (SDR) technology
  - ▶ Baseband radio functions can be *entirely* implemented in digital logic and software

# Types of Microelectronics for SDR Implementation

- ▶ General Purpose Microprocessor
  - ▶ Very flexible in terms of reconfigurability
  - ▶ Easy to implement new digital communication modules
  - ▶ Not specialized for mathematical computations
  - ▶ Potentially power inefficient
- ▶ Digital Signal Processor (DSP)
  - ▶ Specialized for performing mathematical computations
  - ▶ Easy to implement new digital communication modules
  - ▶ Potentially slow for computationally expensive processes
  - ▶ Can be power efficient (e.g., used in cellular telephones)
- ▶ Field Programmable Gate Array (FPGA)
  - ▶ Computationally powerful
  - ▶ Power inefficient
  - ▶ Not flexible nor easy to implement new modules
- ▶ Graphics Processing Unit (GPU)
  - ▶ Extremely powerful computationally
  - ▶ Difficult to use and implement new modules

# SDR Definition

- ▶ A class of reconfigurable/reprogrammable radios whose physical layer characteristics can be significantly modified via software changes
  - ▶ Capable of implementing different functions at different times on the same platform
  - ▶ Defines in software baseband radio features, e.g., modulation, error correction coding
  - ▶ Possesses some software control over RF front-end operations, e.g., transmission carrier frequency
- ▶ Baseband radio functionality stored in memory
  - ▶ Different types of modulation, error correction coding, and other functional blocks are available to the SDR platform
  - ▶ Functional blocks can potentially be changed in real-time
- ▶ Operating parameters of functional blocks can be adjusted either by human operator or automated process

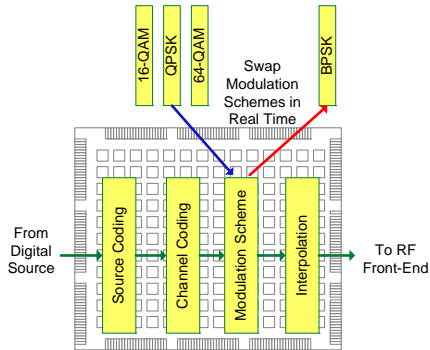
# SDR Key Features<sup>1</sup>

- ▶ **Multifunctionality** – Possessing the ability to support multiple types of radio functions using the same digital communication system platform
- ▶ **Global Mobility** – Transparent operation with different communication networks located in different parts of the world, i.e., not confined to just one standard
- ▶ **Compactness and Power Efficiency** – Many communication standards can be supported with just one SDR platform
- ▶ **Ease of Manufacturing** – Baseband functions a software problem, not a hardware problem
- ▶ **Ease of Upgrading** – Firmware updates can be performed on SDR platform to enable functionality with latest communication standards

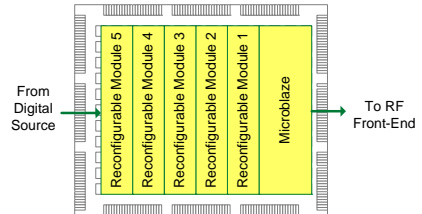
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<sup>1</sup>From *Software Radio: A Modern Approach to Radio Engineering* by Jeffrey H. Reed (Prentice Hall, 2002).

# Example of Multifunctionality



**Figure :** Swapping Different Modulation Schemes on the Same FPGA.



**Figure :** Digital Communication Transmitter Chain on FPGA using *Multiprocessor System-on-Chip (MPSoC)* Concept.

# Digital Communication Transceiver – Revisted

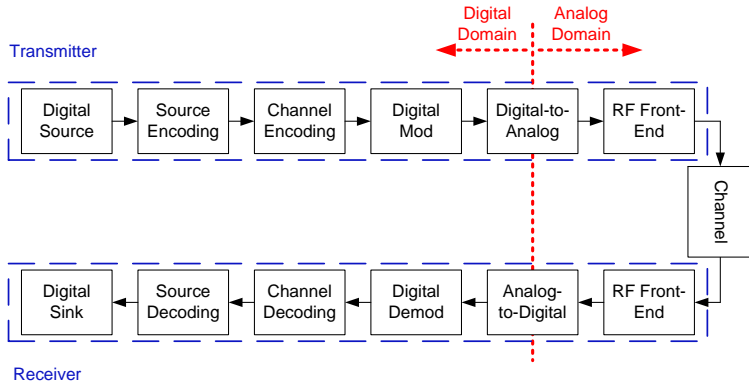


Figure : Generic representation of a digital communication transceiver.

# Software Component

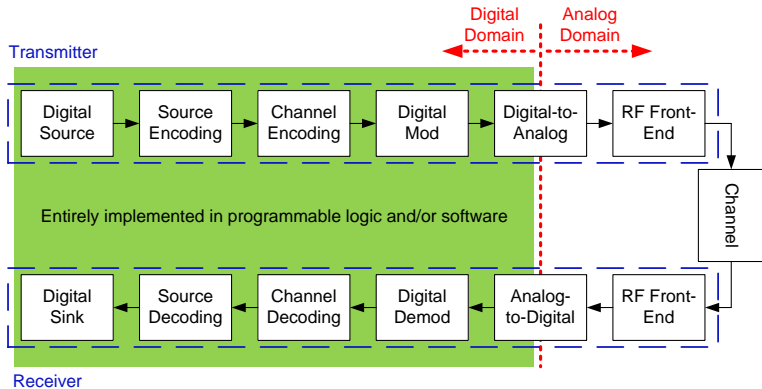


Figure : Generic representation of a digital communication transceiver.



# Hardware Component

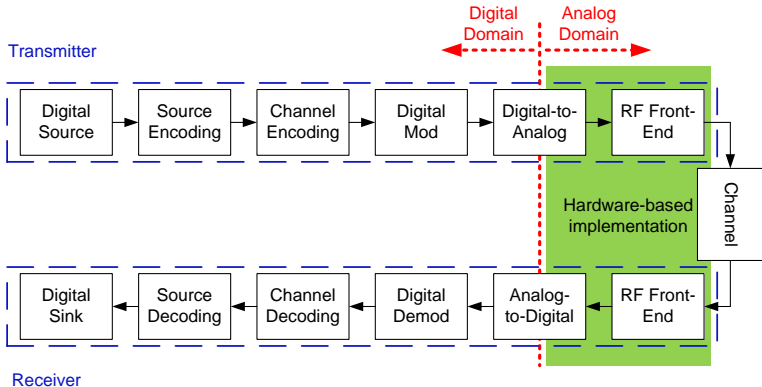


Figure : Generic representation of a digital communication transceiver.

# History of SDR Development

- ▶ “Software-defined radio” first coined by Joseph Mitola in 1991 although SDR technology was available since the 1970s
- ▶ First publicly funded SDR development initiative was *SpeakEasy I/II* by the U.S. military
  - ▶ Employed programmable microprocessors for implementing more than ten military communication standards
  - ▶ Transmission carrier frequencies ranged from 2 MHz to 2 GHz
  - ▶ Allowed for upgrades of new functional blocks, such as modulation schemes and coding schemes
  - ▶ Initially used Texas Instruments TMS320C40 processor (40 MHz)
  - ▶ SpeakEasy II was the first SDR platform to involve FPGA modules for implementing digital baseband functionality
  - ▶ Physical size of prototype fit in the back of a truck
  - ▶ Read “SPEAKeasy, the Military Software Radio” by Upmal and Lackey in *IEEE Communications Magazine* (IEEE Press, 1995)

# List of Currently Available SDR Platforms

- ▶ **Joint Tactical Radio System** – Next-generation voice-and-data radio used by the U.S. military and employs *software communications architecture* (SCA)
- ▶ **Berkeley BEE2** – BEE2 is targeted as a powerful reconfigurable computing engine with five Xilinx Virtex-II Pro FPGAs on the emulation board
- ▶ **Rice University WARP** – WARP radios include a Xilinx Virtex-II Pro FPGA board as well as a MAX2829 transceiver
- ▶ **Kansas University Agile Radio** – KUAR is a small form factor SDR platform containing a Xilinx Virtex-II Pro FPGA board and a PCI Express 1.4 GHz Pentium-M microprocessor
- ▶ **Lyrtech Small Form Factor SDR** – Industry collaboration between Texas Instruments and Xilinx
- ▶ **Universal Software Radio Peripheral 1/2** – Inexpensive, open source, modular, flexible SDR platform

# The USRP Concept

- ▶ Relatively inexpensive hardware for enabling SDR design and development
- ▶ All baseband processing conducted on computer workstation “host”
  - ▶ USRP platform acts as a radio peripheral allowing for over-the-air transmissions
  - ▶ `libusrp` defines interface between USRP platform and host computer workstation
- ▶ USRP design is open source → allows for user customization
- ▶ Platform design is modular in terms of supported RF front-ends, referred to as *daughtercards*
- ▶ Two types of USRP platforms: **USRP1** and **USRP2**

# Universal Software Radio Peripheral 1

- ▶ Designed and manufactured by Ettus Research LLC for a variety of different communities interested in an inexpensive SDR platform

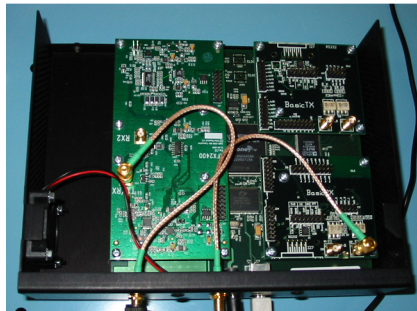


Figure : USRP1 motherboard.

# USRP1 Features

- ▶ USB interface between host computer workstation and USRP1 platform → data bottleneck
- ▶ Supports up to two RF transceiver daughtercards
- ▶ Possesses an Altera Cyclone EP1C12Q240C8 FPGA for performing sampling and filtering
- ▶ Contains four high-speed analog-to-digital converters, each capable of 64 MS/s at a resolution of 12 bit, with 85dB SFDR (AD9862)
- ▶ Contains four high-speed digital-to-analog converters, each capable of 128 MS/s at a resolution of 14 bit, with 83dB SFDR (AD9862)

# Universal Software Radio Peripheral 2

- Officially released in September 2008, the USRP2 platform provides a more capable SDR device for enabling digital communication system design and implementation

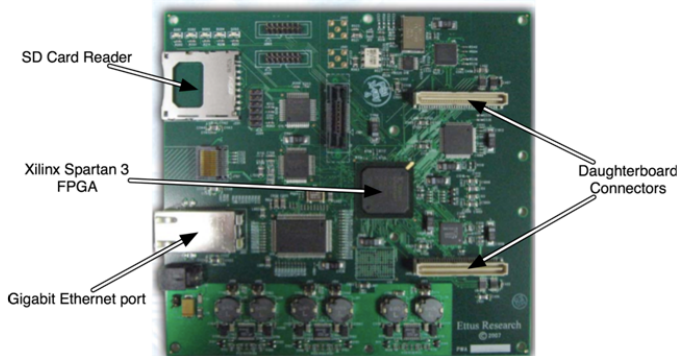


Figure : USRP2 motherboard.

# USRP2 Features

- ▶ Gigabit Ethernet interface between host computer workstation and USRP2 platform
- ▶ Supports only one RF transceiver daughtercard
- ▶ Possesses a Xilinx Spartan 3-2000 FPGA for performing sampling and filtering
- ▶ Contains two 100 MS/s, 14 bit, analog-to-digital converters (LTC2284), with a 72.4dB SNR and 85dB SFDR for signals at the Nyquist frequency
- ▶ Contains two 400 MS/s, 16 bit, digital-to-analog converters (AD9777), with a 160 MSPS without interpolation, and up to 400 MSPS with 8x interpolation
- ▶ MIMO-capable for supporting the processing of digital communication system designs employing multiple antennas



# RF Daughtercards

- ▶ RF front-ends are very difficult to design and are usually limited to a narrow range of transmission carrier frequencies
  - ▶ Properties of the RF circuit and components changes across different frequencies
  - ▶ RF filters constrained in sweep frequency range
- ▶ To support a wide range of transmission carrier frequencies, both USRP1 and USRP2 platforms can use an assortment of modular RF daughtercards
  - ▶ BasicTX, 1-250 MHz Transmitter, for use with external RF hardware
  - ▶ BasicRX, 1-250 MHz Receiver, for use with external RF hardware
  - ▶ RFX900, 800-1000 MHz Transceiver, 200+mW output
  - ▶ RFX2400, 2.3-2.9 GHz Transceiver, 20+mW output
  - ▶ XCVR2450, Dual-band Transceiver, 100+mW output at 2.4-2.5 GHz and 50+mW output 4.9-5.85 GHz

# Software Environment for USRP 1/2 Platforms

- ▶ **GNU Radio** – Open source software consisting of C/C++ libraries wrapped with Python scripts used to define various digital communication modules
- ▶ **GNU Radio Companion** – A graphical user interface for GNU Radio that enables the end user to design digital communication baseband implementations
- ▶ **OSSIE** – Another graphical user interface devised by researchers at Virginia Tech
- ▶ **WPI/MathWorks Simulink Interface** – Simulink blocks that streamed data between the USRP2 platform and the Simulink environment