

# Digital Communication Systems Engineering with Software-Defined Radio

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## Lecture 04

# Signal Types

- ▶ Analog signal: continuous in time and amplitude
  - ▶ Voltage, current, temperature
- ▶ Digital signal: discrete both in time and amplitude
  - ▶ Attendance of this class, digitized analog signals
- ▶ Discrete-time signal: discrete in time and continuous in amplitude
  - ▶ Hourly change of temperature in Worcester

# Sampling Theory

- ▶ Sampling is a continuous to discrete-time conversion
- ▶ Most common sampling is periodic
  - ▶  $x[n] = x_c(nT) \quad -\infty < n < \infty$
  - ▶  $T$  is the sampling period in second
  - ▶  $f_s = 1/T$  is the sampling frequency in Hz
  - ▶ Sampling frequency in radian-per-second  $\Omega = 2\pi f_s \text{rad/sec}$
  - ▶ Use  $[\cdot]$  for discrete-time and  $(\cdot)$  for continuous-time signals
- ▶ This is the ideal case, not the practical, but close enough
  - ▶ In practice, it is implemented with an analog-to-digital converter
  - ▶ We get digital signals that are quantized in amplitude and time

# Sampling Theory

- ▶ In general, sampling is not reversible
- ▶ Given a sampled signal, one can fit infinite continuous signals through the samples
- ▶ Fundamental issue in digital signal sampling
  - ▶ If we lose information during sampling, we cannot recover it
  - ▶ Under certain conditions, an analog signal can be sampled without loss so that it can be reconstructed perfectly

# Representation of Sampling

- ▶ Mathematically convenient to represent in two stages
  - ▶ Impulse train modulator
  - ▶ Conversion of impulse train to a sequence

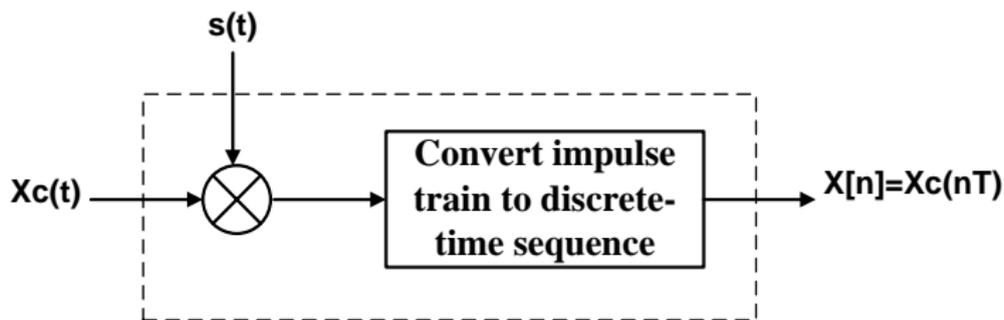


Figure : Conversion of Samples to Analog Waveforms.

# Continuous-Time Fourier Transform

- ▶ Continuous-Time Fourier transform pair is defined as
  - ▶  $X_c(j\Omega) = \int_{-\infty}^{\infty} x_c(t) e^{-j\Omega t} dt$
  - ▶  $x_c(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X_c(j\Omega) e^{j\Omega t} d\Omega$
- ▶ We write  $x_c(t)$  as a weighted sum of complex exponentials
- ▶ Remember some Fourier Transform properties
  - ▶  $x(t) * y(t) \leftrightarrow X(j\Omega) Y(j\Omega)$
  - ▶  $x(t)y(t) \leftrightarrow X(j\Omega) * Y(j\Omega)$
  - ▶  $x(t)e^{j\Omega_0 t} \leftrightarrow X(j(\Omega - \Omega_0))$

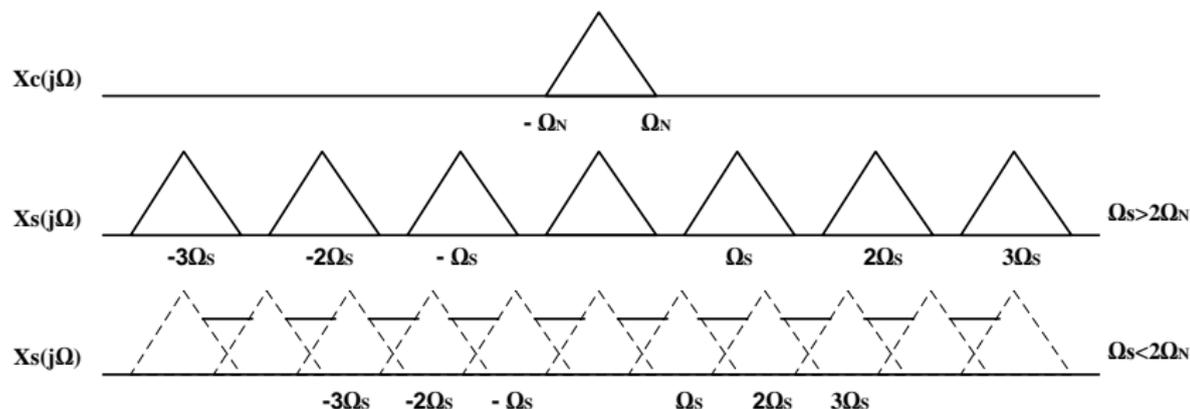
# Frequency Domain Representation of Sampling

- ▶ Modulate (multiply) continuous-time signal with pulse train:
  - ▶  $x_s(t) = x_c(t)s(t) = \sum_{n=-\infty}^{\infty} x_c(t)\delta(t - nT)$   
 $s(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT)$
- ▶ Let's take the Fourier Transform of  $x_s(t)$  and  $s(t)$ 
  - ▶  $X_s(j\Omega) = \frac{1}{2\pi} X_c(j\Omega) * S(j\Omega)$   
 $S(j\Omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\Omega - k\Omega_s)$
- ▶ Fourier transform of pulse train is again a pulse train
- ▶ Note that multiplication in time is convolution in frequency
- ▶ We represent frequency with  $\Omega = 2\pi f$ , hence  $\Omega_s = 2\pi f_s$ 
  - ▶  $X_s(j\Omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(j(\Omega - k\Omega_s))$

# Frequency Domain Representation of Sampling

- ▶ Convolution with pulse creates replicas at pulse location:
  - ▶  $X_s(j\Omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(j(\Omega - k\Omega_s))$
- ▶ This tells us that the impulse train modulator
  - ▶ Creates images of the Fourier transform of the input signal
  - ▶ Images are periodic with sampling frequency
  - ▶ If  $\Omega_s < \Omega_N$ , sampling maybe irreversible due to aliasing of images

# Frequency Domain Representation of Sampling



**Figure :** Signal Spectra (Top: Original, Middle: Sampled Without Aliasing, Bottom: Sampled With Aliasing).

# Nyquist Sampling Theorem

- ▶ Let  $x_c(t)$  be a bandlimited signal with
  - ▶  $X_s(j\Omega) = 0$  for  $|\Omega| \geq \Omega_N$
- ▶ Then  $x_c(t)$  is uniquely determined by its samples  $x[n] = x_c(nT)$  if  $\Omega_s = \frac{2\pi}{T} = 2\pi f_s \geq 2\Omega_N$ 
  - ▶  $\Omega_N$  is generally known as the Nyquist Frequency
- ▶ The minimum sampling rate that must be exceeded is known as the Nyquist Rate

## USRP receive and transmit paths

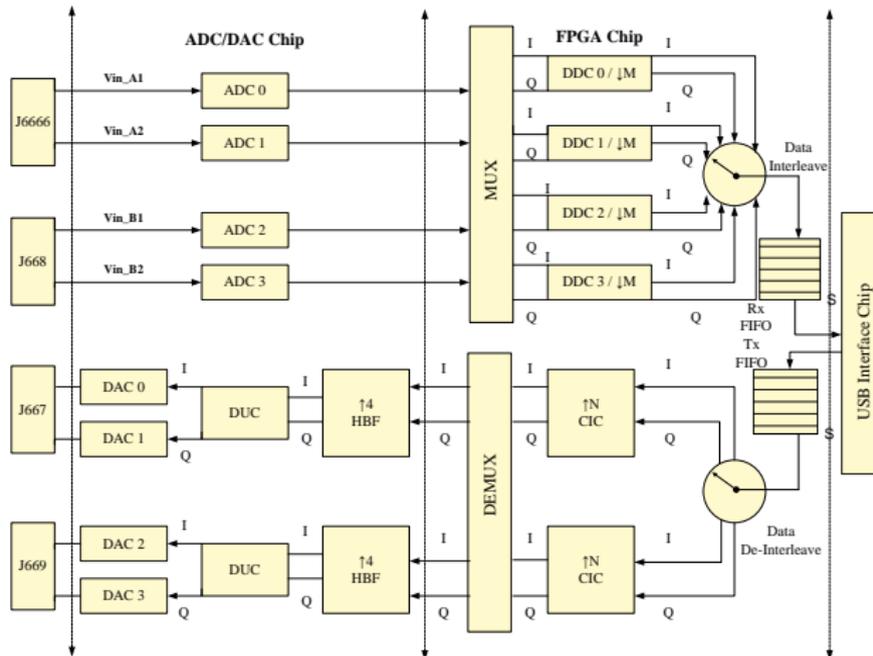


Figure : Schematic of Sampling on USRP2 Platform.

# USRP Receive Path

- ▶ Main components on Rx path
  - ▶ Four analog-to-digital converter (ADC)
  - ▶ Four digital down converter (DDC)
- ▶ Signal processing on Rx path
  - ▶ IF band  $\rightarrow$  ADC  $\rightarrow$  DDC  $\rightarrow$  USRP board  $\rightarrow$  Baseband I/Q

## DDC on Receive Path

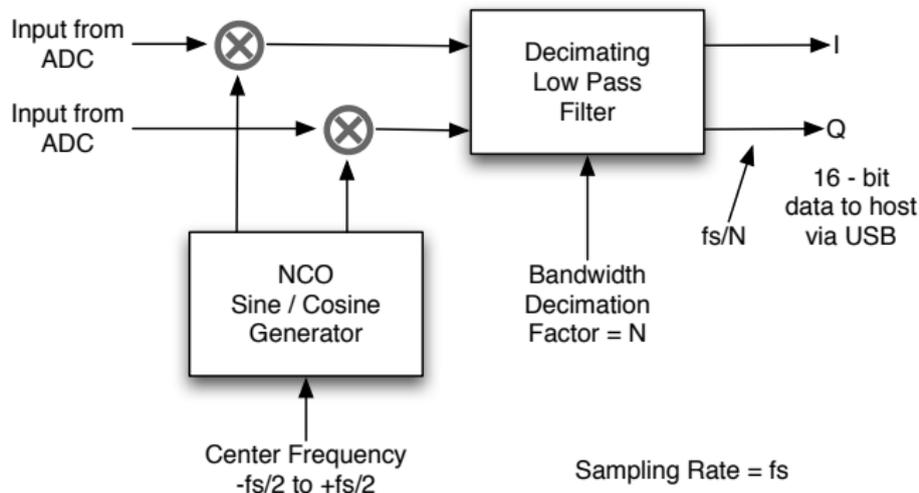


Figure : Schematic of Digital Down Conversion on USRP2 Platform.

## Scenario 1: Four Users

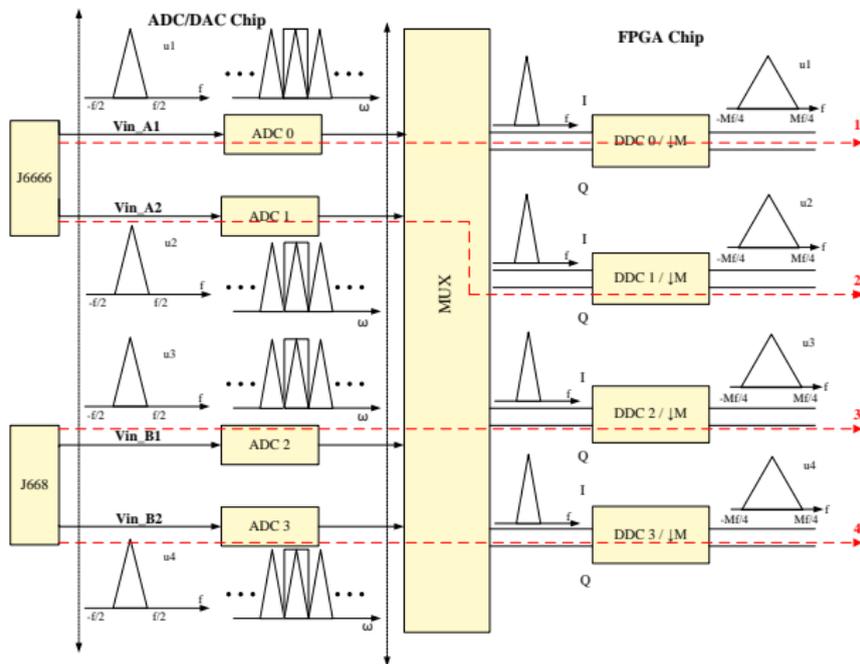


Figure : USRP2 Receiver Configuration for Sampling with Four Users.

## Scenario 2: Two Users

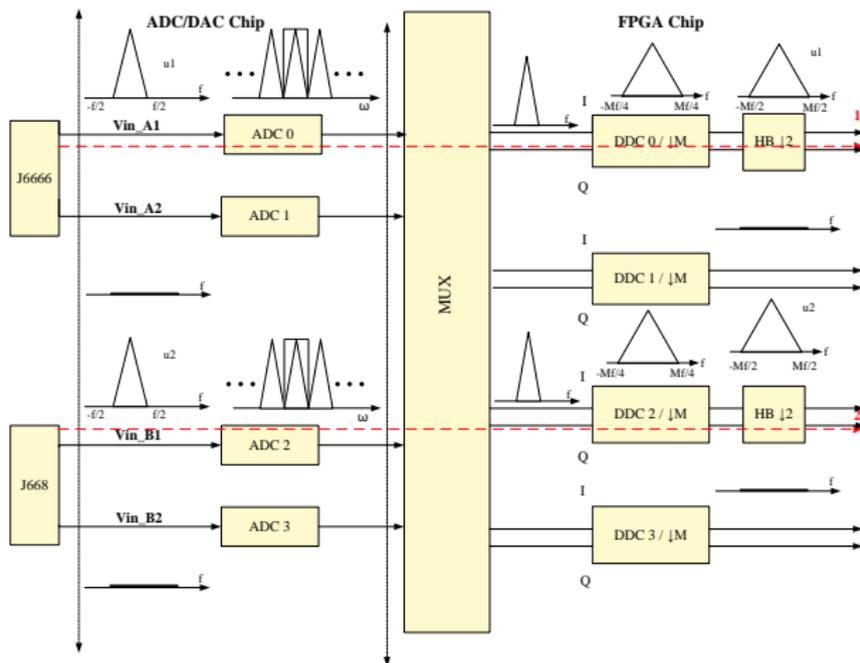


Figure : USRP2 Receiver Configuration for Sampling with Two Users.

# USRP Transmit Path

- ▶ Main components on Tx path
  - ▶ Four digital-to-analog converter (DAC)
  - ▶ Four digital up converter (DUC)
- ▶ Signal processing on Tx path
  - ▶ Reverse to Rx path
  - ▶ Baseband I/Q → USRP board → DUC → DAC → IF band