

# Digital Communication Systems Engineering with Software-Defined Radio

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## Lecture 20

# How Does Energy Detection Work?

- ▶ Energy detection uses the energy spectra of the received signal in order to identify the frequency locations of the transmitted signal
- ▶ Several steps are involved in producing the frequency representation of the intercepted signal
  - ▶ *Pre-filtering* of intercepted signal extracts frequency band of interest
  - ▶ *Analog-to-digital conversion* (ADC) converts filtered intercepted signal into discrete time samples
  - ▶ *Fast Fourier transform* (FFT) provides the frequency representation of the signal
  - ▶ *Square-law device* yields the square of the magnitude of the frequency response from the FFT output

# Detector Implementation



**Figure :** Schematic of an Energy Detector Implementation Employing Pre-Filtering and a Square-Law Device.

# Detection Threshold

- ▶ Energy detection involves the *application* of a threshold in the frequency domain
  - ▶ Threshold is used to decide whether a transmission is present a specific frequency
- ▶ Any portion of the frequency band where the energy exceeds the threshold is considered to be occupied by a transmission
  - ▶ Binary decision making process
  - ▶ Two hypotheses:  $\mathcal{H}_0$  (idle) or  $\mathcal{H}_1$  (occupied)
- ▶ One of the major concerns of energy detection is the selection of an appropriate threshold
  - ▶ A threshold that may work for one transmission may not be sufficient for another
    - ▶ Transmitters employing different signal power levels
    - ▶ Transmission ranges may vary

# An Example

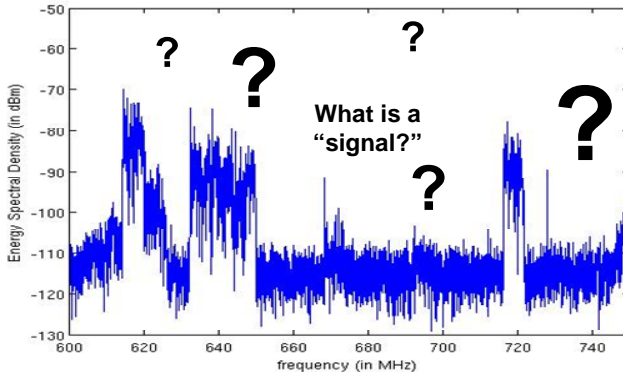


Figure : Spectrum Measurements from Springfield, MA during June 2009.

# Applying the Detection Threshold

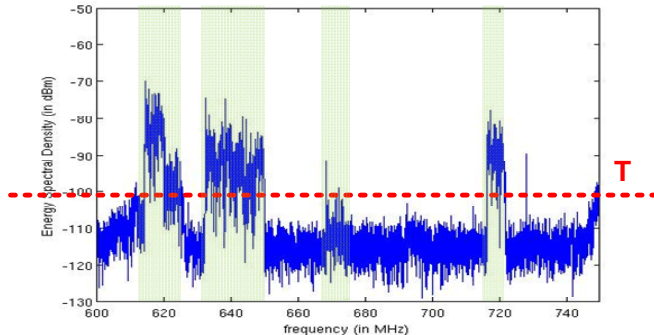


Figure : Energy Detection Threshold used to Identify Occupied Spectrum.

# “False-Alarm” Scenario

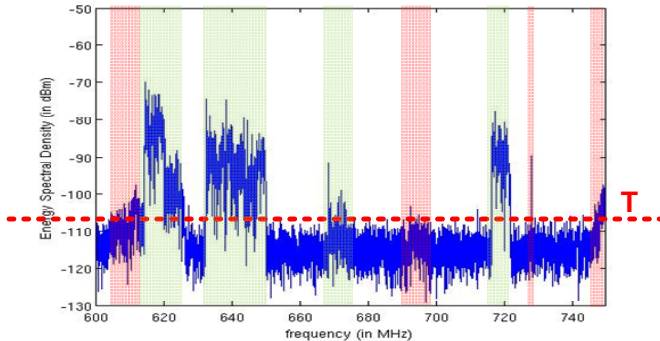


Figure : Energy Detection Threshold Level Yielding False Alarms.

# “Missed Detection” Scenario

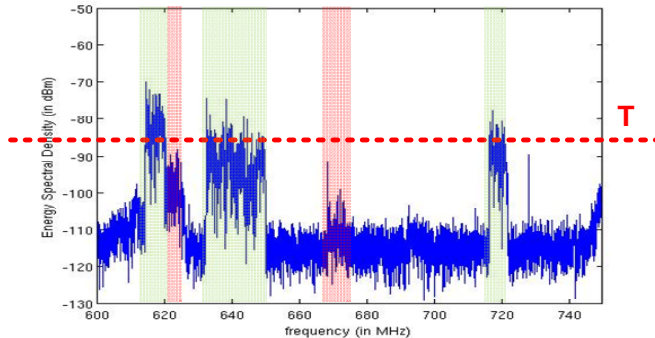


Figure : Energy Detection Threshold Level Yielding Missed Detection.

# Hypothesis Testing Revisited

- ▶ Spectrum sensing involves distinguishing between two mutually independent and identically distributed Gaussian sequences:

$$\mathcal{H}_0 : y(k) = w(k) \rightarrow \text{Idle}$$

$$\mathcal{H}_1 : y(k) = s(k) + w(k) \rightarrow \text{Occupied}$$

where  $w(k)$ ,  $k = 1, \dots, n$ , is the noise signal sample, and  $s(k)$ ,  $k = 1, \dots, n$ , is a transmitted signal sample

- ▶ Both  $w(k)$  and  $s(k)$  are zero-mean complex Gaussian random variables with variances  $\sigma_w^2$  and  $\sigma_s^2$  per dimension
- ▶ Let us define the vector of the  $n$  observed samples:

$$\mathbf{y} = [y(1), \dots, y(n)]'$$

# Log-Likelihood Ratio

- ▶ Suppose we define the variances  $\sigma_0^2 = \sigma_w^2$  and  $\sigma_1^2 = \sigma_s^2 + \sigma_w^2$
- ▶ Neymann-Pearson detector is a threshold detector on either the likelihood ratio or the log-likelihood ratio (LLR):

$$\text{LLR} = \log \left( \frac{p(\mathbf{y}|\mathcal{H}_1)}{p(\mathbf{y}|\mathcal{H}_0)} \right) > \tau' \quad (1)$$

where  $\tau'$  is a suitably chosen threshold

- ▶ The detector is equivalent to deciding  $\mathcal{H}_1$  given the independent and identical assumption if:

$$z = \frac{1}{2n\sigma_0^2} \sum_{k=1}^n |y(k)|^2 > \tau \quad (2)$$

where  $z$  is a statistic possessing a scaled version of a standard  $\chi^2$  distribution with  $2n$  degrees of freedom

# Computing Tail Probability

- ▶ Given that  $x_i$  are independent real Gaussian variables with zero means and unit variances, we get  $x = \sum_{i=1}^{2n} x_i^2$  where  $x$  is  $\chi^2$  distributed with  $2n$  degrees of freedom
- ▶ The  $\chi^2$  PDF with  $2n$  degrees of freedom is:

$$p(x) = \frac{1}{2^n(n-1)!} x^{n-1} e^{-x/2} \quad (3)$$

- ▶ Using integration by parts, we compute  $P(x > \tau)$  :

$$\begin{aligned} P(x > \tau) &= \int_{\tau}^{\infty} \frac{1}{2^n(n-1)!} x^{n-1} e^{-x/2} dx \\ &= e^{-\tau/2} \sum_{k=0}^{n-1} \frac{1}{k!} \left(\frac{\tau}{2}\right)^k = \Gamma_u\left(\frac{\tau}{2}, n\right) \end{aligned}$$

# Computing $P_{FA}$ and $P_{MD}$

- ▶ What is  $\Gamma_u()$ ?
  - ▶ The *upper incomplete gamma function* defined as:

$$\Gamma_u(a, n) = \frac{1}{\Gamma(n)} \int_a^{\infty} x^{n-1} e^{-x} dx$$

- ▶ Consequently, the test statistic  $z \times 2n$  has the same PDF as a  $\chi^2$  variable with  $2n$  degrees of freedom
- ▶ The probability of false alarm ( $P_{FA}$ ) and probability of missed detection ( $P_{MD}$ ) are equal to:

$$\epsilon = P_{FA} = \Gamma_u(n\tau, n)$$

$$\delta = P_{MD} = 1 - \Gamma_u\left(\frac{n\tau}{1 + \sigma_s^2/\sigma_w^2}, n\right)$$