

Digital Communication Systems Engineering with Software-Defined Radio

Di Pu, Alexander M. Wyglinski
Worcester Polytechnic Institute

Lecture 04

Signal Types

- ▶ Analog signal: continuous in time and amplitude
 - ▶ Voltage, current, temperature
- ▶ Digital signal: discrete both in time and amplitude
 - ▶ Attendance of this class, digitized analog signals
- ▶ Discrete-time signal: discrete in time and continuous in amplitude
 - ▶ Hourly change of temperature in Worcester

Sampling Theory

- ▶ Sampling is a continuous to discrete-time conversion
- ▶ Most common sampling is periodic
 - ▶ $x[n] = x_c(nT) \quad -\infty < n < \infty$
 - ▶ T is the sampling period in second
 - ▶ $f_s = 1/T$ is the sampling frequency in Hz
 - ▶ Sampling frequency in radian-per-second $\Omega = 2\pi f_s \text{ rad/sec}$
 - ▶ Use $[\cdot]$ for discrete-time and (\cdot) for continuous-time signals
- ▶ This is the ideal case, not the practical, but close enough
 - ▶ In practice, it is implemented with an analog-to-digital converter
 - ▶ We get digital signals that are quantized in amplitude and time

Sampling Theory

- ▶ In general, sampling is not reversible
- ▶ Given a sampled signal, one can fit infinite continuous signals through the samples
- ▶ Fundamental issue in digital signal sampling
 - ▶ If we lose information during sampling, we cannot recover it
 - ▶ Under certain conditions, an analog signal can be sampled without loss so that it can be reconstructed perfectly

Representation of Sampling

- ▶ Mathematically convenient to represent in two stages
 - ▶ Impulse train modulator
 - ▶ Conversion of impulse train to a sequence

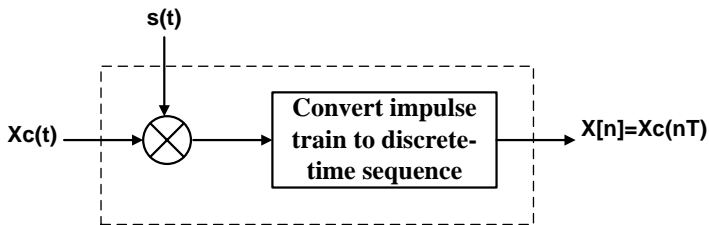


Figure : Conversion of Samples to Analog Waveforms.

Continuous-Time Fourier Transform

- ▶ Continuous-Time Fourier transform pair is defined as
 - ▶ $X_c(j\Omega) = \int_{-\infty}^{\infty} x_c(t) e^{-j\Omega t} dt$
 - ▶ $x_c(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X_c(j\Omega) e^{j\Omega t} d\Omega$
- ▶ We write $x_c(t)$ as a weighted sum of complex exponentials
- ▶ Remember some Fourier Transform properties
 - ▶ $x(t) * y(t) \leftrightarrow X(j\Omega) Y(j\Omega)$
 - ▶ $x(t)y(t) \leftrightarrow X(j\Omega) * Y(j\Omega)$
 - ▶ $x(t)e^{j\Omega_0 t} \leftrightarrow X(j(\Omega - \Omega_0))$

Frequency Domain Representation of Sampling

- ▶ Modulate (multiply) continuous-time signal with pulse train:

- ▶ $x_s(t) = x_c(t)s(t) = \sum_{n=-\infty}^{\infty} x_c(t)\delta(t - nT)$
 $s(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT)$

- ▶ Let's take the Fourier Transform of $x_s(t)$ and $s(t)$

- ▶ $X_s(j\Omega) = \frac{1}{2\pi} X_c(j\Omega) * S(j\Omega)$
 $S(j\Omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\Omega - k\Omega_s)$

- ▶ Fourier transform of pulse train is again a pulse train
- ▶ Note that multiplication in time is convolution in frequency
- ▶ We represent frequency with $\Omega = 2\pi f$, hence $\Omega_s = 2\pi f_s$
 - ▶ $X_s(j\Omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(j(\Omega - k\Omega_s))$

Frequency Domain Representation of Sampling

- ▶ Convolution with pulse creates replicas at pulse location:
 - ▶ $X_s(j\Omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(j(\Omega - k\Omega_s))$
- ▶ This tells us that the impulse train modulator
 - ▶ Creates images of the Fourier transform of the input signal
 - ▶ Images are periodic with sampling frequency
 - ▶ If $\Omega_s < \Omega_N$, sampling maybe irreversible due to aliasing of images

Frequency Domain Representation of Sampling

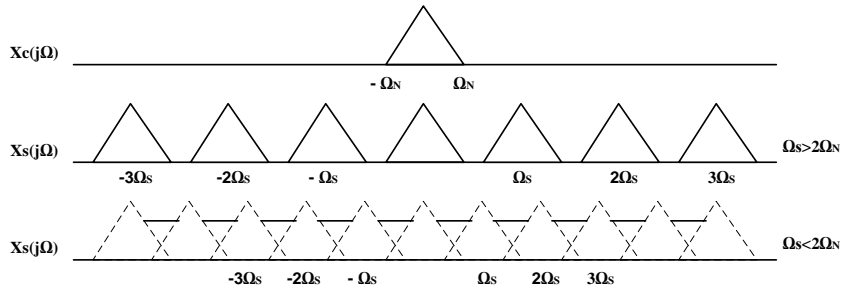


Figure : Signal Spectra (Top: Original, Middle: Sampled Without Aliasing, Bottom: Sampled With Aliasing).

Nyquist Sampling Theorem

- ▶ Let $x_c(t)$ be a bandlimited signal with
 - ▶ $X_s(j\Omega) = 0$ for $|\Omega| \geq \Omega_N$
- ▶ Then $x_c(t)$ is uniquely determined by its samples $x[n] = x_c(nT)$ if $\Omega_s = \frac{2\pi}{T} = 2\pi f_s \geq 2\Omega_N$
 - ▶ Ω_N is generally known as the Nyquist Frequency
- ▶ The minimum sampling rate that must be exceeded is known as the Nyquist Rate

USRP receive and transmit paths

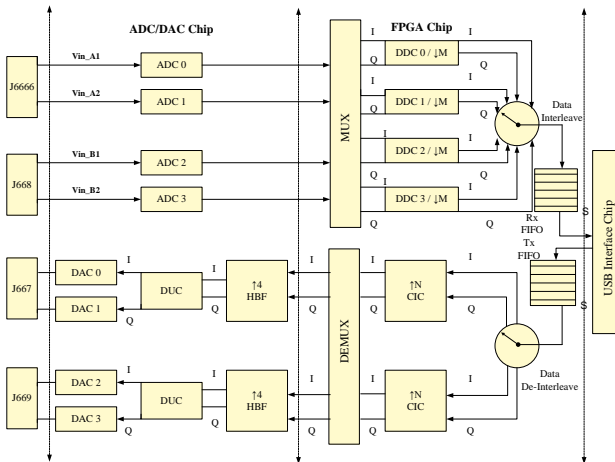


Figure : Schematic of Sampling on USRP2 Platform.

USRP Receive Path

- ▶ Main components on Rx path
 - ▶ Four analog-to-digital converter (ADC)
 - ▶ Four digital down converter (DDC)
- ▶ Signal processing on Rx path
 - ▶ IF band \rightarrow ADC \rightarrow DDC \rightarrow USRP board \rightarrow Baseband I/Q

DDC on Receive Path

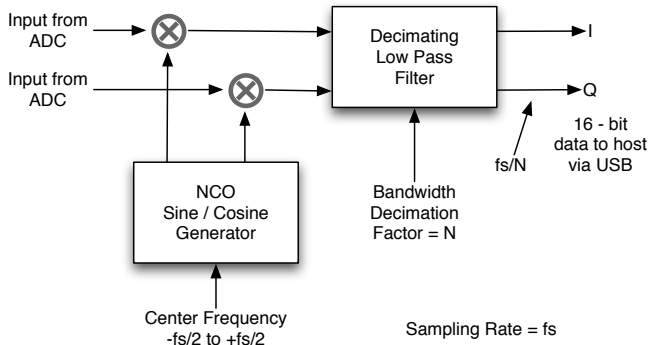


Figure : Schematic of Digital Down Conversion on USRP2 Platform.

Scenario 1: Four Users

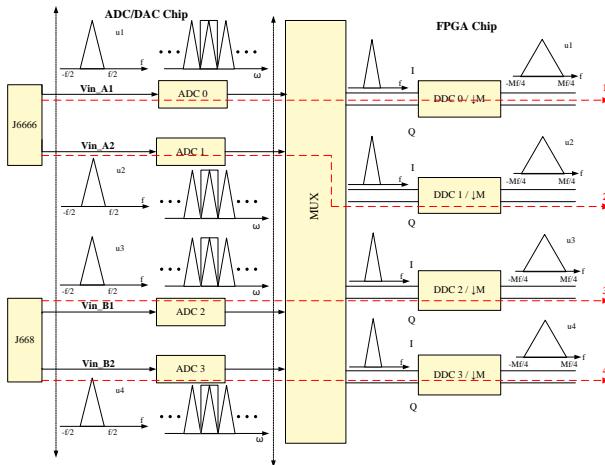


Figure : USRP2 Receiver Configuration for Sampling with Four Users.

Scenario 2: Two Users

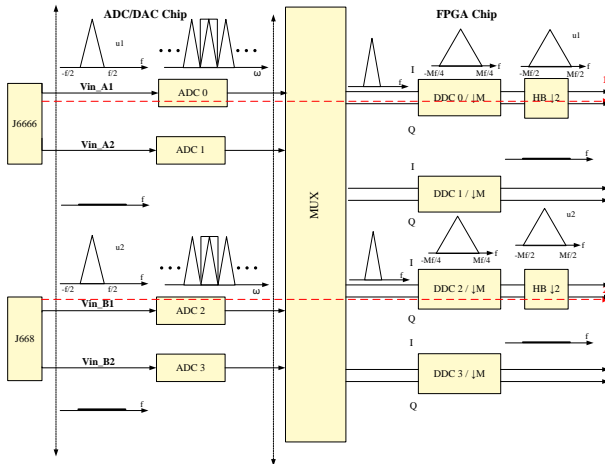


Figure : USRP2 Receiver Configuration for Sampling with Two Users.

USRP Transmit Path

- ▶ Main components on Tx path
 - ▶ Four digital-to-analog converter (DAC)
 - ▶ Four digital up converter (DUC)
- ▶ Signal processing on Tx path
 - ▶ Reverse to Rx path
 - ▶ Baseband I/Q → USRP board → DUC → DAC → IF band