

a.) Use energy balance to find the velocity at B:

$$mgh = \frac{1}{2}mv_b^2$$

$$gh = \frac{1}{2}v_b^2$$

$$v_b = (2gh)^{\frac{1}{2}} \quad (10pts)$$

b.) There are (at least) two analogous ways to find t. The direction of motion is parallel to the length L, such that only a component of the acceleration g acts in the direction of motion. You can confirm this by drawing a free body diagram with the x-axis aligned along L, and the y-axis aligned in the direction of the normal force, N, revealing that the net acceleration comes from the component of gravity in the +L direction.

Solution 1:

$$l = \frac{(v_f - v_i)}{2} * t$$

$$l = \frac{v_f}{2} * t$$

$$t = \frac{2l}{v_f} = \frac{2l}{(2gh)^{\frac{1}{2}}} \quad (5pts)$$

Solution 2:

$$a = g \frac{h}{l}$$

$$l = l_0 + v_0 t + \frac{1}{2}at^2$$

$$l = \frac{1}{2} \left(\frac{gh}{l} \right) t^2$$

$$t = \left(\frac{2l^2}{gh} \right)^{\frac{1}{2}} = \frac{2l}{(2gh)^{\frac{1}{2}}} \quad (5pts)$$

c.) First, find the velocity at c. Because the tube is oriented vertically, there is additional gravitational potential energy that we must consider:

$$\frac{1}{2}mgh + \frac{1}{2}mgp = \frac{1}{2}mv_c^2$$

$$v_c = (gh + gp)^{\frac{1}{2}}$$

$$a_n = \frac{v_c^2}{p}$$

$$a_t = g$$

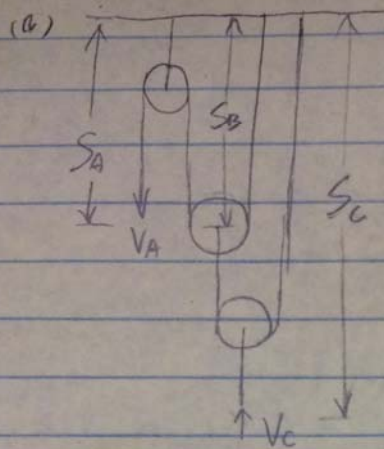
$$a_{\text{magnitude}} = (a_n^2 + a_t^2)^{\frac{1}{2}}$$

$$a_{\text{magnitude}} = \left(\left(g \frac{h}{p} + g \right)^2 + g^2 \right)^{\frac{1}{2}}$$

$$a_{\text{direction}} = \tan^{-1} \left(\frac{a_t}{a_n} \right)$$

$$a_{\text{direction}} = \tan^{-1} \left(\frac{g}{g \frac{h}{p} + g} \right) = \tan^{-1} \left(\frac{1}{1 + \frac{h}{p}} \right)$$

Solution:

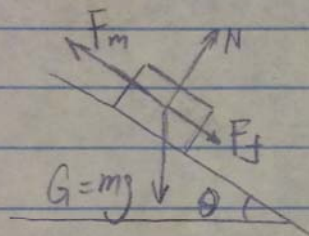


$$\begin{cases} S_A + 2S_B = l_1 \\ S_C + (S_C - S_B) = l_2 \end{cases}$$

$$\therefore \begin{cases} V_A + 2V_B = 0 \\ 2V_C - V_B = 0 \end{cases}$$

$$\Rightarrow |V_C| = \frac{1}{4} |V_A|$$

$$F_m = 4F$$



$$\begin{cases} F_f = N \cdot \mu_0 \\ N = mg \cdot \cos \theta \\ F_m = 4F \end{cases}$$

$$\Sigma F_x = m \cdot a_x$$

$$F_m - F_f - mg \cdot \sin \theta = m a_x$$

$$a_x = \frac{1}{m} (4F - mg \cos \theta \cdot \mu_0 - mg \sin \theta)$$

$$a ds = v dv$$

$$\int_0^l a ds = \int_0^v v dv$$

$$al = \frac{1}{2} \cdot v^2$$

$$v = \sqrt{2al}$$

$$= \sqrt{\frac{2l}{m} (4F - mg \cos \theta \mu_0 - mg \sin \theta)}$$

(b).

$$\begin{aligned}\Sigma U_{1-2} &= W_F - W_{F_f} - W_G \\ &= 4F \cdot L - mg \cos \theta \cdot \mu_0 \cdot L - mg \sin \theta \cdot L\end{aligned}$$

$$\Sigma U_{1-2} = \frac{1}{2} \cdot m \cdot V_2^2 - \frac{1}{2} \cdot m \cdot V_1^2$$

$$4FL - mg \cos \theta \cdot \mu_0 L - mg \sin \theta \cdot L = \frac{1}{2} \cdot m \cdot V^2$$

$$V = \sqrt{\frac{2L}{m} (4F - mg \cos \theta \mu_0 - mg \sin \theta)}$$

(c). $P = F_x \cdot V$

$$= (F_m - F_f - mg \sin \theta) \cdot V$$

$$= (4F - mg \cos \theta \cdot \mu_0 - mg \sin \theta) \cdot \sqrt{\frac{2L}{m} (4F - mg \cos \theta \mu_0 - mg \sin \theta)}$$

(d). $\epsilon = \frac{\text{power out}}{\text{power input}}$

$$\text{power output} = \frac{1}{2} \cdot m \cdot V^2$$

$$= \frac{1}{2} \cdot m \cdot \frac{2L}{m} (4F - mg \cos \theta \mu_0 - mg \sin \theta)$$

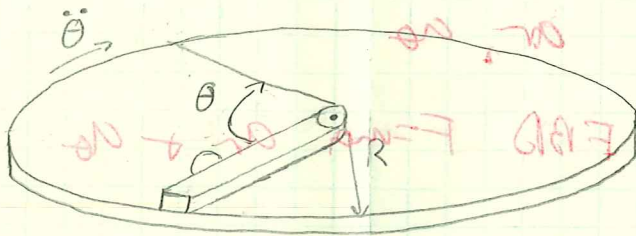
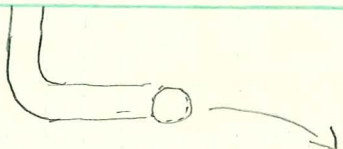
$$= L \cdot (4F - mg \cos \theta \mu_0 - mg \sin \theta)$$

$$\text{power input} = F_m \cdot L$$

$$= 4F \cdot L$$

$$\epsilon = \frac{L (4F - mg \cos \theta \mu_0 - mg \sin \theta)}{4FL}$$

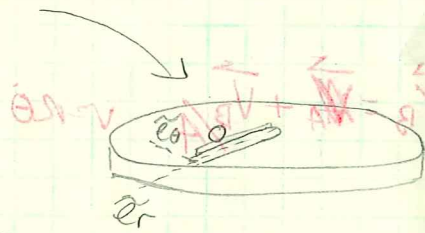
$$= 1 - \frac{mg (\cos \theta \mu_0 + \sin \theta)}{4F}$$



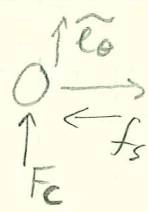
$$\frac{8}{10} = \frac{x}{15}$$

$$\frac{8 \cdot 15}{10} = \frac{8 \cdot 3}{2} = 12$$

AMPAD



FBD



(F_c is force from Arm C.)

$$\ddot{\theta} = \text{const.}$$

$$\Sigma F_r = m a_r$$

$$-f_s = m(\ddot{r} - R\dot{\theta}^2)$$

$$-m_s F_c = m(-R\dot{\theta}^2)$$

$$F_c = \frac{m R \dot{\theta}^2}{m_s}$$

$$\Sigma F_\theta = m a_\theta$$

$$F_c = m(R\ddot{\theta} + 2\dot{R}\dot{\theta})$$

$$\frac{m R \dot{\theta}^2}{m_s} = m(R\ddot{\theta} + 2\dot{R}\dot{\theta})$$

$$\frac{\dot{\theta}^2}{m_s} = \ddot{\theta}$$

$$\dot{\theta} = \sqrt{m_s \ddot{\theta}}$$

Kinematic Relations

$$v^2 = \dot{r}^2 + 2ac(s-s_0)\dot{\theta}^2$$

$$(R\dot{\theta})^2 = 2(R\ddot{\theta})(R\theta)$$

$$R^2\dot{\theta}^2 = 2R^2\ddot{\theta}\theta$$

$$m_s\ddot{\theta} = 2\ddot{\theta}\theta$$

$$\theta = \frac{m_s}{2}$$

$$\ddot{\theta} = \frac{d\dot{\theta}}{dt}$$

$$\int \ddot{\theta} dt = \int d\dot{\theta}$$

$$\dot{\theta} t = \dot{\theta} + C_1$$

$$t = \frac{\dot{\theta}}{\ddot{\theta}} = \frac{\sqrt{m_s \ddot{\theta}}}{\ddot{\theta}}$$

$$t = \sqrt{\frac{m_s}{\ddot{\theta}}}$$

$$t = \sqrt{\frac{m_s}{\ddot{\theta}}}$$

$$\sqrt{m_s \ddot{\theta}} = \dot{\theta} t$$

$$\ddot{\theta} = C_1$$

$$\dot{\theta} = \ddot{\theta} t$$

$$\int C_1 dt = \dot{\theta}$$

$$C_1 t = \dot{\theta}$$

FBD

$w_g \downarrow \quad O \rightleftharpoons F_D$

$$\sum F_x = -F_D = \max$$

$$a_x = \frac{-F_D}{m} = -\frac{kv}{m}$$

$$a_x = \frac{dv}{dt} \quad \int_0^{V_B} dt = \int_{V_A}^{V_B} \frac{dv}{a_x}$$

$$t = -\frac{m}{k} \ln(v) \Big|_{V_A}^{V_B}$$

$$t = -\frac{m}{k} \ln\left(\frac{V_B}{V_A}\right)$$

$$t = -\frac{m}{k} (-1) = \frac{m}{k}$$

$$s_y = s_{oy} + v_{oy}^0 + \frac{1}{2} a_y t^2$$

$$s_o - s_{oy} = -\frac{1}{2} g t^2$$

$$t = \sqrt{\frac{2(s_y - s_{oy})}{-g}} = \sqrt{\frac{2y}{g}}$$



$$-\frac{m}{k} \ln\left(\frac{V_B}{V_A}\right) = \sqrt{\frac{2y}{g}}$$

$$k = -m \sqrt{\frac{g}{2y}} \ln\left(\frac{V_B}{V_A}\right) \quad V_B = e^{-1} V_A$$

$$k = -m \sqrt{\frac{g}{2y}} (-1)$$

$$\boxed{k = m \sqrt{\frac{g}{2y}}}$$