Motion and Time Study

The Goals of Motion Study

- Improvement
- Planning / Scheduling (Cost)
- Safety

Know How Long to Complete Task for

- Scheduling (Sequencing)
- Efficiency (Best Way)
- Safety (Easiest Way)

How Does a Job Incumbent Spend a Day

• Value Added vs. Non-Value Added

The General Strategy of IE to Reduce and Control Cost

- Are people productive <u>ALL</u> of the time ?
- Which parts of job are really necessary ?
- Can the job be done <u>EASIER, SAFER</u> and <u>FASTER</u> ?
- Is there a sense of employee involvement?

Some Techniques of Industrial Engineering

- Measure
 - Time and Motion Study
 - Work Sampling
- Control
 - Work Standards (Best Practices)
 - Accounting Labor Reporting
- Improve
 - Small group activities

Time Study

- Observation
 - Stop Watch
 - Computer / Interactive
- Engineering Labor Standards (Bad Idea)
- Job Order / Labor reporting data

History

- Frederick Taylor (1900's)
 Studied motions of iron workers attempted to "mechanize" motions to maximize efficiency – including proper rest, ergonomics, etc.
- Frank and Lillian Gilbreth used motion picture to study worker motions developed 17 motions called "therbligs" that describe all possible work.

TABLE 7-1

Therblig Name	Symbol	Color Designation	Symbol
Search	S	Black	Ó
Select	SE	Gray, Light	\rightarrow
Grasp	G	Lake Red	\cap
Reach	RE	Olive Green	\sim
Move	м	Green	Ý
Hold	н	Gold Ocher	<u> </u>
Release	RL	Carmine Red	6
Position	Ρ	Blue	9
Pre-position	PP	Sky Blue	8
Inspect	1	Burnt Ocher	0
Assemble	А	Violet, Heavy	#
Disassemble	DA	Violet, Light	#
Use	U	Purple	U
Unavoidable Delay	UD	Yellow Ocher	~
Avoidable Delay	AD	Lemon Yellow	م
Plan	PL	Brown	B
Rest to Overcome Fatigue	R	Orange	ę

TABLE I-REACH-R

Distance		Time	TMU		Han		CASE AND DESCRIPTION
Inches	A	B	Cor	ε	A	B	A Reach to object in fixed loca- tion, or to object in other
% or less	2.0	2.0	2.0	2.0	1.6	1.6	hand or on which other hand
1	2.5	2.5	3.6	2.4	2.3	2.3	rests.
2	4.0	4.0	5.9	3.8	3.5	2.7	10313.
3	5.3	5.3	7.3	5.3	4.5	3.6	B Reach to single object in
4	6.1	6.4	8.4	6.8	4.9	4.3	
5	6.5	7.8	9.4	7.4	5.3	6.0	location which may vary
6	7.0	8.6	10.1	8.0	5.7	5.7	slightly from cycle to cycle.
7	7.4	9.3	10.8	8.7	6.1	6.5	
8	7.9	10.1	11.5	9.3	6.5	7.2	C Reach to object jumbled with
9	8.3	10.8	12.2	9.9	6.9	7.9	other objects in a group so
10	8.7	11.5	12.9	10.5	7.3	8.6	that search and select occur.
12	9.6	12.9	14.2	11.8	8.1	10.1]
14	10.5	14.4	15.6	13.0	8.9	11.5	D Reach to a very small object
16	11.4	15.8	17.0	14.2	9.7	12.9	or where accurate grasp is
18	12.3	17.2	18.4	15.5	10.5	14.4	required.
20	13.1	18.6	19.8	16.7	11.3	15.8	toquirou.
22	14.0	20.1	21.2	18.0	12.1	17.3	E Reach to indefinite location
24	14.9	21.5	22.5	19.2	12.9	18.8	
26	15.8	22.9	23.9	20.4	13.7	20.2	to get hand in position for
28	16.7	24.4	25.3	21.7	14.5	21.7	body balance or next motion
30	17.5	25.8	26.7	22.9	15.3	23.2	or out of way.

TABLE II-MOVE-M

		Time	TMU		Wt.	Allows	ince					
Moved Inches		B	с	Hand In Motion B	Wt. (Ib.) Up to	Fac- tor	Con- stant TMU	CASE AND DESCRIPTION				
% or less	2.0	2.0	2.0	1.7	2.5	0	0					
1	2.5	2.9	3.4	2.3								
Inches A B C In Motion B 2 3.6 2.0 2.0 1.7 1 2.5 2.9 3.4 2.3 2 3.6 4.6 5.2 2.9 3 4.9 5.7 6.7 3.6 4 6.1 6.9 8.0 4.3 5 7.3 8.0 9.2 5.0 6 8.1 8.9 10.3 6.7 7 8.9 9.7 11.1 6.5 8 9.7 10.6 11.8 7.2 9 10.5 11.5 12.7 7.9 10 11.3 12.2 13.5 8.6 12 12.9 13.4 15.2 10.0 14 14.4 14.6 16.9 11.4 16 16.0 15.8 18.7 12.8 18 17.6 17.0 20.4 14.2 20 19.2	7.5	1.06	2.2	A Move object to								
3	4.9 5.7 6.7 3.6			1.5	1.00	6.6	other hand or against					
4	6.1	6.9										
the second s	7.3	8.0	9.2	5.0	12.5	1.11	3.9	stop.				
6	8.1	8.9	10.3	5.7								
7	8.9	9.7	11.1		17.5	1.17	5.6					
								1				
	1				22.5	1.22	7.4	B Move object to				
10	11.3	12.2	13.5									
12	12.9	13.4	15.2	10.0	27.5	1.28	9.1	approximate or in-				
14	14.4	14.6	16.9	5 8.6 2 10.0 9 11.4 27.5 1.28 9.1			definite location.					
16	16.0	15.8	18.7		32.5	1.33	10.8					
18					32.0	1.33	10.8	1				
20	19.2	18.2	22.1	Statement and a statement of the local division of the local divis		1						
22	20.8	19.4	23.8		37.5	1.39	12.5	1				
	22.4							C Move object to ex-				
					42.5	1.44	14.3					
28	25.5	23.1	29.0	21.2				act location.				
30	27.1	24.3	30.7	22.7	47.5	1.50	16.0					

TABLE III-TURN AND APPLY PRESSURE-T AND AP

		TI	me T	MUf	or De	grees	Tur	ber		
30°	45°	60°	75°	90°	105°	120°	135°	150°	165*	180*
8.4	10.5	12.3	14.4	16.2	18.3	20.4	22.2	24.3	26.1	28.2
	2.8 4.4	2.8 3.5 4.4 5.5	30° 45° 60° 2.8 3.5 4.1 4.4 5.5 6.5	30° 45° 60° 75° 2.8 3.5 4.1 4.8 4.4 5.5 6.5 7.5	30° 45° 60° 75° 90° 2.8 3.5 4.1 4.8 5.4 4.4 5.5 6.5 7.5 8.5	30° 45° 60° 75° 90° 105° 2.8 3.5 4.1 4.8 5.4 6.1 4.4 5.5 6.5 7.5 8.5 9.6	30° 45° 60° 75° 90° 105° 120° 2.8 3.5 4.1 4.8 5.4 6.1 6.8 4.4 5.5 6.5 7.5 8.5 9.6 10.6	30° 45° 60° 75° 90° 105° 120° 135° 2.8 3.5 4.1 4.8 5.4 6.1 6.8 7.4 4.4 5.5 6.5 7.5 8.5 9.6 10.6 11.6	2.8 3.5 4.1 4.8 5.4 6.1 6.8 7.4 8.1 4.4 5.5 6.5 7.5 8.5 9.6 10.6 11.6 12.7	Time TMU for Degrees Turned 30° 45° 60° 75° 90° 105° 120° 135° 150° 165° 2.8 3.5 4.1 4.8 5.4 6.1 6.8 7.4 8.1 8.7 4.4 5.5 6.5 7.5 8.5 9.6 10.6 11.6 12.7 13.7 8.4 10.5 12.3 14.4 16.2 18.3 20.4 22.2 24.3 26.1

TABLE IV-GRASP-G

Case	Time	DESCRIPTION
1A	2.0	Pick Up Grasp-Small, medium or large object by itself, easily grasped.
18	3.5	Very small object or object lying close against a flat surface.
1C1	7.3	Interference with grasp on bottom and one side of nearly cylindrical object. Diameter larger than 3/2".
1C2	8.7	Interference with grasp on bottom and one side of nearly cylindrical object. Diameter 3/4" to 3/2".
1C3	10.8	Interference with grasp on bottom and one side of nearly cylindrical object. Diameter less than 1/4".
2	5.6	Regrasp.
3	5.6	Transfer Grasp.
48	7.3	Object jumbled with other objects so search and select occur. Larger than 1" x 1" x 1".
4B	9.1	Object jumbled with other objects so search and select occur. 1/4" x 1/4" x 1/4" to 1" x 1" x 1".
4C	12.9	Object jumbled with other objects so search and select occur. Smaller than 3/4" x 3/4" x 3/4".
5	0	Contact, sliding or hook grasp.

TABLE V-POSITION*-P

c	LASS OF FIT	Symmetry	Easy To Handle	Difficult Te Handle
		S	5.6	11.2
1-Loose	No pressure required	SS	9.1	14,7
		NS	10.4	16.0
		S	16.2	21.8
2-Close	Light pressure required	SS	19.7	25.3
		NS	21.0	26.6
		S	43.0	48.6
3-Exact	Heavy pressure required.	SS	46.5	52.1
		NS	47.8	53.4

*Distance moved to engage-1" or less.

TABLE VI-RELEASE-RL

TABLE VII-DISENGAGE-D

Case	Time TMU	DESCRIPTION
1	2.0	Normal release per- formed by opening fingers as independent motion.
2	0	Contact Release.

CLASS OF FIT	Easy to Handle	Difficult to Handle
1-Loose-Very slight effort, blends with subsequent move.	4.0	5.7
2-Close Normal effort, slight recoil.	7.5	11.8
3—Tight — Consider- able effort, hand re- coils markedly.	22.9	34.7

TABLE VIII-EYE TRAVEL TIME AND EYE FOCUS-ET AND EF

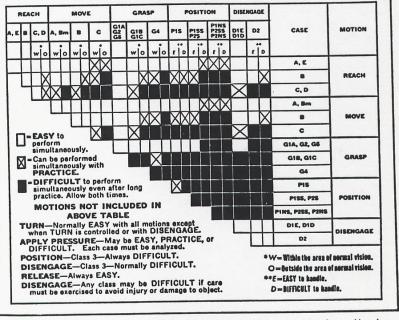
Eye Travel Time = 15.2 $x \frac{T}{D}$ TMU, with a maximum value of 20 TMU.

where T = the distance between points from and to which the eye travels. D = the perpendicular distance from the eye to the line of travel T.

Eye Focus Time=7.3 TMU.

TABLE IX-BODY, LE	G, AND P	OOT MOTIC	ONS		
DESCRIPTION	SYMBOL	DISTANCE	8.5 19.1 7.1 1.2		
Foot Motion—Hinged at Ankle. With heavy pressure. Leg or Foreleg Motion.	FM FMP LM —	Up to 4" Up to 6" Each add'l. inch			
Sidestep—Case 1—Complete when lead- ing leg contacts floor. Case 2—Lagging leg must contact floor before next motion can be made.	SS-C1 SS-C2	Less than 12" 12" Each add'l. inch 12" Each add'l. inch	Use REACH or MOVE Time 17.0 .6 34.1 1.1		
Bend, Stoop, or Kneel on One Knee. Arise. Kneel on Floor—Both Knees. Arise.	B,S,KOK AB,AS,AKOK KBK AKBK		29.0 31.9 69.4 76.7		
Sit. Stand from Sitting Position. Turn Body 45 to 90 degrees— Case 1—Complete when leading leg contacts floor. Case 2—Lagging leg must contact floor before next motion can be made.	TBC2		34.7 43.4 18.6 37.2		
Walk. Walk.	W-FT. W-P	Per Foot Per Pace	5.3 15.0		

TABLE X-SIMULTANEOUS MOTIONS



MTM Association for Standards and Research, Fair Lawn, New Jersey

•	GET	G
•	PUT	Р
•	GET WEIGHT	GW
•	PUT WEIGHT	PW
•	REGRASP	R
•	APPLY PRESSURE	А
•	EYE ACTION	E
•	FOOT ACTION	F
•	STEP	S
•	BEND & ARISE	В
•	CRANK	С

Time Study (Stopwatch Measurement)

- 1. List work elements
- 2. Discuss with worker
- 3. Measure with stopwatch (running VS reset)
- 4. Repeat for n Observations
- 5. Compute mean and std dev of work station time
- 6. Be aware of allowances/foreign element, etc

	OPER. NO.
SHOP	STUDY NO.
PART NAME	SHEET NO.
PART NO	
OPERATION	OBSERVER
	OPERATOR

ELEMENTS	1	2	3	4	5	6	7	8	9	10	TOT.	AVG.	RF	BAS
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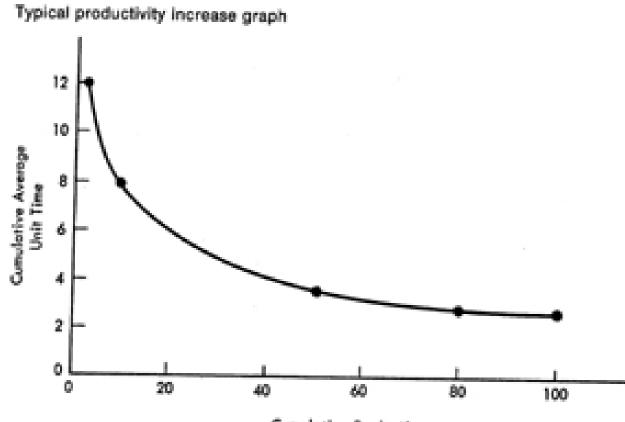
Figure 1. Activity-Timestudy of a Secretary for One Day

Work Sampling

- Determined what is done over typical day
- Random Reporting
- Periodic Reporting

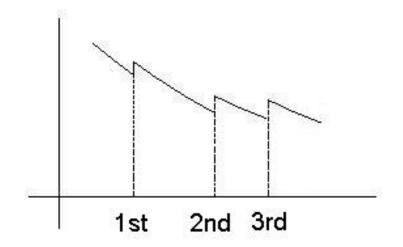
- For repetitive work, worker gains skill, knowledge of product/process, etc over time
- Thus we expect output to increase over time as more units are produced over time to complete task decreases as more units are produced

Traditional Learning Curve



Cumulative Production

Actual Curve



Change, Design, Process, etc

- Usually define learning as a percentage reduction in the time it takes to make a unit.
- The definition says a doubling of the total number of units made produce a constant decrease in the time per unit
- An 80% learning curve implies a 20% decrease in unit time with each doubling of the number produced (90% implies 10% decrease, 100% implies no improvement)

• For an 80% learning Curve: Unit Unit Time (hours) 10 (.8)(10) = 82 (.8)(8) = 6.44 8 (.8)(6.4) = 5.1216 (.8)(5.12) = 4.096

• We can also compute the time to complete the nth unit based on the learning %, and the time for the 1st unit

 $Tn = T1 \times n^{b}$

Where, b = (natural log of learning %) / (natural log of 2)

• From Previous 80% learning curve example:

$$b = \ln (.8) / \ln (2)$$

For 3rd unit:

 $T3 = T1 (3 ^ (ln(.8)/ln(2)))$ T3 = T1 (.702)

• Can plot using log/log paper as a straight line and can also got unit curve and average curve

Learning Curve Applies

- Mass Production Assembly line
- G.T. Cell Repetitive work
- Other places where rep. Works performed.