Hyperplane

### Point and vector

- A point in n-dimensional space is given by an n-tuple, e.g., P = (p<sub>i</sub>)
  - A point denotes an absolute position in space
- A vector represents magnitude and direction in space, and is given by an n-tuple.
  Vectors do not have a fixed position in place, but can be located at any initial base point P.
- The vector from point P to Q is given by  $v = Q P = (q_i p_i)$
- Vector addition:  $v + w = (v_i + w_i)$
- The length of a vector v:  $|v| = \sqrt{\sum_{i=1}^{n} v_i^2}$
- http://geomalgorithms.com/points\_and\_vectors.html

#### Normal vector

- A normal vector is a vector perpendicular to another object (e.g., a plane).
- A unit normal vector is a normal vector of length one.
   If N is a normal vector, the unit normal vector is
   N/|N|, where |N| is the length of N.

# The equation for a hyperplane

 A 3-D plane determined by normal vector N=(A, B, C) and point Q=(x0, y0, z0) is: A(x - x0) + B(y - y0) + C(z - z0) = 0

which can be written as

$$Ax + By + Cz + D = 0$$
, where  $D = -A x0 - B y0 - c z0$ 

• Hyperplane: w x + d = 0,

where w is a normal vector, x is a point on the hyperplane

It separates the space into two half-spaces:
 wx + d > 0 and wx + d < 0</li>

## The distance from a point to a plane

 Given a plane Ax + By + Cz + D = 0, and a point P=(x1, y1, z1), the distance from P to the plane is:

$$d = \frac{|Ax_1 + By_1 + Cz_1 + D|}{\sqrt{A^2 + B^2 + C^2}}$$

See http://mathinsight.org/distance\_point\_plane

Distance from a point x to a hyperplane wx + d = 0 is:
 |w x + d |/||w||

## Distance between two parallel planes

- Two planes  $A_1x + B_1y + C_1z + D_1=0$  and  $A_2x + B_2y + C_2z + D_2=0$  are parallel if  $A_1=k A_2$ ,  $B_1=k B_2$  and  $C_1=k C_2$
- The distance between Ax + By + Cz + D1 = 0 and Ax + By + Cz + D2 = 0 is equal to the distance from a point (x1, y1, z1) on the first plane to the second plane:

$$\frac{|Ax_1 + By_1 + Cz_1 + D2|}{\sqrt{A^2 + B^2 + C^2}} = \frac{|D2 - D1|}{\sqrt{A^2 + B^2 + C^2}}$$

• The distance between two hyperplanes wx + d1 = 0 and wx + d2 = 0 is  $\frac{|d2 - d1|}{|d2 - d1|}$