

ME 355

NOTES ON MACHINING
PROCESSES.

Ch. 16 (TEXT).

MINIMUM READING:

§ 16.1 (p. 617-645)

16.2-1 (p. 646)

16.3.1 (p. 652-653)

16.7.1 { p. 684-690 }

16.7.2

16.7-5 (p. 694-696)

PLUS: ANYTHING NEEDED TO
DO HOMEWORK ASSIGNED.

Nipin Kurnan

MACHINING PROCESSES

CASTING & FORMING INVOLVE MATERIAL FLOW - EITHER AS LIQUID OR AS SOLID. BOTH HAVE LIMITATIONS:

CASTING: MATERIAL PROPERTIES,
DIMENSIONAL ACCURACY

FORMING: LARGE JOB → HUGE MACHINERY
GEOMETRIC COMPLEXITIES

THESE PROBLEMS OVERCOME IN MACHINING WHERE EXCESS MATERIAL IS REMOVED IN THE FORM OF SMALL CHIPS

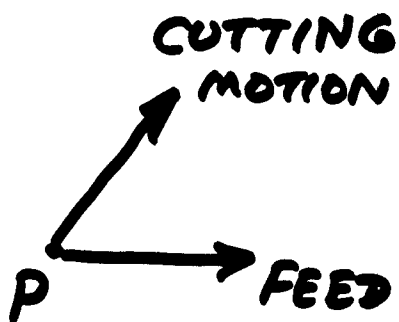
MACHINING TERMINOLOGY

CUTTING TOOL REMOVES MATERIAL

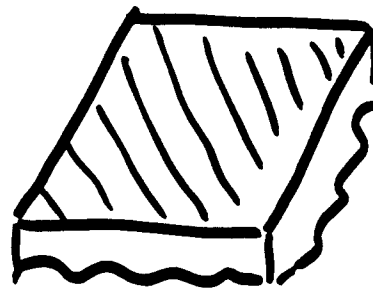
MACHINE TOOL PROVIDES RELATIVE
MOTIONS

PRIMARY CUTTING MOTION

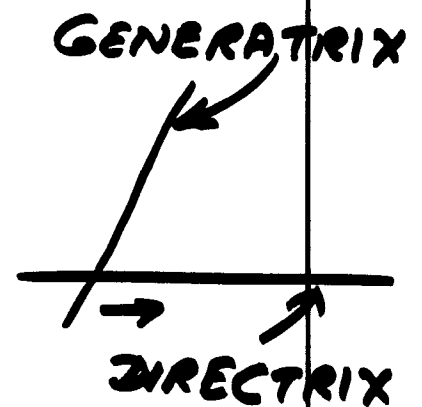
SECONDARY CUTTING MOTION (FEED)



(a)



(b)

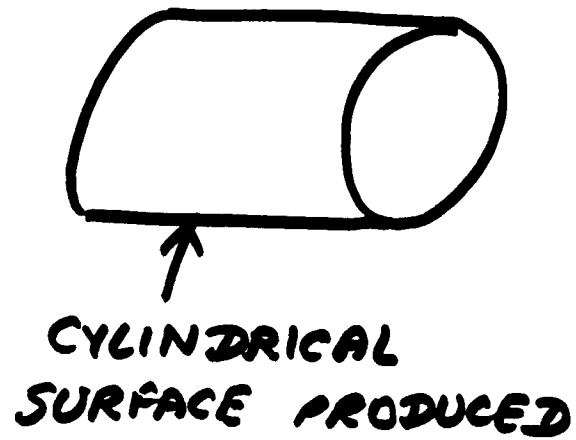
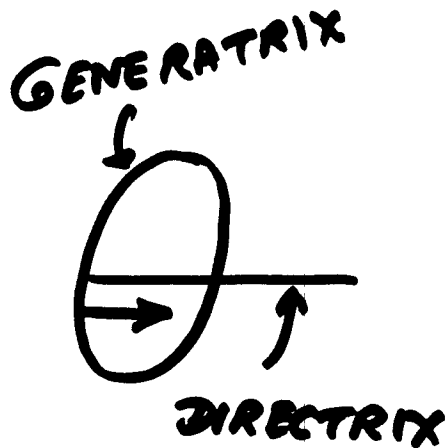


(c)

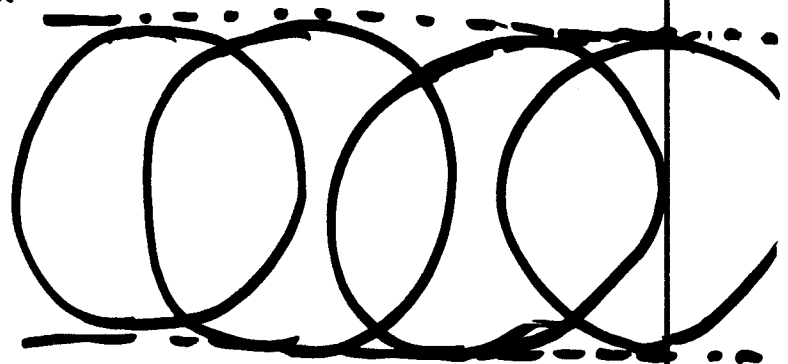
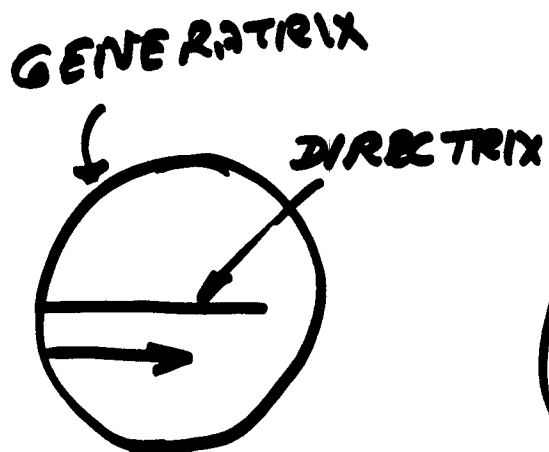
(a): MOTIONS OF THE CUTTING PT.

(b): SURFACE PRODUCED

(c): GENERATRIX E. DIRECTRIX
↓
LINE GENERATED
BY CUTTING MOTION ↓
BY FEED
MOTION



DIRECTRIX $\perp$ TO PLANE OF GENERATRIX



**DIRECTRIX IN THE PLANE OF
GENERATRIX**

COMMON MACHINING PROCESSES

- SHAPING & PLANNING
- TURNING
- DRILLING
- MILLING
- GRINDING

COMMON MACHINING OPERATIONS

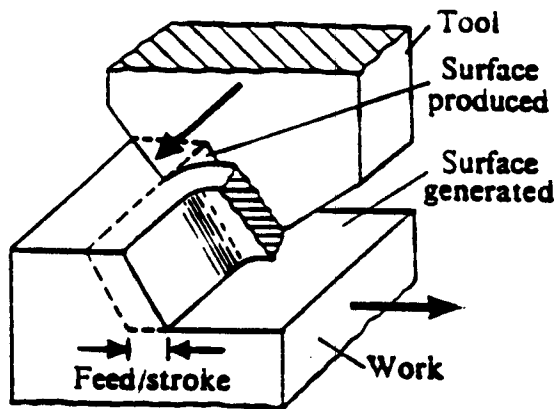


Fig. 4.3 Shaping operation.

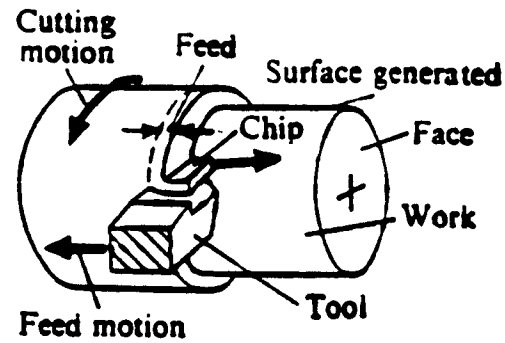


Fig. 4.4 Turning operation.

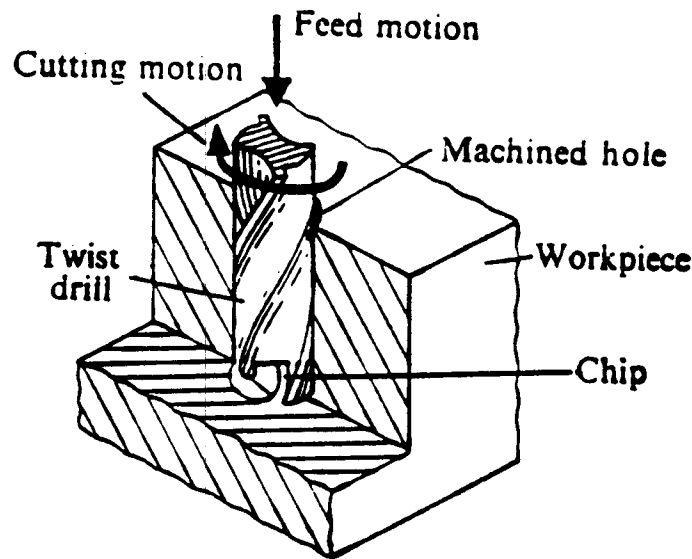
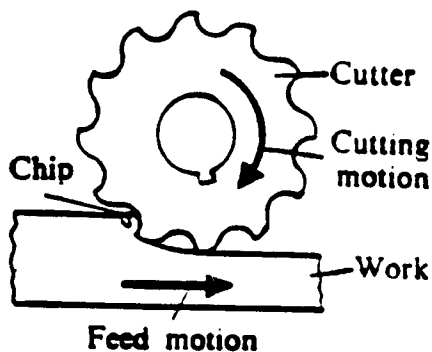
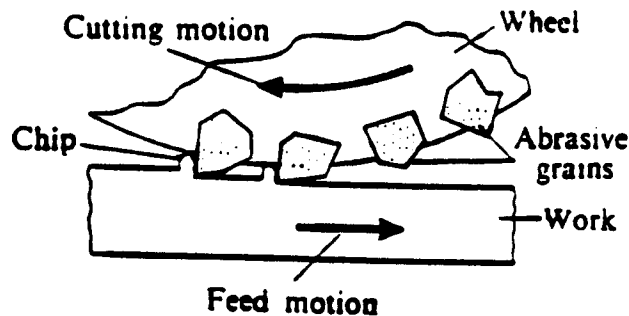


Fig. 4.5 Drilling operation.



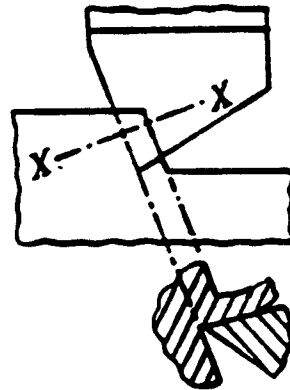
(a) Scheme of milling operation



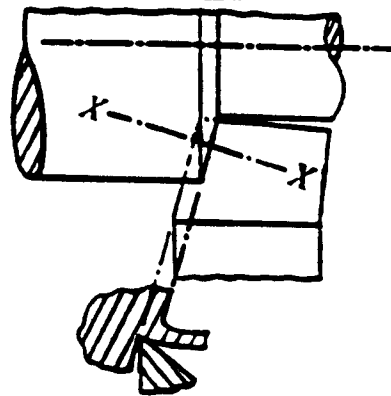
(b) Scheme of grinding operation

Fig. 4.6 Machining with multipoint tools.

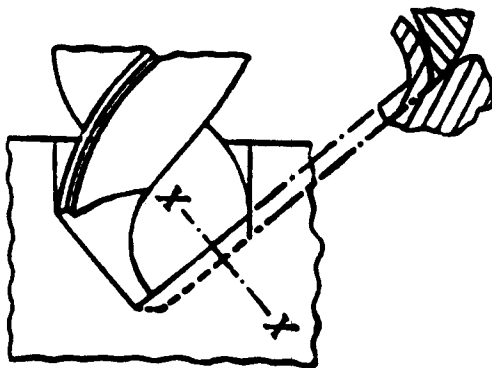
SIMILARITY IN THE MATERIAL REMOVAL PROCESSES



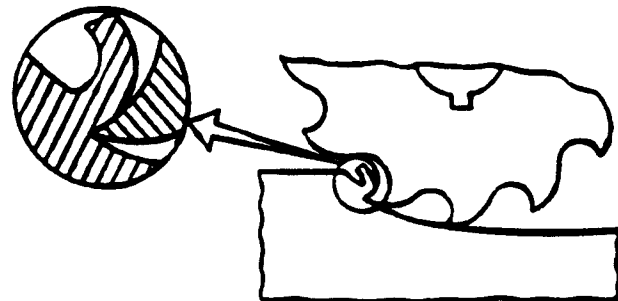
(a) Shaping



(b) Turning

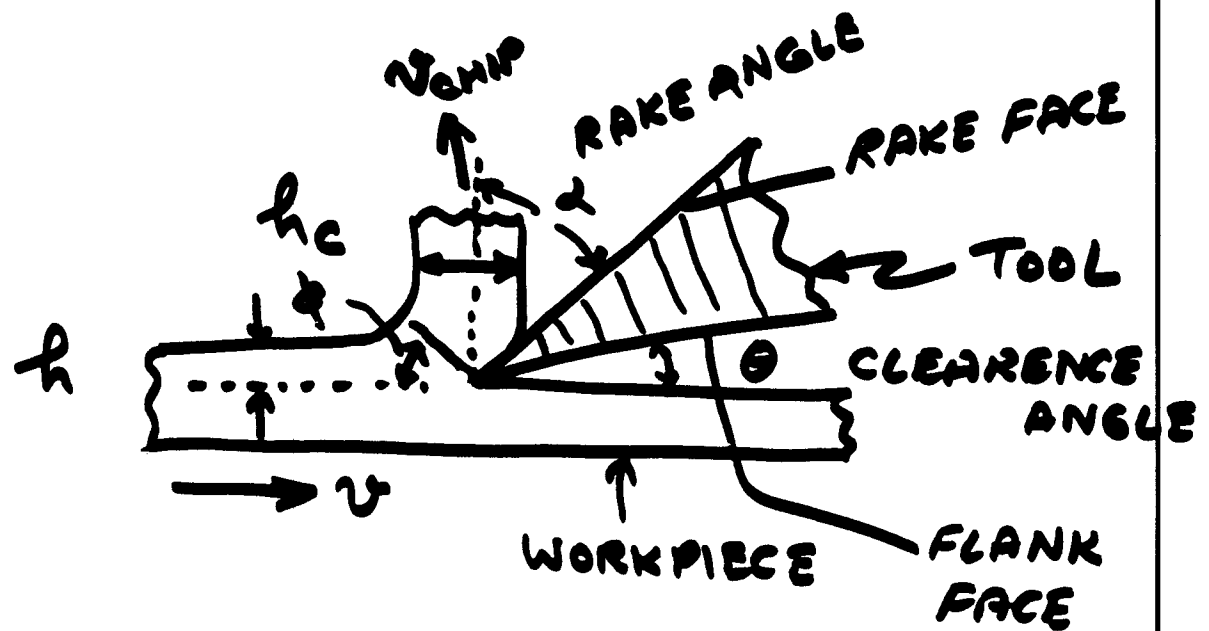


(c) Drilling



(d) Milling

Fig. 4.7 Simulation of actual machining processes.



h : UNCUT CHIP THICKNESS

h_c : CHIP THICKNESS

BASIC OPERATION AND PARAMETERS.

VARIABLES

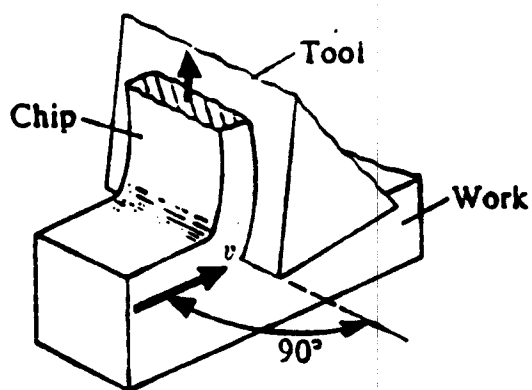
INDEPENDENT

TOOL MAT'L, α , θ
 TOOL GEOMETRY
 WORKPC. MAT'L + GEOM.
 TEMP. OF WORKPC.
 SPEED, FEED, etc.
 CUTTING FLUID
 MACHINE TOOL: POWER,
 STIFFNESS, etc.

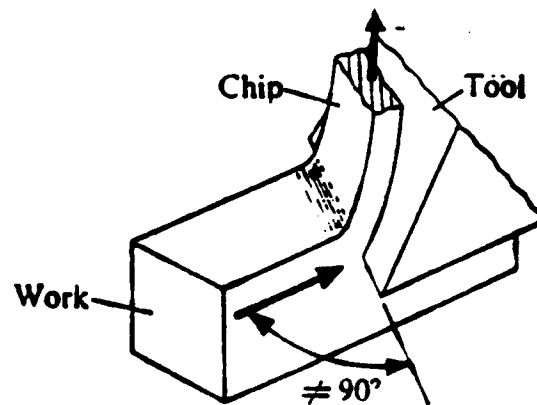
DEPENDENT

SHEAR ANGLE ϕ
 CHIP FORMATION
 E. MORPHOLOGY
 FORCES; ENERGY
 WEAR
 TEMP. RISE
 SURFACE FINISH

ORTHOGONAL VS OBLIQUE CUTTING OPERATIONS



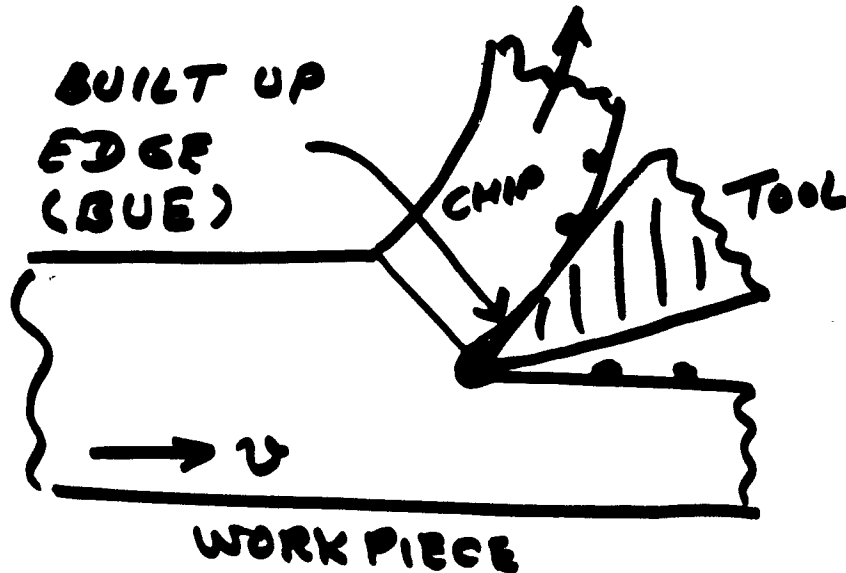
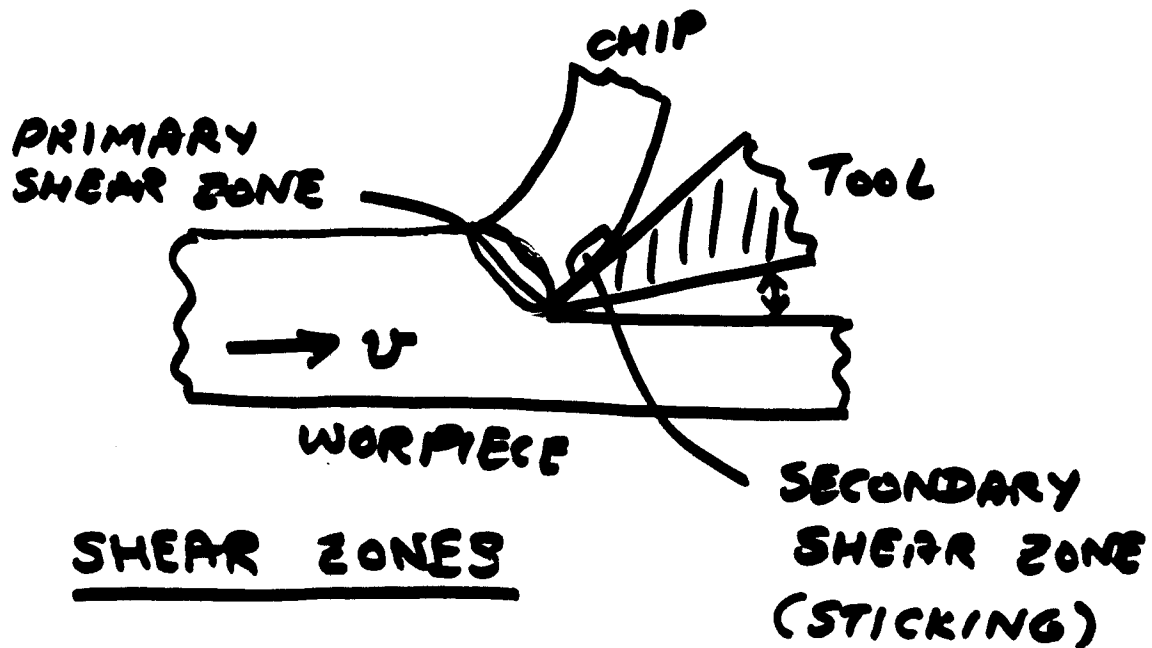
(a) Orthogonal



(b) Oblique

Fig. 4.9 Types of machining operations.

MECHANISM OF CHIP FORMATION



BUE FORMATION

HIGH EFFECTIVE α : ENERGY CONSUMPTION $\downarrow$
BUT DIMENSIONAL CONTROL & SURFACE FINISH LOST

CHIP FORMATION ;

BUILT-UP. EDGE (BUE) ; EFFECT OF CUTTING SPEED.

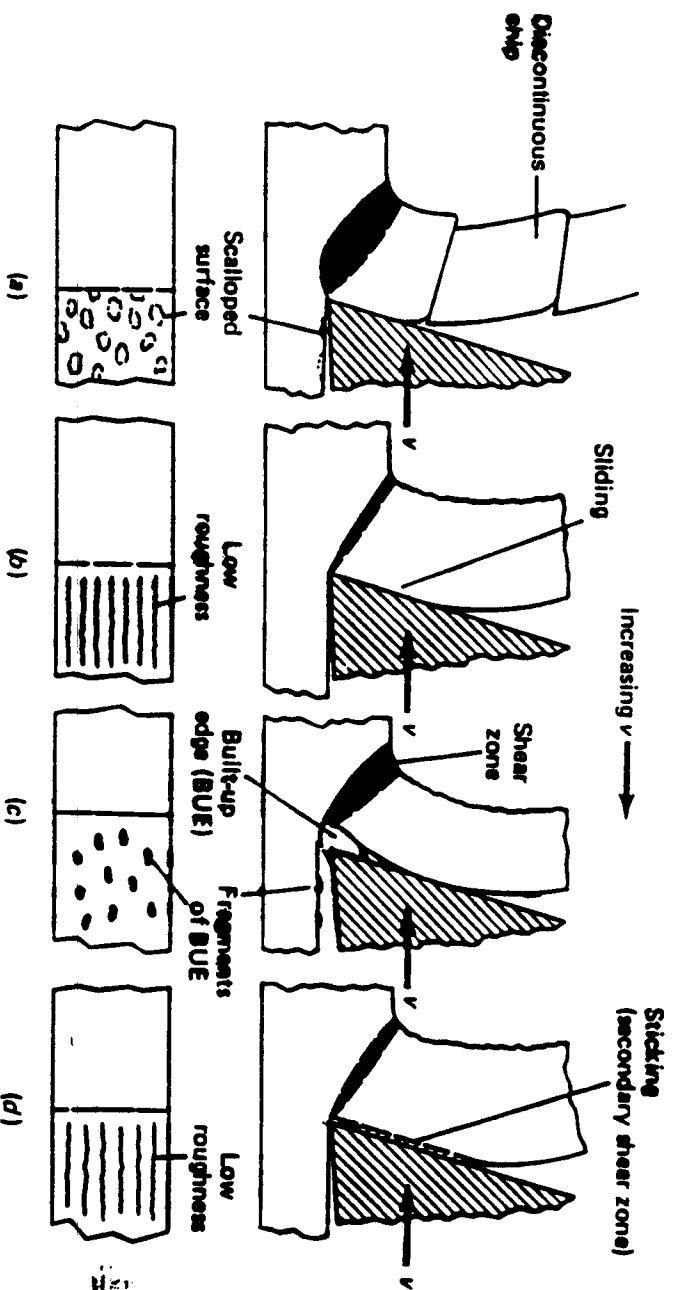


FIGURE 8-4

The process of chip formation changes with cutting speed. When cutting steel, the chip (a) is discontinuous at speeds below 2 m/min, (b) is continuous and slides on the rake face at 7 m/min, (c) forms with a built-up edge at 20 m/min, and (d) develops a secondary shear zone at 40 m/min. (After M. C. Shaw, in *Machinability*, Spec. Rep. 94, The Iron and Steel Institute, London, 1967, pp. 1-9.)

VARIOUS KINDS OF CHIPS

1. CONTINUOUS WITHOUT BUE

DUCTILE MATERIAL

SMALL UNCUT THICKNESS

HIGH CUTTING SPEED

SUITABLE CUTTING FLUID

2. CONTINUOUS WITH BUE

STRONG ADHESION BETWEEN
CHIPS & TOOL FACE

LOW RAKE ANGLE

LARGE UNCUT THICKNESS

3. DISCONTINUOUS CHIPS

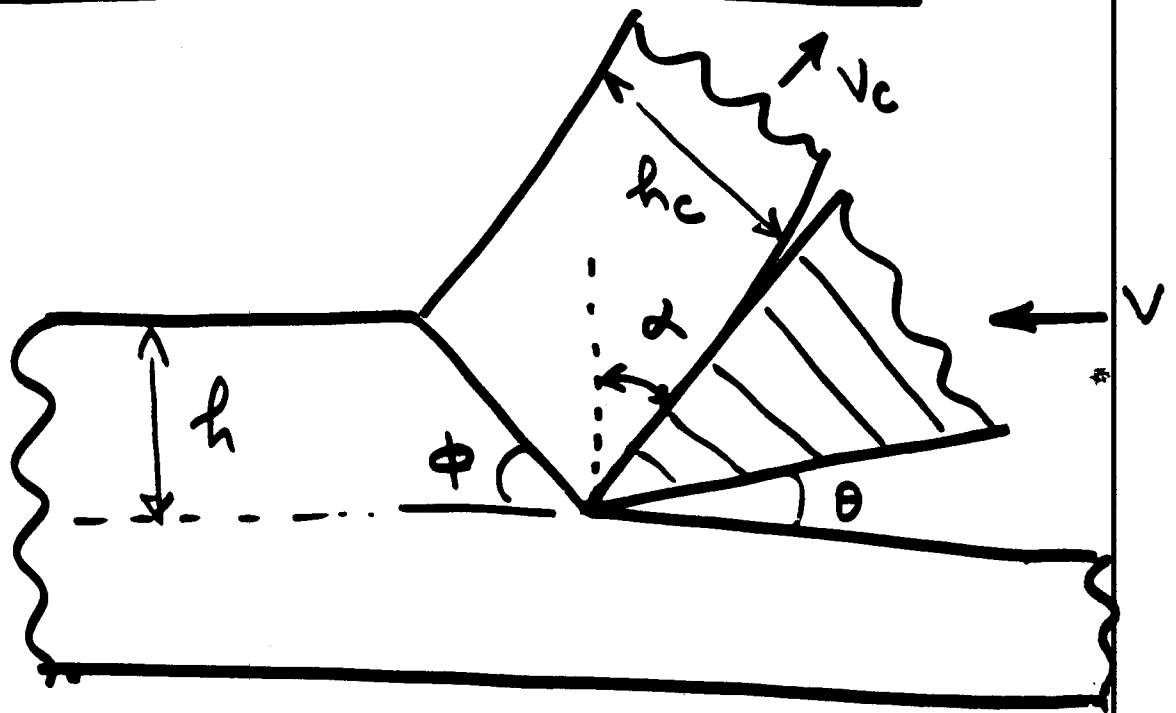
LOW CUTTING SPEED

BRITTLE WORK MATERIAL

SMALL RAKE ANGLE

LARGE UNCUT THICKNESS

ORTHOGONAL CUTTING



h = uncut chip thickness

h_c = Chip thickness

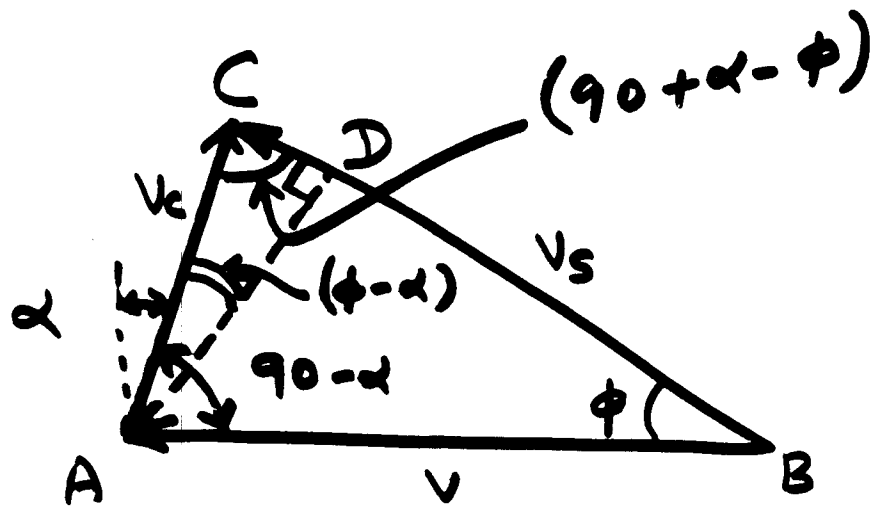
v_c = Chip speed

v = Cutting speed

ϕ = Shear angle

α = rake angle

θ = clearance angle



from $\triangle ACB$

$$\phi + (90 - \alpha) + \angle ACB = 180^\circ$$

$$\begin{aligned} \therefore \angle ACB &= 180 - (90 - \alpha) - \phi \\ &= 90 + \alpha - \phi \end{aligned}$$

from $\triangle ACD$

$$\begin{aligned} \angle DAC &= 90 - (90 + \alpha - \phi) \\ &= (\phi - \alpha) \end{aligned}$$

Now from $\triangle ABC$

(using $\frac{\sin A}{A} = \frac{\sin B}{B} = \frac{\sin C}{C}$)

$\uparrow$
length of side opposite to angle A)

$$\frac{V_c}{\sin \phi} = \frac{V}{\sin(90 + \alpha - \phi)} = \frac{V_s}{\sin(90 - \alpha)}$$

Cutting ratio

$$r_c = \frac{h}{h_c} = \frac{h_c}{l} = \frac{V_c}{V}$$

$$r_c = \frac{V_c}{V} = \frac{\sin \phi}{\sin(90 - (\phi - \alpha))}$$

$$\alpha \quad r_c = \frac{\sin \phi}{\cos(\phi - \alpha)} \quad (\text{Eq. 16.3})$$

NOTE, as $\phi \uparrow$, $r_c \uparrow$ Thus $h_c \downarrow$ and $V_c \uparrow$
 $\Rightarrow$ CHIP BECOMES THINNER AND COMES OFF FASTER

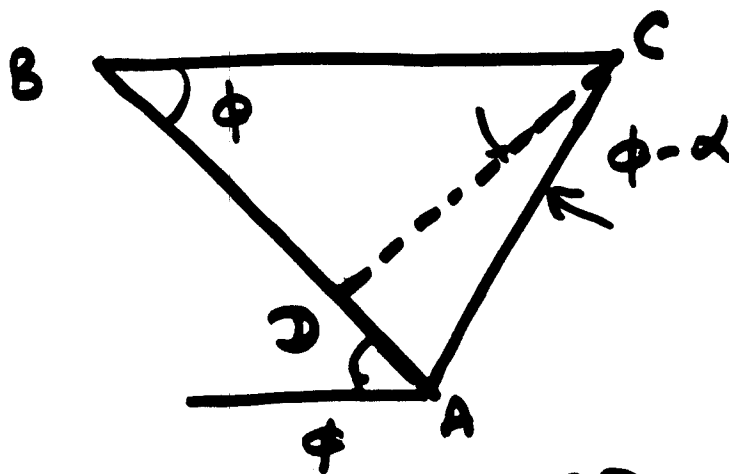
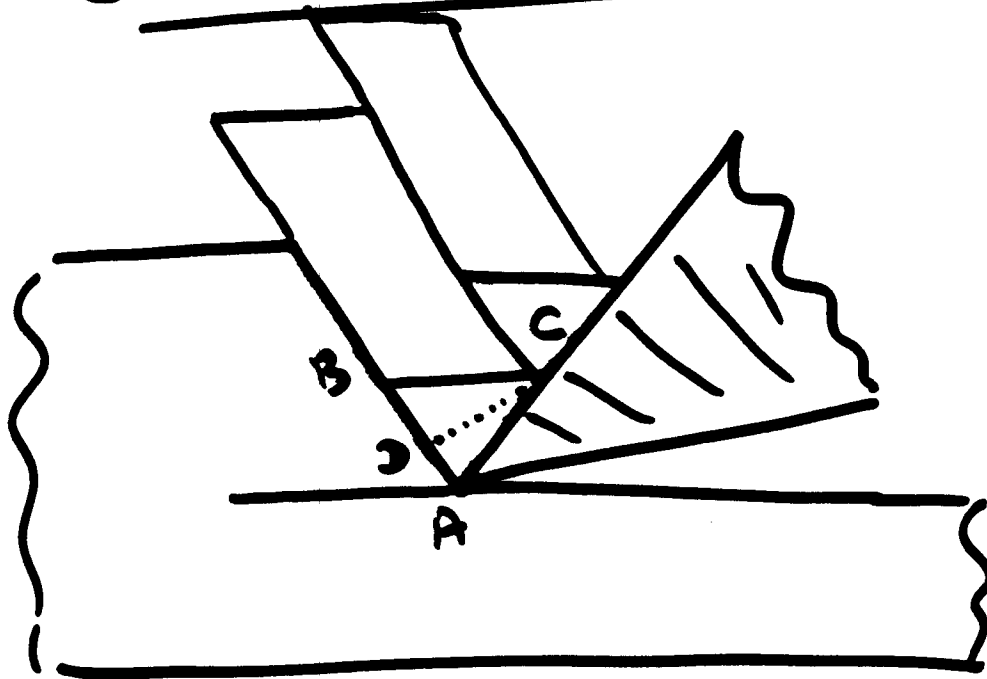
$$c) \quad R_c = \frac{\sin \phi}{\cos \phi \cos \alpha + \sin \phi \sin \alpha}$$

$$a, \quad \sin \phi = R_c \cos \phi \cos \alpha + R_c \sin \phi \sin \alpha$$

$$a, \quad \sin \phi (1 - R_c \sin \alpha) = R_c \cos \phi \cos \alpha$$

$$a, \quad \tan \phi = \frac{R_c \cos \alpha}{1 - R_c \sin \alpha} \quad (\text{Eq. } \frac{16.2}{8-2})$$

Shear Strain



$$\gamma = \frac{AB}{CD} = \frac{AD}{CD} + \frac{BD}{CD} = \tan(\phi - \alpha) + \cot \phi$$

Shear rate

$$\dot{\gamma} = \frac{V_s}{\Delta y} = \frac{V_s}{V} \frac{V}{\Delta y}$$

where Δy = thickness of shear zone ($\approx .001$ in.)

$$\dot{\gamma} = \left(\frac{\sin(90-\alpha)}{\sin(90-(\phi-\alpha))} \right) \cdot \frac{V}{\Delta y}$$

$$\text{or } \dot{\gamma} = \frac{\cos \alpha}{\cos(\phi-\alpha)} \cdot \frac{V}{\Delta y} \quad (\text{Eq. } 16.5)_{16.5}$$

$\dot{\gamma}$ CAN EASILY BE $10^3 - 10^4 / \text{sec.}$

FORCES IN orthogonal cutting



P_c : Cutting force } on tool holder

P_t : Thrust force } (measured)

P_h : Normal force } on tool

F : Frictional force }

{ P_h : Hydrostatic (Compressive) force

{ F_s : Shearing force

on workpiece.

$$P_n = P_c \cos \alpha - P_t \sin \alpha$$

$$F = P_c \sin \alpha + P_t \cos \alpha$$

Friction angle ψ

$$\tan \psi = \mu = \frac{F}{P_n}$$

$$\tan \psi = \frac{P_t + P_c \tan \alpha}{P_c - P_t \tan \alpha}$$

ϕ depends on the process itself.

For minimum energy

$$\phi = 45^\circ - \frac{1}{2} (\psi - \alpha)$$

Thus if $\psi \uparrow$ or $\alpha \downarrow \Rightarrow \phi \downarrow$

$\Rightarrow$ larger energy consumption.

$\therefore$ for min. energy, use high α and low ψ .

Forces and Energy

Experimental material constants

Specific Cutting pressure

1. $P_c = \frac{P_c}{hw} \left[\frac{N}{m^2} \right]$ (not a true stress)

cross section of undeformed chip

2. Specific cutting energy (See Table 16-1)

$$E_1 = \frac{P_c \cdot l}{hw \cdot l} \left[\frac{J}{m^3} \right] \text{ or } \left[\frac{N}{m^2} \right]$$

= Energy required to remove a unit Vol.

(l = length of uncut chip)

3. Material removal factor

$$K_1 = \frac{1}{E_1} = \left[\frac{m^3}{J} \right] \text{ material removed per unit power.}$$

Adjusted Specific Cutting Energy

$$E = E_1 \left(\frac{h}{h_{\text{ref}}} \right)^{-a}$$

$$h_{\text{ref}} = 1 \text{ mm}$$

$$E = E_1 h^{-a}$$

$$a \approx 0.2 \text{ to } 0.4$$

(Take $a = 0.3$ for most materials.)

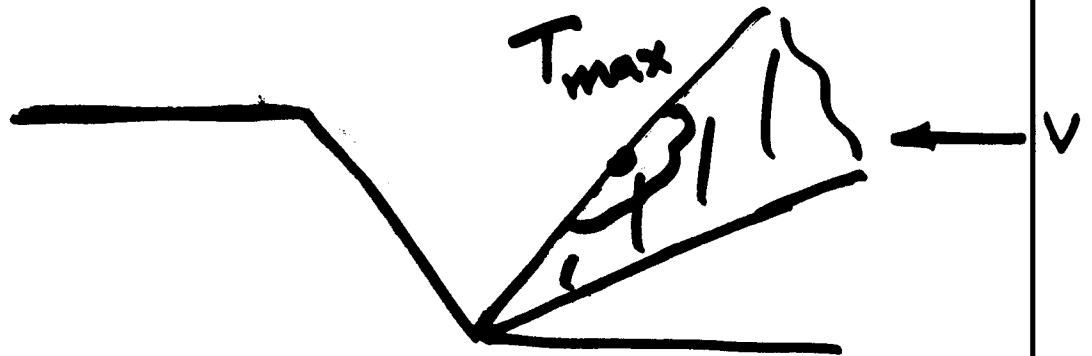
$$\text{Power req'd} = \frac{E V_t}{\eta}$$

where V_t = material removal rate.

$$\text{Cutting force } P_c = \frac{\text{Power}}{V}$$

TOOL TEMPERATURES

(depend on v)

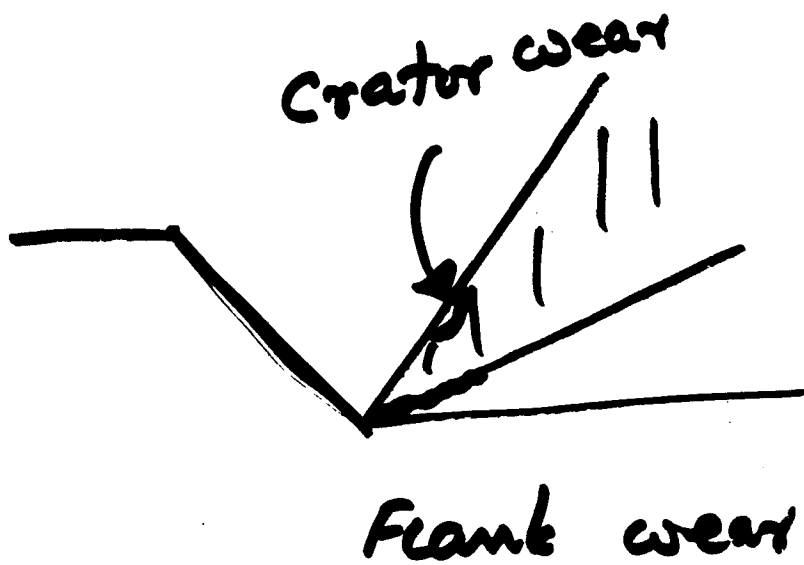


Mean tool face temp. T_T

$$T_T = E \left(\frac{v h}{k \rho c} \right)^{1/2}$$

k = heat conductivity } workpc.
 ρ = density } mat'l
 c = specific heat }

TOOL LIFE.



Taylor

$$V t^n = C$$

$$t = \frac{C}{V^n}$$

V = Cutting speed

t = tool life

C = Cutting speed for life of 1 min.

Refinement :

$$t = \frac{K}{v^{1/n_1} f^{1/n_2} w^{1/n_3}}$$

f : feed rate

w = depth of cut