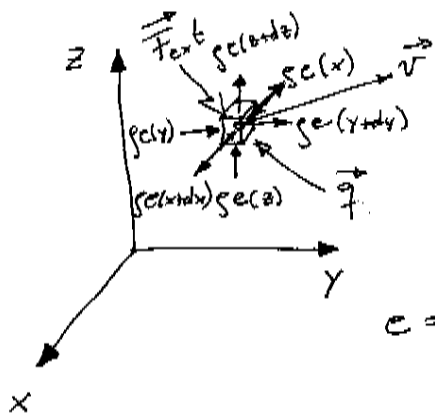


Conservation of Energy in Differential form



$$\frac{\rho}{\rho t} \int_{c.v} \rho c dV + \int_{c.s} \rho e (\vec{v} \cdot \vec{n}) \cdot \vec{n} dA = - \int_{c.s} p \vec{n} \cdot \vec{v} dA + \int_{c.s} \vec{v} \cdot \vec{z} \cdot \vec{n} dA$$

$$+ \int_{c.v} \rho \vec{g} \cdot \vec{v} dV + \int_{c.v} \dot{Q}_{md} dV - \int_{c.s} \vec{q} \cdot \vec{n} dA$$

$$e = u + \frac{1}{2} v^2$$

$$\frac{\rho e}{\rho t} + \nabla \cdot (\rho e \vec{v}) = - \nabla \cdot (p \vec{v}) + \nabla \cdot (\vec{v} \cdot \vec{z}') + \rho \vec{g} \cdot \vec{v} + \dot{q}_{md} - \nabla \cdot \vec{q}$$

$$\rho \frac{de}{dt} + \rho \vec{v} \cdot \nabla e + \underbrace{\rho \left[\frac{de}{dt} + \vec{v} \cdot \nabla e \right]}_0 = - \rho (\nabla \cdot \vec{v}) - \vec{v} \cdot \nabla p + \vec{z}' : \nabla \vec{v} + \vec{v} \cdot \nabla (p)$$

$$+ \rho \vec{g} \cdot \vec{v} + \dot{q}_{md} - \nabla \cdot \vec{q}$$

Conservation of total energy

Mechanical Energy: multiply the momentum conservation equation by the velocity

$$\frac{D}{Dt} \rho \vec{v} \cdot \vec{v} = \sum F_{ext} \cdot \vec{v}$$

$$\frac{D}{Dt} \left(\frac{1}{2} \rho v^2 \right) = \dot{W}_{ext}$$

$$\vec{v} \cdot \left[\rho \frac{D\vec{v}}{Dt} + \rho (\vec{v} \cdot \nabla) \vec{v} \right] = \left(-\nabla p + \nabla \cdot \vec{z}' + \rho \vec{g} \right) \cdot \vec{v}$$

$$\rho \frac{D}{Dt} \left(\frac{1}{2} v^2 \right) + \rho (\vec{v} \cdot \nabla) \left(\frac{1}{2} v^2 \right) = -\vec{v} \cdot \nabla p + \vec{v} \cdot (\nabla \cdot \vec{z}') + \rho \vec{g} \cdot \vec{v}$$

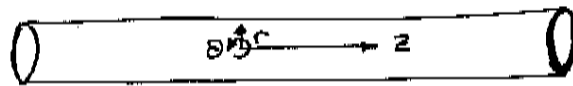
Subtracting Mechanical Energy from the total energy we get:

$$\int \frac{\rho u}{\rho t} + \int \vec{v} \cdot \nabla u = -p(\nabla \cdot \vec{v}) + \underbrace{\bar{Z}': \nabla \vec{v}}_{\text{viscous dissipation } \phi \text{ (positive definite)}} + \underbrace{\dot{q}_{\text{rad che}} - \nabla \cdot \vec{q}}_{\text{Heat addition}}$$

The rate of change of the internal energy of the fluid is due to:

Pipe flow

Fully develop, laminar, steady, incompressible



Continuity: $\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \vec{v} = 0$

$$\int \left[\frac{1}{r} \frac{\partial}{\partial r} (r v_r) + \frac{1}{r} \frac{\partial}{\partial \theta} v_\theta + \frac{\partial}{\partial z} v_z \right] = 0$$

Fully develop means $\frac{\partial \vec{v}}{\partial z} = 0$

$$\frac{\partial}{\partial r} (r v_r) = -\frac{\partial}{\partial \theta} v_\theta$$

$$r \frac{\partial v_r}{\partial r} + v_r = -\frac{\partial}{\partial \theta} v_\theta$$

$$\partial r = 0 \quad v_r = v_\theta = 0$$

$$\partial r = R \quad v_r = v_\theta = 0$$

$$\partial r = 0 \Rightarrow \frac{\partial v_\theta}{\partial \theta} = 0$$

$$\partial r = R \Rightarrow \frac{\partial v_\theta}{\partial \theta} = 0 \Rightarrow \frac{\partial v_r}{\partial r} = 0$$

Only solution is $v_r = v_\theta = 0$

Conservation of momentum

$$\int \frac{\rho v_r}{\rho t} + \int \left(v_r \frac{\rho v_r}{\rho r} + \frac{v_\theta}{r} \frac{\rho v_r}{\rho \theta} + v_z \frac{\rho v_r}{\rho z} - \frac{v_\theta^2}{r} \right) = -\frac{\rho P}{\rho r} + \mu \left[\frac{1}{r} \frac{\rho}{\rho r} \left(r \frac{\rho v_r}{\rho r} \right) + \frac{1}{r^2} \frac{\rho^2 v_r}{\rho \theta^2} + \frac{\rho^2 v_r}{\rho z^2} - \frac{v_\theta}{r^2} - \frac{2}{r^2} \frac{\rho v_\theta}{\rho \theta} \right]$$

$$\int \frac{\rho v_\theta}{\rho t} + \int \left(v_r \frac{\rho v_\theta}{\rho r} + \frac{v_\theta}{r} \frac{\rho v_\theta}{\rho \theta} + v_z \frac{\rho v_\theta}{\rho z} + \frac{v_r v_\theta}{r} \right) = -\frac{1}{r} \frac{\rho P}{\rho \theta} + \mu \left[\frac{1}{r} \frac{\rho}{\rho r} \left(r \frac{\rho v_\theta}{\rho r} \right) + \frac{1}{r^2} \frac{\rho^2 v_\theta}{\rho \theta^2} + \frac{\rho^2 v_\theta}{\rho z^2} + \frac{2}{r} \frac{\rho v_\theta}{\rho \theta} - \frac{v_\theta}{r^2} \right]$$

$$\int \frac{\rho v_z}{\rho t} + \int \left(v_r \frac{\rho v_z}{\rho r} + \frac{v_\theta}{r} \frac{\rho v_z}{\rho \theta} + v_z \frac{\rho v_z}{\rho z} \right) = -\frac{\rho P}{\rho z} + \mu \left[\frac{1}{r} \frac{\rho}{\rho r} \left(r \frac{\rho v_z}{\rho r} \right) + \frac{1}{r^2} \frac{\rho^2 v_z}{\rho \theta^2} + \frac{\rho^2 v_z}{\rho z^2} \right]$$

$$\nabla^2 \left(\frac{\rho v_z}{\rho \theta} \right) = 0 \quad \text{with} \quad \frac{\rho v_z}{\rho \theta} = 0 \quad \text{at} \quad r=0 \quad \text{and} \quad r=R$$

Resulting equations are $\frac{\rho P}{\rho r} = \frac{1}{r} \frac{\rho P}{\rho \theta} = 0$

$$0 = -\frac{\rho P}{\rho z} + \mu \frac{1}{r} \frac{\rho}{\rho r} \left(r \frac{\rho v_z}{\rho r} \right)$$

If I take the derivative $\frac{\rho}{\rho z}$

$$\frac{\rho^3 P}{\rho z^2} = \mu \frac{1}{r} \frac{\rho}{\rho r} \left[r \frac{\rho}{\rho r} \left(\frac{\rho v_z}{\rho r} \right) \right] = c$$

Therefore $\frac{\rho P}{\rho z} = \frac{dP}{dz} = \text{constant}$

$$\frac{1}{r} \frac{\rho}{\rho r} \left[r \left(\frac{\rho v_z}{\rho r} \right) \right] = \frac{1}{\mu} \frac{dP}{dz} = \text{constant}$$

$$\frac{d}{dr} \left(r \frac{dv_z}{dr} \right) = \frac{1}{\mu} \frac{dP}{dz} r$$

$$r \frac{dv_z}{dr} = \frac{1}{\mu} \frac{dP}{dz} \frac{r^2}{2} + \frac{C_2}{r}$$

$$\frac{dv_z}{dr} = \frac{1}{\mu} \frac{dP}{dz} \frac{r}{2} + \frac{C_2}{r}$$

$$v_z(r) = \frac{1}{\mu} \frac{dP}{dz} \frac{r^2}{4} + C_2$$

$$\left. \frac{dv_z}{dr} \right|_{r=0} = 0 \quad \text{Symmetry}$$

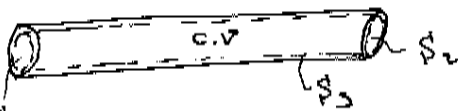
$$v_z(r) = \frac{1}{\mu} \frac{dP}{dz} \frac{r^2}{4} + C_2$$

$$v_z(r=R) = 0 \Rightarrow C_2 = -\frac{1}{\mu} \frac{dP}{dz} \frac{R^2}{4}$$

$$v_z(r) = \frac{1}{4\mu} \frac{dP}{dz} (r^2 - R^2)$$

$$v_z(r) = \frac{1}{4\mu} \left(-\frac{dP}{dz} \right) (R^2 - r^2)$$

Conservation of energy



$$\frac{d}{dt} \int_{c.v.} \rho e dV + \int_{c.s.} \rho e (\vec{v} \cdot \vec{e}_c) \cdot \vec{n} dA = - \int_{c.s.} P \vec{n} \cdot \vec{v} dA + \int_{c.s.} \vec{v} \cdot \vec{\tau} \cdot \vec{n} dA + \int_{c.v.} \vec{S} \cdot \vec{v} dV + \int_{c.v.} \dot{q}_{che} dV$$

Steady

$$\underbrace{\int_{S_1} \rho e_1 \vec{v} \cdot \vec{n} dA}_{-Q} + \underbrace{\int_{S_2} \rho e_2 \vec{v} \cdot \vec{n} dA}_{Q} + \underbrace{\int_{S_3} \rho e \vec{v} \cdot \vec{n} dA}_{0 \text{ SOLID WALL}} = -P_1 \underbrace{\int_{S_1} \vec{v} \cdot \vec{n} dA}_{-Q} - P_2 \underbrace{\int_{S_2} \vec{v} \cdot \vec{n} dA}_{Q} - \underbrace{\int_{S_3} P \vec{v} \cdot \vec{n} dA}_{0 \text{ SOLID WALL}}$$

$$+ \underbrace{\int_{S_1} \vec{v} \cdot \vec{\tau} \cdot \vec{n} dA}_{\text{negligible}} + \underbrace{\int_{S_2} \vec{v} \cdot \vec{\tau} \cdot \vec{n} dA}_{\text{negligible}} + \underbrace{\int_{S_3} \vec{v} \cdot \vec{\tau} \cdot \vec{n} dA}_{0 \text{ SOLID WALL}}$$

negligible
no increase in kinetic energy
Adiabatic

$$\int_{S_2} e_2 - \int_{S_1} e_1 = P_1 - P_2$$

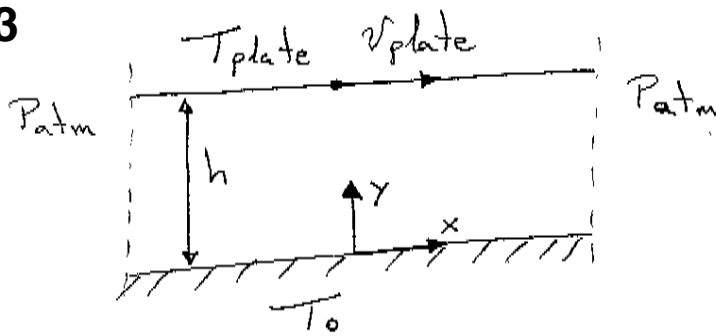
If I consider $e = u + \frac{1}{2} v^2$ then

$$\int_{S_1} u_1 \int_{S_1} \vec{v} \cdot \vec{n} dA + \int_{S_1} \frac{1}{2} v^2 \int_{S_1} \vec{v} \cdot \vec{n} dA + \int_{S_2} u_2 \int_{S_2} \vec{v} \cdot \vec{n} dA + \int_{S_2} \frac{1}{2} v^2 \int_{S_2} \vec{v} \cdot \vec{n} dA =$$

equal but opposite signs (cancel out)

therefore:

$$\boxed{u_2 - u_1 = \frac{P_1 - P_2}{\rho}}$$



Steady, incompressible flo.
between two infinite plate

$$\frac{\rho}{\rho t} = 0, v_z = 0, \frac{\rho}{\rho x} = 0$$

• Continuity: $\frac{\rho}{\rho t} + \frac{\rho}{\rho x} \cancel{v_x} + \frac{\rho}{\rho y} \cancel{v_y} + \frac{\rho}{\rho z} \cancel{v_z} = 0 \Rightarrow$

STEADY INFINITE PLATES

$$\Rightarrow \frac{\rho}{\rho y} \cancel{v_y} = 0 \Rightarrow \frac{\rho v_y}{\rho y} = 0 \quad \text{at } y=0 \Rightarrow v_y = 0 \Rightarrow$$

$v_y = 0$

• Conservation of momentum:

$$\cancel{\rho \frac{\partial v_x}{\partial t}} + v_x \cancel{\frac{\partial v_x}{\partial x}} + v_y \cancel{\frac{\partial v_x}{\partial y}} + v_z \cancel{\frac{\partial v_x}{\partial z}} = - \frac{\rho P}{\rho x} + \mu \left(\cancel{\frac{\partial^2 v_x}{\partial x^2}} + \frac{\partial^2 v_x}{\partial y^2} + \cancel{\frac{\partial^2 v_x}{\partial z^2}} \right)$$

STEADY

$$0 = \mu \frac{d^2 v_x}{dy^2}$$

$$\cancel{\rho \frac{\partial v_y}{\partial t}} + v_x \cancel{\frac{\partial v_y}{\partial x}} + v_y \cancel{\frac{\partial v_y}{\partial y}} + v_z \cancel{\frac{\partial v_y}{\partial z}} = - \frac{\rho P}{\rho y} + \mu \left(\cancel{\frac{\partial^2 v_y}{\partial x^2}} + \frac{\partial^2 v_y}{\partial y^2} + \cancel{\frac{\partial^2 v_y}{\partial z^2}} \right)$$

$\frac{\rho P}{\rho y} = 0$

$$\frac{d^2 v_x}{dy^2} = 0 \Rightarrow \frac{dv_x}{dy} = C_1 \Rightarrow v_x = C_1 \cdot y + C_2$$

$$v_x(y=0) = 0 \Rightarrow C_2 = 0$$

$$v_x(y=h) = v_{plate} \Rightarrow C_1 = \frac{v_{plate}}{h}$$

$$v_x = v_{plate} \cdot \left(\frac{y}{h} \right)$$

• Conservation of Energy

STEADY INFINITE PLATES Continuity

$$\rho \left(\frac{\partial e}{\partial t} + v_x \frac{\partial e}{\partial x} + v_y \frac{\partial e}{\partial y} + v_z \frac{\partial e}{\partial z} \right) = -\rho \left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right) - \left(v_x \frac{\partial p}{\partial x} + v_y \frac{\partial p}{\partial y} + v_z \frac{\partial p}{\partial z} \right) + \left[2\mu \left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right) + \mu \left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right) \right] + \lambda \left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right)$$

$$\rho \begin{pmatrix} \frac{\partial v_x}{\partial x} & \frac{\partial v_x}{\partial y} & \frac{\partial v_x}{\partial z} \\ \frac{\partial v_y}{\partial x} & \frac{\partial v_y}{\partial y} & \frac{\partial v_y}{\partial z} \\ \frac{\partial v_z}{\partial x} & \frac{\partial v_z}{\partial y} & \frac{\partial v_z}{\partial z} \end{pmatrix} + \begin{pmatrix} \rho & \rho & \rho \end{pmatrix} \left[2\mu \begin{pmatrix} \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \\ \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \\ \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \end{pmatrix} + \lambda \begin{pmatrix} \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \\ \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \\ \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \end{pmatrix} \right]$$

Continuity Incompressible

$$+ \lambda \left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right) \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} v_x \\ v_y \\ v_z \end{pmatrix} + k \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} \right)$$

INFINITE PLATES

$$0 = 2\mu \cdot \frac{1}{2} \left(\frac{\partial v_x}{\partial y} \right) \left(\frac{\partial v_x}{\partial y} \right) + 2\mu \cdot \frac{1}{2} \left(\frac{\partial^2 v_x}{\partial y^2} - \frac{\partial}{\partial x} \left(\frac{\partial v_x}{\partial y} \right) \right) \begin{pmatrix} v_x \\ v_y \\ v_z \end{pmatrix} - k \frac{\partial^2 T}{\partial y^2}$$

$$0 = \mu \left(\frac{\partial v_x}{\partial y} \right)^2 + \mu v_x \frac{\partial^2 v_x}{\partial y^2} + k \frac{\partial^2 T}{\partial y^2}$$

$$\frac{dv_x}{dy} = \frac{v_{plate}}{h} ; \frac{d^2 v_x}{dy^2} = 0 \Rightarrow \frac{d^2 T}{dy^2} = -\frac{\mu}{k} \left(\frac{v_{plate}}{h} \right)^2$$

$$T(y=0) = T_0$$

$$T(y=h) = T_{plate}$$

$$\frac{dT}{dy} = -\frac{\mu}{\kappa} \left(\frac{v_{plate}}{h} \right)^2 y + C_3$$

$$T = -\frac{\mu}{\kappa} \left(\frac{v_{plate}}{h} \right)^2 \frac{y^2}{2} + C_3 y + C_4$$

$$\text{at } y=0 \Rightarrow T = T_0 = C_4$$

$$\text{at } y=h \Rightarrow T = T_{plate} = -\frac{\mu}{\kappa} \left(\frac{v_{plate}}{h} \right)^2 \frac{h^2}{2} + C_3 h + T_0$$

$$C_3 = \frac{T_{plate} - T_0}{h} + \frac{\mu}{\kappa} \left(\frac{v_{plate}}{h} \right)^2 \frac{h}{2}$$

$$T(y) = -\frac{\mu}{\kappa} \left(\frac{v_{plate}}{h} \right)^2 \frac{y^2 - yh}{2} + \frac{T_{plate} - T_0}{h} y + T_0$$