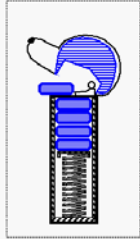


# Elementary Data Structures

Stacks, Queues, Vectors,  
Lists & Sequences  
Trees



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## The Stack ADT (§2.1.1)



- ◆ The **Stack** ADT stores arbitrary objects
- ◆ Insertions and deletions follow the last-in first-out scheme
- ◆ Think of a spring-loaded plate dispenser
- ◆ Main stack operations:
  - **push(object)**: inserts an element
  - **object pop()**: removes and returns the last inserted element
- ◆ Auxiliary stack operations:
  - **object top()**: returns the last inserted element without removing it
  - **integer size()**: returns the number of elements stored
  - **boolean isEmpty()**: indicates whether no elements are stored

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## Applications of Stacks



- ◆ Direct applications
  - Page-visited history in a Web browser
  - Undo sequence in a text editor
  - Chain of method calls in the Java Virtual Machine or C++ runtime environment
- ◆ Indirect applications
  - Auxiliary data structure for algorithms
  - Component of other data structures

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## Array-based Stack (§2.1.1)

- ◆ A simple way of implementing the Stack ADT uses an array
- ◆ We add elements from left to right
- ◆ A variable  $t$  keeps track of the index of the top element (size is  $t+1$ )

```
Algorithm pop():
if isEmpty() then
    throw EmptyStackException
else
     $t \leftarrow t - 1$ 
    return  $S[t + 1]$ 

Algorithm push(o):
if  $t = S.length - 1$  then
    throw FullStackException
else
     $t \leftarrow t + 1$ 
     $S[t] \leftarrow o$ 
```



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## The Queue ADT (§2.1.2)

- ◆ The Queue ADT stores arbitrary objects
- ◆ Insertions and deletions follow the first-in first-out scheme
- ◆ Insertions are at the rear of the queue and removals are at the front of the queue
- ◆ Main queue operations:
  - `enqueue(object)`: inserts an element at the end of the queue
  - `object dequeue()`: removes and returns the element at the front of the queue
- ◆ Auxiliary queue operations:
  - `object front()`: returns the element at the front without removing it
  - `integer size()`: returns the number of elements stored
  - `boolean isEmpty()`: indicates whether no elements are stored
- ◆ Exceptions
  - Attempting the execution of `dequeue` or `front` on an empty queue throws an `EmptyQueueException`



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## Applications of Queues



- ◆ Direct applications
  - Waiting lines
  - Access to shared resources (e.g., printer)
  - Multiprogramming
- ◆ Indirect applications
  - Auxiliary data structure for algorithms
  - Component of other data structures

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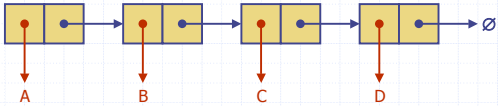
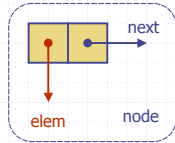
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## Singly Linked List

- ◆ A singly linked list is a concrete data structure consisting of a sequence of nodes
- ◆ Each node stores
  - element
  - link to the next node



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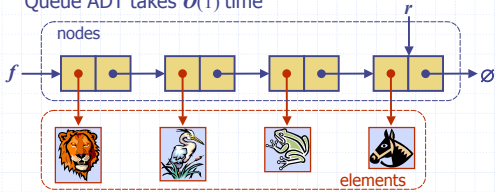
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## Queue with a Singly Linked List

- ◆ We can implement a queue with a singly linked list
  - The front element is stored at the first node
  - The rear element is stored at the last node
- ◆ The space used is  $O(n)$  and each operation of the Queue ADT takes  $O(1)$  time



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## The Vector ADT

- ◆ The **Vector** ADT extends the notion of array by storing a sequence of arbitrary objects
- ◆ An element can be accessed, inserted or removed by specifying its rank (number of elements preceding it)
- ◆ An exception is thrown if an incorrect rank is specified (e.g., a negative rank)
- ◆ Main vector operations:
  - object `elemAtRank(integer r)`: returns the element at rank `r` without removing it
  - object `replaceAtRank(integer r, object o)`: replace the element at rank with `o` and return the old element
  - `insertAtRank(integer r, object o)`: insert a new element `o` to have rank `r`
  - object `removeAtRank(integer r)`: removes and returns the element at rank `r`
- ◆ Additional operations `size()` and `isEmpty()`

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## Applications of Vectors

- ◆ Direct applications
  - Sorted collection of objects (elementary database)
- ◆ Indirect applications
  - Auxiliary data structure for algorithms
  - Component of other data structures

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## Array-based Vector

- ◆ Use an array  $V$  of size  $N$
- ◆ A variable  $n$  keeps track of the size of the vector (number of elements stored)
- ◆ Operation *elemAtRank*( $r$ ) is implemented in  $O(1)$  time by returning  $V[r]$



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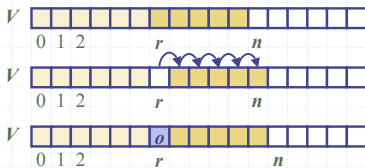
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## Insertion

- ◆ In operation *insertAtRank*( $r, o$ ), we need to make room for the new element by shifting forward the  $n - r$  elements  $V[r], \dots, V[n - 1]$
- ◆ In the worst case ( $r = 0$ ), this takes  $O(n)$  time



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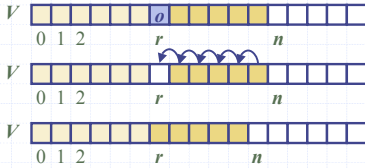
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## Deletion

- ◆ In operation *removeAtRank*( $r$ ), we need to fill the hole left by the removed element by shifting backward the  $n - r - 1$  elements  $V[r + 1], \dots, V[n - 1]$
- ◆ In the worst case ( $r = 0$ ), this takes  $O(n)$  time



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## Performance

- ◆ In the array based implementation of a Vector
  - The space used by the data structure is  $O(N)$
  - *size*, *isEmpty*, *elemAtRank* and *replaceAtRank* run in  $O(1)$  time
  - *insertAtRank* and *removeAtRank* run in  $O(n)$  time
- ◆ If we use the array in a circular fashion, *insertAtRank*(0) and *removeAtRank*(0) run in  $O(1)$  time
- ◆ In an *insertAtRank* operation, when the array is full, instead of throwing an exception, we can replace the array with a larger one

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## Position ADT

- ◆ The **Position** ADT models the notion of place within a data structure where a single object is stored
- ◆ It gives a unified view of diverse ways of storing data, such as
  - a cell of an array
  - a node of a linked list
- ◆ Just one method:
  - object *element*() : returns the element stored at the position

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## List ADT (§2.2.2)

- ◆ The **List** ADT models a sequence of positions storing arbitrary objects
- ◆ It establishes a before/after relation between positions
- ◆ Generic methods:
  - `size()`, `isEmpty()`
- ◆ Query methods:
  - `isFirst(p)`, `isLast(p)`
- ◆ Accessor methods:
  - `first()`, `last()`
  - `before(p)`, `after(p)`
- ◆ Update methods:
  - `replaceElement(p, o)`, `swapElements(p, q)`
  - `insertBefore(p, o)`, `insertAfter(p, o)`
  - `insertFirst(o)`, `insertLast(o)`
  - `remove(p)`

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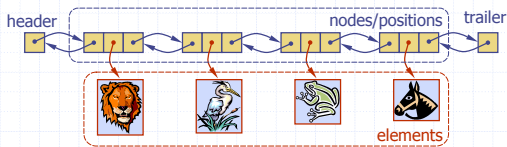
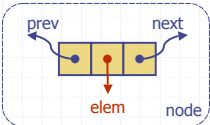
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## Doubly Linked List

- ◆ A doubly linked list provides a natural implementation of the List ADT
- ◆ Nodes implement Position and store:
  - element
  - link to the previous node
  - link to the next node
- ◆ Special trailer and header nodes




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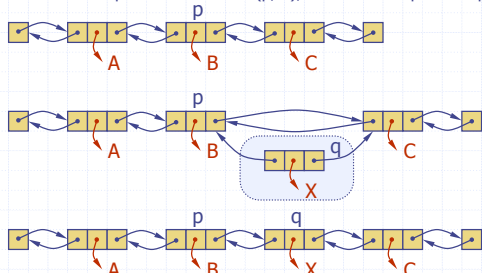
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## Insertion

- ◆ We visualize operation `insertAfter(p, X)`, which returns position `q`




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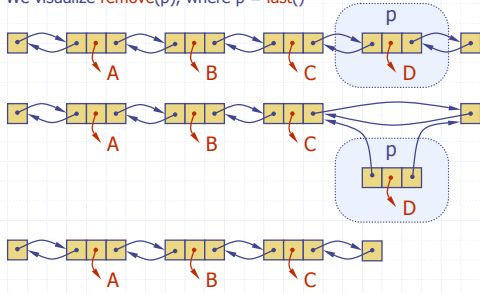
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## Deletion

◆ We visualize `remove(p)`, where  $p = \text{last}()$




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## Performance

◆ In the implementation of the List ADT by means of a doubly linked list

- The space used by a list with  $n$  elements is  $O(n)$
- The space used by each position of the list is  $O(1)$
- All the operations of the List ADT run in  $O(1)$  time
- Operation `element()` of the Position ADT runs in  $O(1)$  time

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## Sequence ADT

◆ The Sequence ADT is the union of the Vector and List ADTs

◆ Elements accessed by

- Rank, or
- Position

◆ Generic methods:

- `size()`, `isEmpty()`

◆ Vector-based methods:

- `elemAtRank(r)`, `replaceAtRank(r, o)`, `insertAtRank(r, o)`, `removeAtRank(r)`

◆ List-based methods:

- `first()`, `last()`, `before(p)`, `after(p)`, `replaceElement(p, o)`, `swapElements(p, q)`, `insertBefore(p, o)`, `insertAfter(p, o)`, `insertFirst(o)`, `insertLast(o)`, `remove(p)`

◆ Bridge methods:

- `atRank(r)`, `rankOf(p)`

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## Applications of Sequences

- ◆ The Sequence ADT is a basic, general-purpose, data structure for storing an ordered collection of elements
- ◆ Direct applications:
  - Generic replacement for stack, queue, vector, or list
  - small database (e.g., address book)
- ◆ Indirect applications:
  - Building block of more complex data structures

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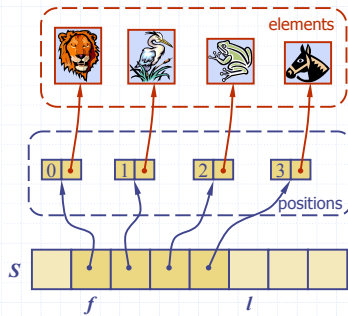
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## Array-based Implementation

- ◆ We use a circular array storing positions
- ◆ A position object stores:
  - Element
  - Rank
- ◆ Indices  $f$  and  $l$  keep track of first and last positions




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## Sequence Implementations

Operation	Array	List
size, isEmpty	1	1
atRank, rankOf, elemAtRank	1	$n$
first, last, before, after	1	1
replaceElement, swapElements	1	1
replaceAtRank	1	$n$
insertAtRank, removeAtRank	$n$	$n$
insertFirst, insertLast	1	1
insertAfter, insertBefore	$n$	1
remove	$n$	1

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# Iterators

- ◆ An iterator abstracts the process of scanning through a collection of elements
- ◆ An iterator is typically associated with another data structure
- ◆ Methods of the ObjectIterator ADT:
  - object `object()`
  - boolean `hasNext()`
  - object `nextObject()`
  - `reset()`
- ◆ We can augment the Stack, Queue, Vector, List and Sequence ADTs with method:
  - ObjectIterator `elements()`
- ◆ Extends the concept of Position by adding a traversal capability
- ◆ Two notions of iterator:
  - snapshot: freezes the contents of the data structure at a given time
  - dynamic: follows changes to the data structure
- ◆ Implementation with an array or singly linked list

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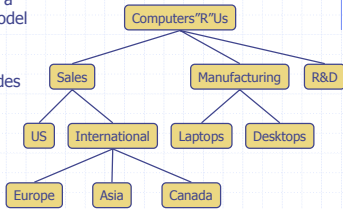
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# Trees (§2.3)

- ◆ In computer science, a tree is an abstract model of a hierarchical structure
- ◆ A tree consists of nodes with a parent-child relation
- ◆ Applications:
  - Organization charts
  - File systems
  - Programming environments




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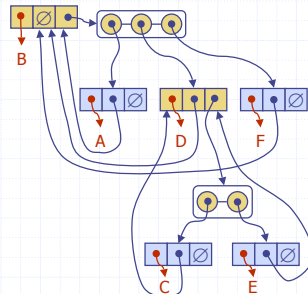
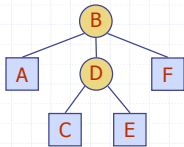
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# Linked Data Structure for Representing Trees (§2.3.4)

- ◆ A node is represented by an object storing
  - Element
  - Parent node
  - Sequence of children nodes
- ◆ Node objects implement the Position ADT




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## Tree ADT (§2.3.1)



- ◆ We use positions to abstract nodes
- ◆ Generic methods:
  - integer `size()`
  - boolean `isEmpty()`
  - objectIterator `elements()`
  - positionIterator `positions()`
- ◆ Accessor methods:
  - position `root()`
  - position `parent(p)`
  - positionIterator `children(p)`
- ◆ Query methods:
  - boolean `isInternal(p)`
  - boolean `isExternal(p)`
  - boolean `isRoot(p)`
- ◆ Update methods:
  - `swapElements(p, q)`
  - object `replaceElement(p, o)`
- ◆ Additional update methods may be defined by data structures implementing the Tree ADT

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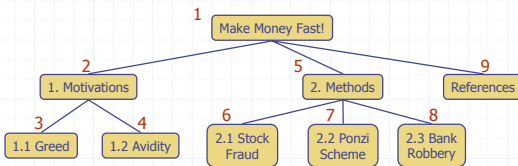
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## Preorder Traversal (§2.3.2)



- ◆ A traversal visits the nodes of a tree in a systematic manner
- ◆ In a preorder traversal, a node is visited before its descendants
- ◆ Application: print a structured document

**Algorithm *preOrder*(v)**  
*visit*(v)  
**for each** child *w* of *v*  
*preorder*(w)




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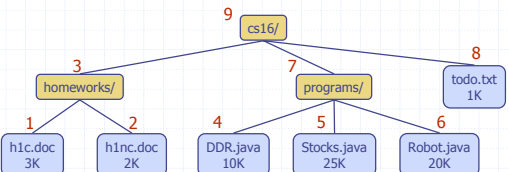
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## Postorder Traversal (§2.3.2)



- ◆ In a postorder traversal, a node is visited after its descendants
- ◆ Application: compute space used by files in a directory and its subdirectories

**Algorithm *postOrder*(v)**  
**for each** child *w* of *v*  
*postOrder*(w)  
*visit*(v)




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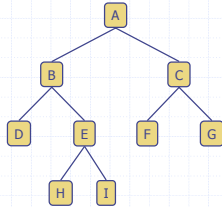
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## Binary Trees (§2.3.3)

- ◆ A binary tree is a tree where:
  - Each internal node has at most two children
- ◆ A **proper** binary tree is a binary tree where:
  - each internal node has exactly two children
  - The children are an ordered pair, denoted left child and right child.
- ◆ Alternative recursive definition: a (proper) binary tree is either
  - a tree consisting of a single node, or
  - a tree whose root has an ordered pair of children, each of which is a (proper) binary tree
- ◆ Applications:
  - arithmetic expressions
  - decision processes
  - searching




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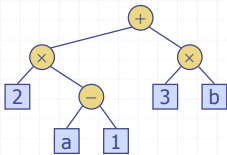
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## Arithmetic Expression Tree

- ◆ Binary tree associated with an arithmetic expression
  - internal nodes: operators
  - external nodes: operands
- ◆ Example: arithmetic expression tree for the expression  $((2 \times (a - 1)) + (3 \times b))$




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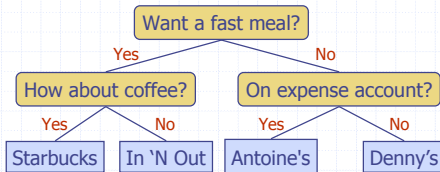
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## Decision Tree

- ◆ Binary tree associated with a decision process
  - internal nodes: questions with yes/no answer
  - external nodes: decisions
- ◆ Example: dining decision




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