

SOLUTION FOR HW #3

p1

$$\dot{D} = (30 - W)D, \quad \dot{W} = (.5D - 40)W + f$$

1. Equilibrium points

Set derivatives and input to zero

$$\dot{D} = 0 = (30 - W)D \rightarrow a) W = 30$$

$$b) D = 0$$

$$\dot{W} = 0 = \left(\frac{D}{2} - 40\right)W$$

$$\dot{D} = 0 = \left(\frac{0}{2} - 40\right)W$$

$$D = 80$$

$$W = 0$$

$$(0, 0)$$

Two points $\rightarrow (80, 30)$

2. System is linearized using Jacobian matrix, which is 2-D version of Taylor series

$$\begin{bmatrix} \frac{\partial \dot{D}}{\partial D} & \frac{\partial \dot{D}}{\partial W} \\ \frac{\partial \dot{W}}{\partial D} & \frac{\partial \dot{W}}{\partial W} \end{bmatrix} = \begin{bmatrix} 30 - W & -D \\ .5W & .5D - 40 \end{bmatrix}$$

Evaluate at $(0, 0)$:

$$A_{0,0} = \begin{bmatrix} 30 & 0 \\ 0 & -40 \end{bmatrix}$$

Evaluate at $(80, 30)$:

$$A_{80,30} = \begin{bmatrix} 0 & -30 \\ 40 & 0 \end{bmatrix}$$

3. Write system in state space form near each eq. point.

$$\text{Near } (0, 0): \begin{bmatrix} \dot{D} \\ \dot{W} \end{bmatrix} = \begin{bmatrix} 30 & 0 \\ 0 & -40 \end{bmatrix} \begin{bmatrix} D \\ W \end{bmatrix} + \begin{bmatrix} 0 \\ -1 \end{bmatrix} f \quad y = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} D \\ W \end{bmatrix}$$

$$\text{Near } (80, 30): \begin{bmatrix} \dot{D} \\ \dot{W} \end{bmatrix} = \begin{bmatrix} 0 & -30 \\ 40 & 0 \end{bmatrix} \begin{bmatrix} D_e \\ W_e \end{bmatrix} + \begin{bmatrix} 0 \\ -1 \end{bmatrix} f \quad y = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} D \\ W \end{bmatrix}$$

NOTE 1: I have chosen the output y to be deer — you will be given this information on the quiz.

NOTE 2: The new variables $D_e = D - 80$ and $W_e = W - 30$ are used near the point $(80, 30)$

4. Eigenvalues

$$\text{Near } (0,0) \quad |sI-A| = \begin{vmatrix} s-30 & 0 \\ 0 & s+40 \end{vmatrix} = 0$$

$$(s-30)(s+40) = 0$$

The eigenvalues are 30 and -40.

#5.

This system is unstable, with one pole in the right half plane.

It produces a saddle point because the roots are real and have opposite sign.

$$\text{Near } (80,30) \quad |sI-A| = \begin{vmatrix} s & 30 \\ -40 & s \end{vmatrix} = 0$$

$$s^2 + 1200 = 0$$

$$\text{eigenvalues} \rightarrow s = \pm j20\sqrt{3}$$

This system is conditionally stable, with two poles on the imaginary s-axis.

It produces a center near (80,30).

6. Sketch phase portrait.

Find \dot{D} and \dot{w} near the eq. points.

$$\text{At } (80,40) \quad \left. \begin{aligned} \dot{D} &= (30-40)(80) = -800 \\ \dot{w} &= (.5(80)-40)40 = 0 \end{aligned} \right\} \text{Vector points } \leftarrow$$

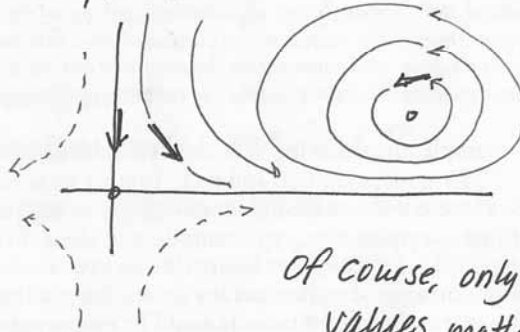
$$\text{At } (0,10) \quad \left. \begin{aligned} \dot{D} &= (30-10)(0) = 0 \\ \dot{w} &= (.5(0)-40)(10) = -400 \end{aligned} \right\} \text{Vector points } \downarrow$$

$$\text{At } (10,10) \quad \left. \begin{aligned} \dot{D} &= 200 \\ \dot{w} &= -350 \end{aligned} \right\} \text{Vector points } \searrow$$

HW # 3

p.3

The phase portrait :



Of course, only the positive values matter because we cannot have a negative population.