Earth's Magnetic Field

Magnetic Potential for a dipole field pointing South

 $V(\mathbf{r}) = \mathbf{m} \cdot \mathbf{r} / (4 \pi r^3) = -m \cos\theta / (4 \pi r^2) = \text{scalar magnetic potential of dipole}$ field. Field is expanded in spherical harmonics. First term (above) is the dipole term.

 $m = 8 \times 10^{22} \text{ Am}^2$ is dipole moment at center of Earth point south r = distance from dipole $\theta = \text{colatitude}$

$$\mathbf{B}(\mathbf{r}) = -\mu_0 \text{ grad V} = \text{vector magnetic field}$$

where $\mu_0 = 4\pi \times 10^{-7}$ kg m A⁻² s⁻² = magnetic permeability in free space (A=amps)

$$B_r = -\mu_0 dV/dr = -\mu_0 m 2 \cos\theta / (4 \pi r^3)$$
 radial component of magnetic field (up) $B_\theta = -\mu_0 r^{-1} dV/d\theta = -\mu_0 m \sin\theta / (4 \pi r^3)$ tangential component of field (south)

 $|\mathbf{B}| = \operatorname{sqrt}(B_r^2 + B_\theta^2) = \mu_0 \, \text{m} / (4 \, \pi \, R^3) \, \operatorname{sqrt}(\sin^2 \theta + 4\cos^2 \theta) = B_0 \, \operatorname{sqrt}(1 + 3\cos^2 \theta)$ size of magnetic field at Earths surface

at $r=R=6371*10^3$ m (surface of earth) define: $B_0=\mu_0$ m / (4 π R³) $B_0=4\pi$ x 10^{-7} kg m A⁻² s⁻² * 8 x 10^{22} Am² / (4 π (6.371*10⁶)³ m³) $=10^{-7+22-18}$ *8*6.371⁻³ kg A⁻¹ s⁻² = 3 * 10^{-5} kg A⁻¹ s⁻² = 3 * 10^{-5} Tesla (T) = 3 * 10^4 nanoTesla

So the strength of the magnetic field at Earth's surface varies from 30,000nT at the equator ($\theta = 90$; $\cos^2\theta = 0$) to 60,000nT at the poles ($\theta = 0$ or 180; $\cos^2\theta = 1$).

The inclination angle (I) is defined to be the dip of magnetic field: horizontal=0, down is positive) so:

$$\begin{array}{ll} tan(I) = -B_r \, / \, | \, B_{_{\! 0}} \, | \, = (B_0 \, 2 \, cos\theta \,) \, / \, (B_0 \, sin\theta \,) \, = \, 2/tan\theta \, = \, 2 \, tan\lambda \\ negative \, B_r \, because \, we \, measure \, dip \, pointing \, down \, but \, positive \, r \, is \, up \\ \theta \, is \, colatitude; \, \lambda = 90 \, - \, \theta \, is \, latitude \end{array}$$

Time variation of magnetic field

Secular variation
Intensity
Direction
Westward drift of non-dipole field
Reversals

Properties of Earth's magnetic field

- Approximated with a centered dipole tilted by 11.5°. (explains 90% of field at surface)
- dipole moment of 8x10²² Am² (60,000 nT at poles, 30,000 nT at equator)
 - o discuss non-dipole in terms of multipoles (quadrapole etc)
- Field tilted down in northern hemisphere.
- Define "inclination" and "declination" (geomagnetic poles and equator are where I=±90° and 0° respectively). Magnetic poles and equator are for best fitting dipole.
- Has internal and external sources. External sources associated with magnetosphere-sun interactions

Variable properties of field:

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external (order 100 nT)

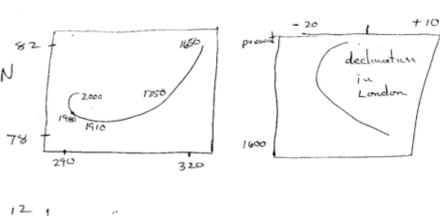
micropulses (ms-minutes) 1 nT

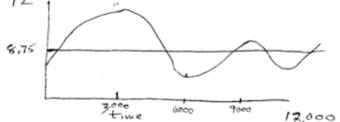
magnetospheric substorms (hours) 10 nT

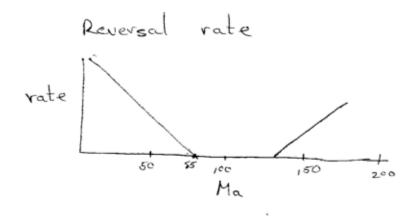
solar daily variations 20 nT

solar storms (4-60 hrs) 40 nT

sun spot cycle (11 and 22 years)
internal sources (greater than 4 years)
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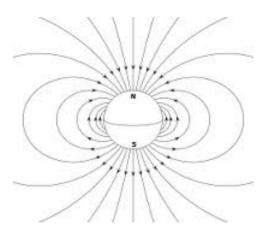




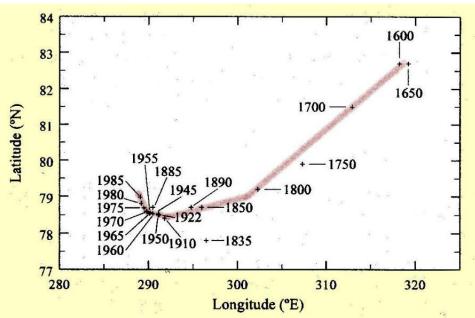


Recent observation of rapid movement of the magnetic pole: (from http://science.nasa.gov/science-news/science-at-nasa/2003/29dec magneticfield/)

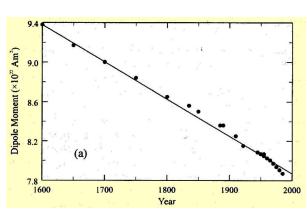




This has resulted in a change in declination at Johnson Hall (-122.30861, 47.65453) from 22.3° E in 1950 to 18.7 in 2000 to 16.6 in 2012, currently dropping at a rate of 1.8° per decade. http://www.ngdc.noaa.gov/geomag-web/#ushistoric



Variation of the dipole axis as represented by the change in position of North Geomagnetic Pole. After Fraser-Smith(1987).



Variation of dipole moment from spherical harmonic analysis.

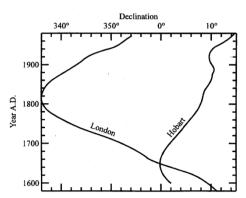


Fig. 2.8. Variation in declination at London, England (51.5°N), and at Hobart, Tasmania (42.9°S), from observatory measurements. The earliest measurement in the Tasmanian region was made by Abel Tasman at sea in 1642 in the vicinity of the present location of Hobart. Preobservatory data have been derived also by interpolation from isogonic charts.

Geometry of Earth Magnetic field

Dipole field
Non-dipole field
Inclination
Declination
equation for dipole magnetic field
equation relating inclination to latitude
GMP, VGP, Paleomagnetic Pole
Geocentric Axial dipole hypothesis

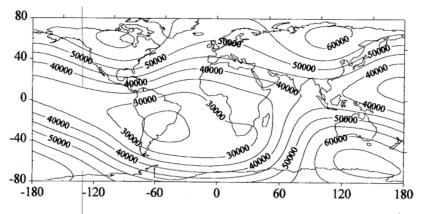


Fig. 2.3c. Isodynamic chart for 1990 showing the variation of total intensity over the Earth's surface. Contours are labeled in nT.

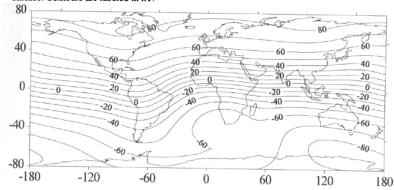


Fig. 2.3b. Isoclinic chart for 1990 showing the variation of inclination in degrees over the Earth's surface.

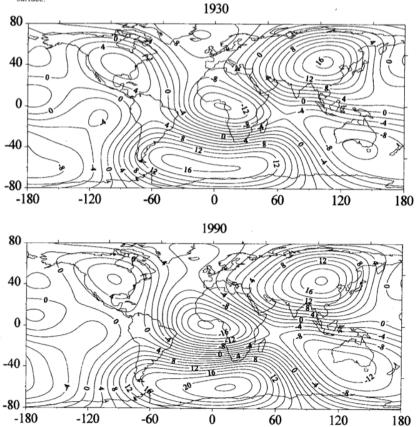


Fig. 2.10. The vertical component of the nondipole field for 1930 and 1990. Contours are labeled in units of 1000 nT.

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History of field as recorded in rocks
Ferromagnetic minerals
Magnetic Hysteresis
Curie temperature
Blocking temperature
Remanent magnetization
TRM
IRM
DRM
CRM
VRM
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Paleomagnetic data from continents magnetic data from oceans

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Dynamo theory
MHD
Dynamo equations
"Frozen-in" field
Free decay
numerical simulations
how close are simulations?
Examples
Role of inner core
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(8.1.9)
\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}
                                                                                                                                                             (8.1.10)
                                                                                                               Maxwell's equations
                                                                                                                                                             (8.1.11)
 \nabla \cdot \mathbf{B} = 0
                                                                                                                                                             (8.1.12)
 \nabla \cdot \mathbf{D} = \rho_e
\mathbf{J} = \sigma \mathbf{E} + \sigma (\mathbf{v} \times \mathbf{B})
                                                                                                                               Ohm's Law
                                                                                                                                                             (8.1.13)
                                                                                                        Navier-Stokes' equation
                                                                                                                                                             (8.1.14)
\rho \left( \frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla \right) \mathbf{v} + 2\rho (\mathbf{\Omega} \times \mathbf{v})
  = -\nabla P + \eta \nabla^2 \mathbf{v} + \frac{1}{3} \eta \nabla (\nabla \cdot \mathbf{v}) - \rho \nabla \phi_g + \mathbf{J} \times \mathbf{B}
\nabla \cdot (\rho \mathbf{v}) + \frac{\partial \rho}{\partial t} = 0
                                                                                                                 Continuity equation
                                                                                                                                                             (8.1.15)
                                                                                                                   Poisson's equation
                                                                                                                                                             (8.1.16)
\nabla^2 \phi_{\sigma} = -4\pi G \rho
                                                                                                                      Generalized heat
                                                                                                                                                            (8.1.17)
 \frac{\partial T}{\partial t} = k_T \nabla^2 T + (\nabla k_T \cdot \nabla T) - \mathbf{v} \cdot \nabla T + \varepsilon
                                                                                                                                    equation
                                                                                                                      Equation of state
                                                                                                                                                             (8.1.18)
 \rho = \text{Function}(P, T, H)
Notation:
                                         H = magnetic field
                                                                                                                                       \rho \equiv \text{material density}
                                         \mathbf{B} = \text{magnetic induction}
                                                                                                                                            \sigma = conductivity
                                         J = electric current
                                                                                                                                              T \equiv \text{temperature}
                                         E \equiv electric field
                                                                                                                                                    P \equiv \text{pressure}
                                         D = electric displacement vector
                                                                                                                            G = gravitational constant
                                                                                                                          \phi_{Q} = \text{gravitational potential}
                                         v = velocity
                                         \eta = viscosity
                                                                                                                                      \varepsilon = heat source term
                                         \rho_e = electric charge density
                                                                                                                                 k_T = thermal diffusivity
                                         \Omega = angular velocity of rotation
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The magnetohydrodyanmic (MHD) assumption that dD/dt=0 is almost always made, so:

$$\nabla \times \mathbf{H} = \sigma \mathbf{E} + \sigma (\mathbf{v} \times \mathbf{B}) \qquad (8.2.1)$$

Then taking the curl of both sides of this equation and using (8.1.12), (8.1.13) and $\mathbf{B} = \mu_0 \mathbf{H}$, one obtains the magnetic induction equation:

$$\frac{\partial \mathbf{H}}{\partial t} = \frac{1}{\sigma \mu_0} \nabla^2 \mathbf{H} + \nabla \times (\mathbf{v} \times \mathbf{H}) \quad . \tag{8.2.2}$$

This and $\nabla \cdot \mathbf{H} = \mathbf{0}$ replaces equations 8.1.9-8.1.13 and removes **E**, **B**, **J** and **D** from the equations. Also **J** x **B** in eq 8.1.14 is replaced by $\mu_0(\nabla \times \mathbf{H}) \times \mathbf{H}$.

Now, if **H** is a solution to the MHD equations, so is –**H**, so regardless of the flow field, initial conditions, or boundary conditions, there is no preference for "normal" versus "reversed" field polarity.

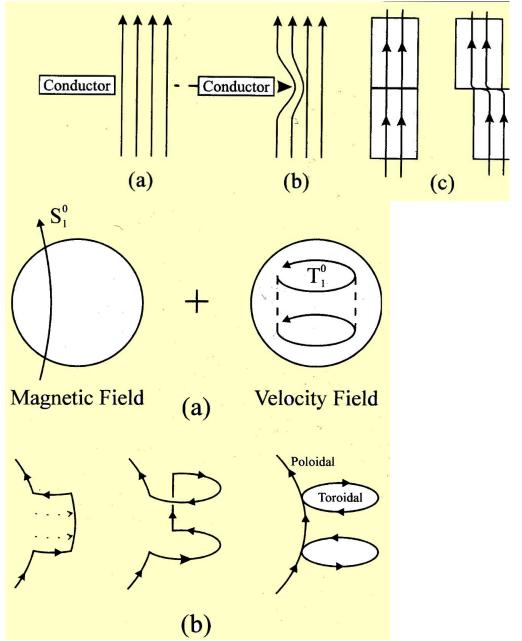




Fig. 8.8. Production of a poloidal magnetic field. A region of fluid upwelling, illustrated by dotted lines on the left, interacts with a toroidal magnetic field (solid line). Because of the Coriolis effect (northern hemisphere) the fluid exhibits helicity, rotating as it moves upward (thin lines, center). The magnetic field line is carried with the conducting liquid and is twisted to produce a poloidal loop as on the right. After Parker (1955a.)

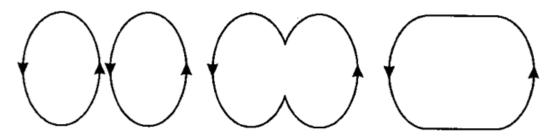


Fig. 8.9. Convergence of two poloidal loops as produced in Fig. 8.8 results in a larger poloidal loop. After Parker (1955a.)

