

ESS 524 Class #6

Highlights from last Monday – Surabhi

Today's highlights report on next Monday – Erich

Highlights reporters – please send me your report by email.

- Great Week 2 journals. You are all doing some good thinking.

Today

- HW #2 on Matlab (Finite Difference code) due today
Are there challenges to discuss now? More time needed?
- Class organization – how is it going with Zoom?
- If you get stuck on HW assignments, please feel free to contact me and/or classmates directly with your questions.
- It's great to work together on problems, just prepare your own answers in the end.
- Zoom study sessions for you to interact, compare approaches and answers?

ESS 524 Class #6

Today

- Project updates
- Continuing with Finite Element Method (FEM)

Next Week

- Finite Volume Method (FVM)
- We will follow Patankar fairly closely, Ch 3 and Ch 4

HW #2

Getting the analytical solution?

- FDM - Handling the second derivative (diffusion term)
- Expand with Product Rule, or not?

$$\frac{d}{dx} \left(k(x) \frac{d\phi}{dx} \right) \quad (*) \text{ when } k(x) \text{ varies with } x$$

① Product Rule Approach

$$(*) = k(x) \frac{d^2\phi}{dx^2} + \frac{dk}{dx} \frac{d\phi}{dx}$$

$$\rightarrow k_j \left(\frac{\phi_{j+1} - 2\phi_j + \phi_{j-1}}{\Delta x^2} \right) + \left(\frac{k_{j+1} - k_{j-1}}{\Delta x} \right) \left(\frac{\phi_{j+1} - \phi_{j-1}}{\Delta x} \right)$$

Problem - First derivatives span $2\Delta x$

HW #2

- FDM – Evaluate the slope at midpoints, so that all first derivatives are taken over span Δx rather than $2\Delta x$

(2) Evaluate slopes at mid points. I assume $k(x)$ is known at mid points or can be estimated there e.g. $k_{j+1/2} = \frac{(k_{j+1} + k_j)}{2}$

$$\begin{aligned} (*) &\rightarrow \frac{\left[k \frac{\partial \phi}{\partial x} \right]_{j+1/2} - \left[k \frac{\partial \phi}{\partial x} \right]_{j-1/2}}{\Delta x} \\ &= \frac{\left[k_{j+1/2} \left(\frac{\phi_{j+1} - \phi_j}{\Delta x} \right) - k_{j-1/2} \left(\frac{\phi_j - \phi_{j-1}}{\Delta x} \right) \right]}{\Delta x} \\ &= \frac{k_{j+1/2} \phi_{j+1} - k_{j+1/2} \phi_j - k_{j-1/2} \phi_j + k_{j-1/2} \phi_{j-1}}{\Delta x^2} \end{aligned}$$

HW 2

2020-04-09

$$S(x) = P_N^{(s)}(x) = \sum_{n=0}^N a_n x^n \quad \frac{1}{k(x)} = P_M^{(k)}(x) = \sum_{m=0}^M b_m x^m$$

$$\frac{d}{dx} \left(k(x) \frac{d\phi}{dx} \right) + S(x) = 0 \quad (1)$$

Integrate once

$$\begin{aligned} \left(k(x) \frac{d\phi}{dx} \right) &= - \int_{x_0}^{x_1} S(x') dx' = \text{a polynomial} \\ &= \left. k(x) \frac{d\phi}{dx} \right|_{x_0} + \sum_{n=0}^N \frac{1}{n+1} a_n x^{n+1} = R(x) \end{aligned}$$

$$\frac{d\phi}{dx} = R(x) P_M^{(k)}(x) = \text{a polynomial } T(x)$$

$$\int_{x_1}^{x_0} \frac{d\phi}{dx} dx' = \phi(x_1) - \phi(x) = \int_{x_0}^{x_1} T(x) dx = u(x)$$

a polynomial

$$\phi(x) = \phi_1 - u(x)$$

↖ gradient BC is embedded here

Product Rule and Integration by Parts

$$\int_{v(a)}^{v(b)} u(x) dv(x) = [uv]_a^b - \int_{u(a)}^{u(b)} v(x) du(x) \quad (1)$$

$$\text{or } \frac{d}{dx} [u(x)v(x)] = u \frac{dv}{dx} + v \frac{du}{dx} \quad (2)$$

Integrate (2) from a to b to get (1)

Product Rule and Integration by Parts

$$\int_{v(a)}^{v(b)} u(x) dv(x) \Rightarrow [uv]_a^b - \int_{u(a)}^{u(b)} v(x) du(x) \quad (1)$$

When $v(x)$ is the 2nd derivative term, and $u(x)$ does not include a derivative, after integration by parts,

- both $u(x)$ and $v(x)$ appear with first derivatives in the new integral term.
- In general, $v(x)$ is differentiated one time less, and $u(x)$ is differentiated one time more.
- boundary conditions show up naturally in the new constant term.

The challenge –

- How to represent a 2nd order differential equation with piecewise 1st order functions?
- The 2nd derivative is identically zero everywhere
- except at the nodes, where it can be infinite.

The Solution - The weak form of the differential equation

- The weak form is a weighted-integral statement that is equivalent to the governing differential equation combined with its natural boundary conditions.
- The original equation is satisfied in an average sense, rather than point by point.
- The weak form is derived from the strong form by an integration by parts.
- After integration by parts, the 2nd derivative has been replaced by a 1st derivative, which is nonzero for a piecewise linear representation.

With Equation (17), the algebraic equations (12) and (13) in element j reduce to

$$\begin{aligned}
 -k_j \left[\frac{d\tilde{\phi}}{dx} \right]_{x_{j-1}}^{(j)} - \frac{k_j}{\Delta x_j} \phi_{j-1} + \frac{k_j}{\Delta x_j} \phi_j + S_j \frac{\Delta x_j}{2} &= 0 \\
 k_j \left[\frac{d\tilde{\phi}}{dx} \right]_{x_j}^{(j)} + \frac{k_j}{\Delta x_j} \phi_{j-1} - \frac{k_j}{\Delta x_j} \phi_j + S_j \frac{\Delta x_j}{2} &= 0
 \end{aligned} \tag{18}$$

Note that if these two equations were added together, we would get an expected finite-volume expression for conservation of ϕ in element j , i.e.

$$k_j \left[\frac{d\tilde{\phi}}{dx} \right]_{x_j}^{(j)} - k_j \left[\frac{d\tilde{\phi}}{dx} \right]_{x_{j-1}}^{(j)} = S_j \Delta x_j \tag{19}$$

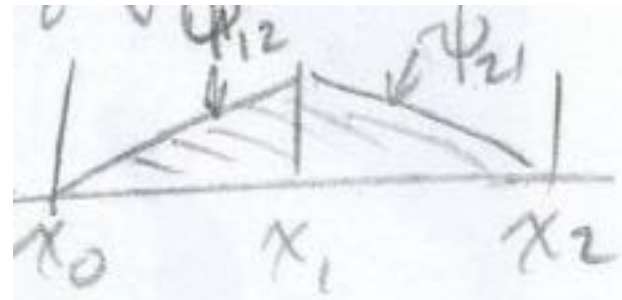
i.e. the difference in fluxes across the boundaries must equal the integrated production rate inside element j .

Equations for 3 linear elements, with 4 nodes

We have 6 weighting equations for 4 nodes.

- We need only 4 equations.
- The first and last equations are just the boundary conditions
- Add together the two equations that apply to the same boundary, but from the elements on opposite sides.
- This effectively isolates the residuals around that node
- Combining the equations at nodes 2 and 3 reduces the number of equations by 2
- We are left with 4 equations.

$$\begin{bmatrix} a_{11} & a_{12} & 0 & 0 \\ a_{21} & a_{22} & 0 & 0 \\ 0 & a_{32} & a_{33} & 0 \\ 0 & a_{42} & a_{43} & 0 \\ 0 & 0 & a_{53} & a_{54} \\ 0 & 0 & a_{63} & a_{64} \end{bmatrix} \begin{bmatrix} \phi_0 \\ \phi_1 \\ \phi_2 \\ \phi_3 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \\ b_4 \\ b_5 \end{bmatrix}$$



- The flux terms will also cancel and vanish.

